

Therefore, then

$$W(\text{work stored in the spring}) = \int_0^y Ky = \frac{1}{2} y^2$$

where y = the limiting deflection of the spring. Thus, if we re-arrange the equation

$$f = \frac{PL^3}{3EI}$$

to the form

$$\frac{3EI}{L^3} = \frac{P}{f} = K = \frac{3\pi E d^4}{32 L^3}$$

we find that

$$K = \frac{3\pi (26 \times 10^6 \text{ lb/in}^2) (\frac{1}{4})^4}{32 (2)^3} = 11,500 \text{ lb/in.}$$

and if the retractor is deflected by a deflection of 0.5072 in. it will be

$$\frac{1}{2} (11,500 \text{ lb/in.}) (0.5072 \text{ in.})^2 = 1,508 \text{ in.-lb.}$$

$$\frac{1,508 \text{ in.-lb.}}{12 \text{ in./ft.}} = 125.7 \text{ ft.-lb.}$$

Therefore, the retractor stores the energy of the shock in

$$125.7 = \frac{1}{2} I \omega^2$$

$$\left[\frac{2(125.7)}{11.77} \right]^{1/2} = \omega = [21.3]^{1/2} = 4.61 \text{ rad/sec.}$$

Now, the retractor spring is not linear. It would mean that the shock with the retractor would produce the same assembly yield from 150.8 in.-lb. as it would from 1,508 in.-lb. after which the retractor takes care of the balance of the energy. This is not desirable for a full stop.

Assuming the use of a 1/8 in. diameter retractor and assuming a retractor force of 200 lb. in. is provided for black and white camera, the retractor provides the stop of the second positioning assembly.

The velocity of the Drive #2 assembly at the end of the above mentioned 120° travel can be determined by applying the formula: $v = \frac{a \cdot t}{2}$ the specified motor to the computed required motor. The acceleration in which the computed motor is based. Since the computed required motor would raise the speed of the Drive Assembly from 0 to 150 ft/sec in 60 sec, or an acceleration of:

$$150 \text{ ft/sec} = \frac{1}{2} a (60)$$

$$\frac{150 \text{ ft/sec}}{30} = 5 \text{ ft/sec}^2$$

Using a 1/2 HP motor in the place of the 0.125 HP computed requirement, we may have:

$$\left[\frac{12.5 \text{ HP}}{0.125 \text{ HP}} \right] [5.03 \text{ ft/sec}^2] = 5.95 \text{ ft/sec}^2$$

With the motor at hand, the required motor would supply the 120° arc of travel in 10.1 sec.

$$\frac{120^\circ}{360} (2\pi) = \frac{2}{3} \pi \text{ radians}$$

The average angular acceleration of 5.95 rad/sec² would be applied to a mass of 10.1 lb. (the motor) which is the rotating mass of the Drive Assembly. The 2 sec. in travel, meaning the acceleration of 10.1 lb. Drive Assembly, the same motor output required would be:

$$6.5 (5.95) = 38.7 \text{ ft/sec}^2$$

By

$$s = \frac{1}{2} a t^2$$

$$\frac{2}{3} \pi = \frac{1}{2} (38.7) (t^2)$$

$$t = \sqrt{\frac{2 \left(\frac{2}{3} \pi \right)}{38.7}} = 0.54 \text{ sec}$$

which requires the motor to accelerate the mass

$$\frac{1}{2} a t^2 = \frac{1}{2} (38.7) (0.54)^2 = 5.74 \text{ ft/sec}^2$$

which is the same velocity at the conclusion of the arc of travel. The fact that the motor is required to accelerate the mass of the Drive Assembly with respect to Drive #1 may be dropped. The two velocity groups

of the two functions which the hatch serves: - (1) firstly, it serves to stop and position Drum #2 with respect to Drum #1 when black-and-white viewing is intended; and (2) it is the means by Drum #1 is actuated along with Drum #2 in color viewing. In stopping Drum #2 after Drum #1 has already been positioned, it must absorb the flywheel energy of Drum #2. This would mean, since $\Sigma m r^2$ for each Drum has been taken at 50.5 lb.-ft.², that

$$\frac{(50.5 \text{ lb.-ft.}^2)}{(32 \frac{\text{ft.}}{\text{sec.}^2})} (3.5 \text{ rad./sec.})^2 = 0.382 \text{ ft.-lb.}$$

of energy must then be absorbed. By reference to the previous calculations concerning the two wheel functions Drum #1, it is clear that a member with a rotational inertia equal to a lb.-ft. would absorb more than sufficient for this purpose, if it were rotating at the same rate as Drum #1. In a practical matter, for the design of the hatch member, it would be appropriate to assume a rotational inertia equal to

$$\frac{(10 \text{ lb.-ft.}^2)}{(32 \frac{\text{ft.}}{\text{sec.}^2})} (3.5 \text{ rad./sec.})^2 = 3.71 \text{ ft.-lb.}$$

$$(10 \text{ ft.-lb.}) (12 \frac{\text{ft.}}{\text{ft.}}) = 120 \text{ in.-lb.}$$

absorbing capacity. Assuming a lever arm of about a 15" radius from the axis of rotation, the torque indicated above implies a load of

$$\frac{120 \text{ in.-lb.}}{15 \text{ in.}} = 8 \text{ lbs.}$$

applied to the end of the hatch. Not the little 2" by 1/2" would mean the loading of a spring load of

$$(8 \text{ lbs.}) (2 \text{ in.}) = 16 \text{ in.-lb.}$$

which is a fair figure, insignificant, and worthy of no further computations. Summary of the function of the shifting key when the Drums are actuated. One consideration of the loader involved, it is practical from a structural viewpoint, to look in terms of a cantilever supporting moment of the Drums from one end as per the figure below: -

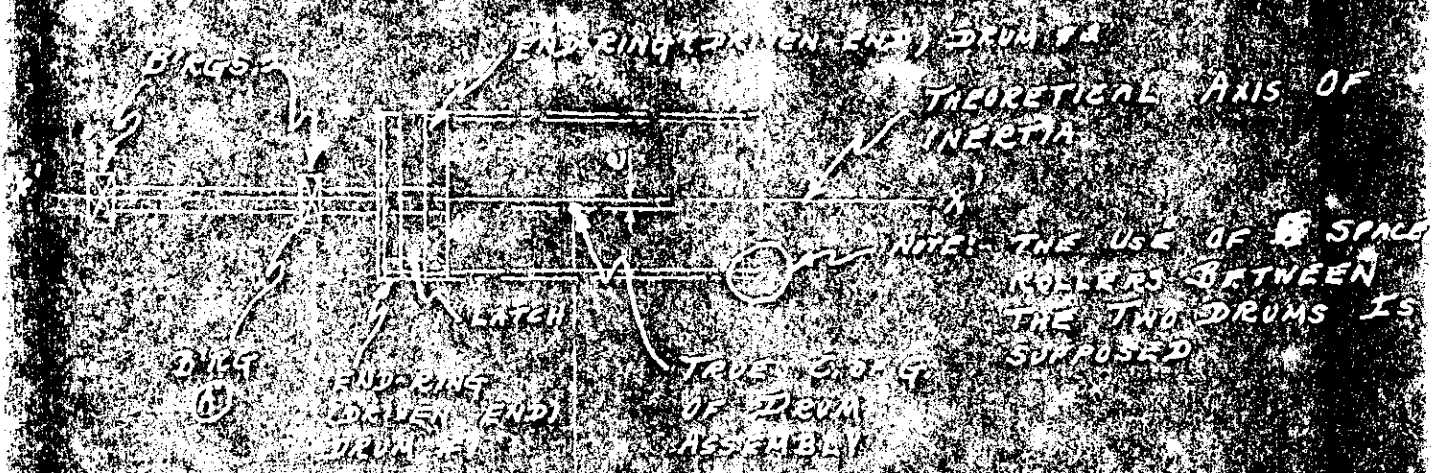
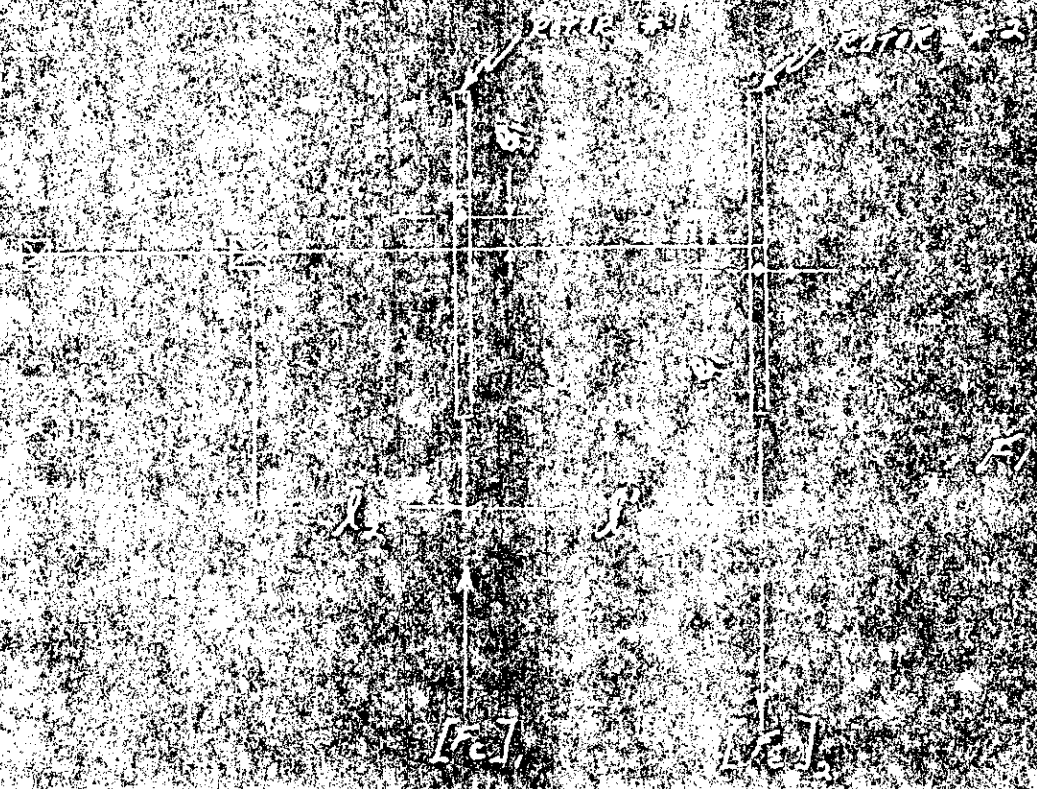
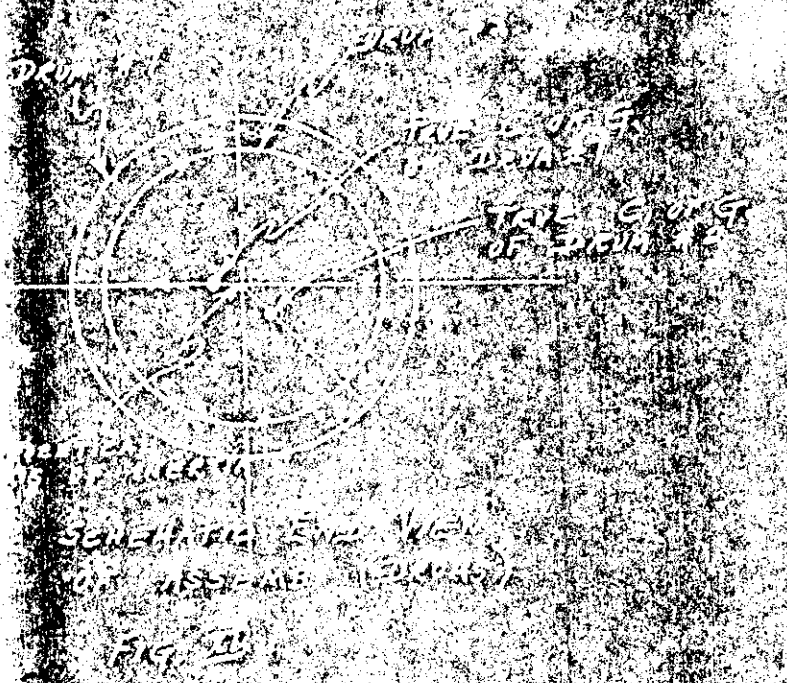


FIG. 9

The shaft and drum, in double drum assembly, is considered as a single member. The drum is a cylindrical member. The length of the shaft being taken equal to the space between Fig. 9 and the true center of gravity of the combined drum assembly. The use of space rollers as indicated contributes towards the rigidity of this assembly.





So, the picture taken above is, first, a photograph, and secondly, an idealized one. It is the operation to the view which is shown, the shape to carry out the operation to the loads. In making the shape the carrying two of the same kind of loads, there is a possibility of a possibility (assuming that the system has been fabricated and is in balance). The possibilities are illustrated in Figs. 10 and 11.

Fig. 10 illustrates the situation in which the system of identical weights is placed in a position of equilibrium. The weights are mounted on the same shaft.

Fig. 11 illustrates the situation in which the system of identical weights is placed in a position of equilibrium. The weights are mounted on the same shaft.

When the system is in a position of equilibrium, the weights are mounted on the same shaft. The weights are mounted on the same shaft.

$$P = P_1 = \frac{1}{2} W_1 e$$

When the system is in a position of equilibrium, the weights are mounted on the same shaft. The weights are mounted on the same shaft.

$$\frac{1}{2} W_1 e$$

When the system is in a position of equilibrium, the weights are mounted on the same shaft. The weights are mounted on the same shaft.

dependence of different forms the distance and magnitude of different magnitudes at $x = 1$ and the distance. Since the different magnitudes would alter the relative magnitudes of (F_1) and (F_2) the shape would be destroyed; and the situation would involve the following situationally below:-

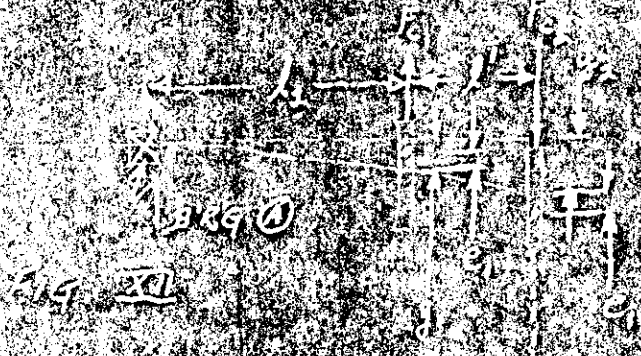


Fig. 20

as the distance is calculated in which the force (F_1) and (F_2) can be reduced and the situation

$$\frac{(F_1)(1-x_1) - (F_2)(1-x_2)}{(1-x_1)^2} = F_1$$

with a constant force (F_1) acting at a distance $(1-x_1)$ from the origin. The mass (m) acting at a distance $(1-x_2)$ would then be given by

$$m = F_1 \left(\frac{1-x_1}{1-x_2} \right)^2 = \frac{F_1 (1-x_1)^2}{(1-x_2)^2}$$

where the distance $(1-x_2)$ is measured from the origin.

$$1 = \frac{F_1}{F_2} \left(\frac{1-x_1}{1-x_2} \right)^2 = \frac{F_1}{F_2} \left(\frac{1-x_1}{1-x_2} \right)^2$$

Therefore the distance $(1-x_2)$ is given by

$$1-x_2 = \frac{F_1}{F_2} \left(\frac{1-x_1}{1-x_2} \right)^2 = \frac{F_1}{F_2} \left(\frac{1-x_1}{1-x_2} \right)^2$$

From this it follows that

$$F_2 = \frac{F_1}{(1-x_2)^2} (1-x_1)^2$$

and

$$F_2 = \frac{W}{g} (g_2 + e_1) \omega^2$$

Similarly, when

$$F_1 + F_2 = K g_2$$

we may write

$$\frac{W}{g} (g_1 - e_1) \omega^2 + \frac{W}{g} (g_2 + e_1) \omega^2 = K g_2$$

we will obtain

$$\omega^2 (g_1 + g_2) = \frac{K g_2}{W} g_2$$

$$\frac{\omega^2 g_2}{K g_2} = \frac{K g_2}{W g_2} \Rightarrow \frac{\omega^2}{K} = \frac{K}{W} \Rightarrow \frac{\omega^2}{K} = 1$$

The frequency of the pendulum is -

1) as ω approaches $\left(\frac{K}{W}\right)$ in value, g_2 would attain a limiting value, becoming infinite when $\omega = \frac{K}{W}$.
2) The shaft would fall in

and

3) when g_1 is expressed in terms of g_2 with $\left[\frac{K}{W} - 1\right]$ as a multiplier of g_2 , it is clear that when $\omega < \left(\frac{K}{W}\right)$ but approaches the latter in value, the portion of the shaft between rotor #1 and the vertical section, which, when $\omega = \left(\frac{K}{W}\right)$, the force that rotor #1 exerts

$$g_2 = \frac{K}{W}$$

means that the action of the shaft above rotor #1 becomes the initial value.

The initial position of shaft #1 is equally important as well, but while in the initial position, it must be considered as two independent masses, one at the rotor #1 and the other at the rotor #2, which would be connected by the shaft. The distance separating the two rotors is the length of the shaft, which is the distance between the two rotors. The shaft is not a single mass, but a continuous mass, and the distance between the two rotors is the length of the shaft. The shaft is not a single mass, but a continuous mass, and the distance between the two rotors is the length of the shaft. The shaft is not a single mass, but a continuous mass, and the distance between the two rotors is the length of the shaft.

between (Y) and (Z) in favor of the relation by the normal static
 relationship. The conditions shown above, however, from the dynamic
 relationship between (Y) and (Z) do not in any way attempt to operate
 at a speed greater than the first resonance speed, and in fact, the relation
 speed in fact, is substantially below the first resonance speed. Here,
 in fact, with the light and essentially zero high concentrated load,
 we will not be needing to speed to the critical speed as indicated by the
 "high concentrated load" equation.

Returning to Eq. II, let

$$W = 1017 \text{ #}$$

$$L = 14"$$

$$SE = 15,000 \text{ #/in}^2$$

$$OD = 150.8 \text{ mm} = 5.93 \text{ in}$$

$$E = 1.1 \times 10^{12} \text{ dynes/cm}^2 \text{ (static)} \quad 0.005(E) = 0.014$$

$$g = \left[\frac{E}{W} \frac{L^3}{32} \right]^{1/2} = 35 \text{ mm/sec}$$

$$E_t = 2.6(10^5) \text{ lb/in}^2$$

Returning to Eq. I, let

$$\frac{W}{32} \frac{L^3}{E} = \frac{25L^2}{3ET} = 0$$

$$\frac{W}{32} \frac{L^3}{E} = 0.14L = \frac{(1017)(14^3)}{3(2.6 \times 10^5)} = 0$$

$$0.005L = 0.14L = 0.0051 = 0$$

$$L^2 = 0.8L = 0.43 = 0$$

In the above equations

$$A = 0$$

$$A = 7 \times 10^{-6}$$

$$B = 0$$

$$B = 7 \times 10^{-6}$$

$$C = 0$$

$$C = 0.2$$

$$D = 0.43$$

$$D = 0.43$$

Then solving

$$A - B = 0 - 0 = 0$$

$$g = A - B = 0 - 0 = 0$$

$$f = E - C - 2ABC + Dg = 0 + 0.04 - 0 + 0 = 0.04$$

$$k = \frac{1}{2} AC = 0.04 \quad D = \frac{1}{2} \left(\frac{1}{2} \right) = 0.143$$

$$L = \frac{1}{2} \left[A + (h^2 + k^2)^{1/2} \right] + \frac{1}{2} \left[h - (h^2 + k^2)^{1/2} \right] =$$

$$= \frac{1}{2} [0.04 + (0.0016 + 0.0039)^{1/2}] + \frac{1}{2} [0.04 -$$

$$(0.0016 + 0.0039)^{1/2}] =$$

$$\frac{1}{2} [0.04 + 0.164] + \frac{1}{2} [0.04 - 0.108] =$$

$$0.102 + 0.071 = 0.176$$

$$M = 9FL = 0 + 0.176 = 0.176$$

$$N = 4FL = 0 + 0.176 = 0.176$$

$$U = 4FL + 3k - 12JL = 4(0.176) + 3(0.143) - 12(0) =$$

$$= 0.696 + 0.429 = 0.124 + 0.429 = 0.573$$

Using the same method we get -

$$d_1 = -k + \frac{1}{2} \sqrt{h^2 + k^2} + (h + \frac{1}{2} \sqrt{h^2 + k^2})^{1/2}$$

$$d_2 = -k + \frac{1}{2} \sqrt{h^2 + k^2} + (h - \frac{1}{2} \sqrt{h^2 + k^2})^{1/2}$$

$$d_3 = -k + \frac{1}{2} \sqrt{h^2 + k^2} - (h + \frac{1}{2} \sqrt{h^2 + k^2})^{1/2}$$

$$d_4 = -k + \frac{1}{2} \sqrt{h^2 + k^2} - (h - \frac{1}{2} \sqrt{h^2 + k^2})^{1/2}$$

$$d_1 = 0 + \frac{1}{2} \sqrt{0.04 + 0.0039} + (0.04 + \frac{1}{2} \sqrt{0.04 + 0.0039})^{1/2} = 0.42 + (0.176 + 0.152)^{1/2}$$

$$= 0.42 + 0.934^{1/2} = 0.42 + 0.966 = 1.386$$

By inspection, the four other roots would lie in the realm of imaginary or irrational values. Checking,

$$d_2 = 0 + \frac{1}{2} \sqrt{0.04 + 0.0039} + (0.04 - \frac{1}{2} \sqrt{0.04 + 0.0039})^{1/2} = 0$$

~~same as above~~

$$d_3 = 0 + \frac{1}{2} \sqrt{0.04 + 0.0039} - (0.04 + \frac{1}{2} \sqrt{0.04 + 0.0039})^{1/2} = 0$$

$$d_4 = 0 + \frac{1}{2} \sqrt{0.04 + 0.0039} - (0.04 - \frac{1}{2} \sqrt{0.04 + 0.0039})^{1/2} = 0$$

Since the above value is correct. Taking (2) as follows:-

$$J = \frac{1}{2} \left[h - (h^2 + k^2)^{1/2} \right] + \frac{1}{2} \left[h - (h^2 + k^2)^{1/2} \right] =$$

$$\frac{1}{2} [0.04 - 0.164 + \frac{1}{2} (0.04 - 0.164)] =$$

$$= \frac{1}{2} [0.204 - \frac{1}{2}(0.124)] = [0.204 - 0.062] / 2 =$$
$$= \frac{1}{2} [0.142] = 0.071$$

$$u = 0.071$$
$$v = 0.071$$
$$w = 4(0.071)^2 + 0.43 = 4(0.005) + 0.43 =$$
$$0.02 + 0.43 = 0.45$$

$$d_1 = 0.071^{1/2} + (0.071 + 0.45)^{1/2} = 0.276 + (0.071 + 0.45)^{1/2}$$
$$= 0.276 + 0.741^{1/2} = 0.276 + 0.86 = 1.136"$$

Check

$$d_1^2 - 0.43 = 0$$
$$1.06 - 0.43(1.136) = 0.43 = 0$$
$$1.06 - 0.9088 = 0.43 = 0$$

Again, taking

$$1 = \frac{1}{2} [1 + (h^2 + k^2)^{1/2}] + \frac{1}{2} [h = (h^2 + k^2)^{1/2}] =$$
$$\frac{1}{2} [0.204] + \frac{1}{2} [-0.04] = 0.102 - 0.062 = 0.04$$

$$u = 0.04$$
$$v = 0.04$$
$$w = 4(0.04)^2 + 0.43 = 4(0.0016) + 0.43 =$$
$$0.0056 + 0.43 = 0.4356$$

$$d_1 = 0.04^{1/2} + (0.04 + 0.4356)^{1/2} =$$
$$0.2 + (0.04 + 0.4356)^{1/2} = 0.2 + 0.7^{1/2} =$$
$$0.2 + 0.835 = 1.035$$

Check

$$d_1^2 - 0.43 = 0$$
$$1.07 - 0.43(1.035) = 0.43 = 0$$
$$1.07 - 0.44505 = 0.43 = 0$$

The answer may be taken to be within the limits of slide-rule accuracy; and we would not expect a shift, if all data derive from check, as the normal standard.

We previously found the torque accelerating the drum to be of the order of 22.75 in.-lbs. Taking the "shock-torque" to be 1.5 times the value, according to Eq. 56 of "Shifting From A Dynamic Vibration",

$$22.7 \left[\frac{1.5}{4} \right]^{1/5} = 22.7 \left[\frac{22.75(1.5)}{12(10^6)} \right]^{1/5} =$$

$$0.227 \left[\frac{33.675}{12} \right]^{1/5} = 0.227(1.415) = 0.321 \text{ in.}$$

shaft would be required to yield not more than a 10/20 diameter of shifting shaft. Finally, we find, by Eq. 58 of "Shifting From A Dynamic Vibration",

$$\frac{36 M_e}{\pi d^3} = S_s$$

where $M_e = 10$ in.-lbs. "shock torque" and $d = 1.125$ in. (as previously assumed)

$$\frac{10(1.5)(100.75)}{\pi (1.125)^3} = \frac{2.2(32.5)}{\pi (1.42)} = 12.1 \text{ ksi.}$$

which gives the shear stress due to torque. The combined stress due to torque and bending would then be:

$$\left[15,000^2 + 12.1^2 \right]^{1/2} = \left[2.25 \times 10^8 + 147(10^4) \right]^{1/2} =$$

$$15,100 \text{ psi.}$$

and hence the 1 1/2" diameter shaft satisfies the principle design condition. It is necessary check the value of permanent speed which will result upon the release of the spring by $\left[\frac{k \cdot g}{W} \right]^{1/2}$ according to Eq. (1) of "Shifting From A Dynamic Vibration", since

$$k = \frac{35.1}{1} = \frac{2(30 \times 10^6)(\pi)(1.125)^4}{64(6.71)} =$$

$$\frac{48(10^6)(\pi)(1.125)^4}{64(2.726)} = 2210 \text{ lb/in.}$$

then

$$\left[\frac{k \cdot g}{W} \right]^{1/2} = \left[\frac{2210(32.1)}{10.77} \right]^{1/2} = [8350.0]^{1/2} = 91.4 \text{ cycles per } 2\pi \text{ sec.}$$

By

$$g = \frac{e}{\frac{w_i}{w_o} - 1}$$

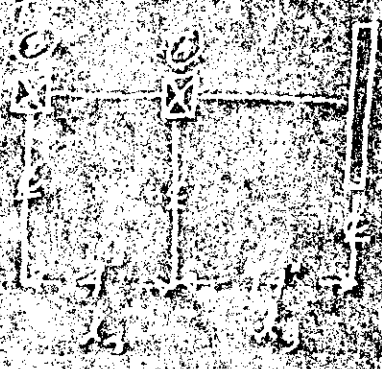
as per Eq. of Vapour from a Dry Air Vapour,

$$\frac{e}{\left(\frac{77}{157.1}\right) - 1} = \frac{e}{1.361 - 1} = \frac{e}{.358}$$

as per Eq. of Vapour from a Dry Air Vapour,

$$\frac{2.571}{.358} = 7.181$$

As the air is to be heated by the heating coil, and passing through it, assume a 4" vertical clearance between the two main heating coils.



The required heating requirement, at a rate of 5,000 ft. per hr. is 1.55". The amount which must be able to withstand at the given area should be:

$$H = S Z = 5000 \times 1.55 = 7750 \text{ ft.} \\ \frac{7750 \times 1.55}{12} = \frac{12012.5}{12} = 1001.04 \text{ ft.}$$

Letting the area be 1000 ft.²

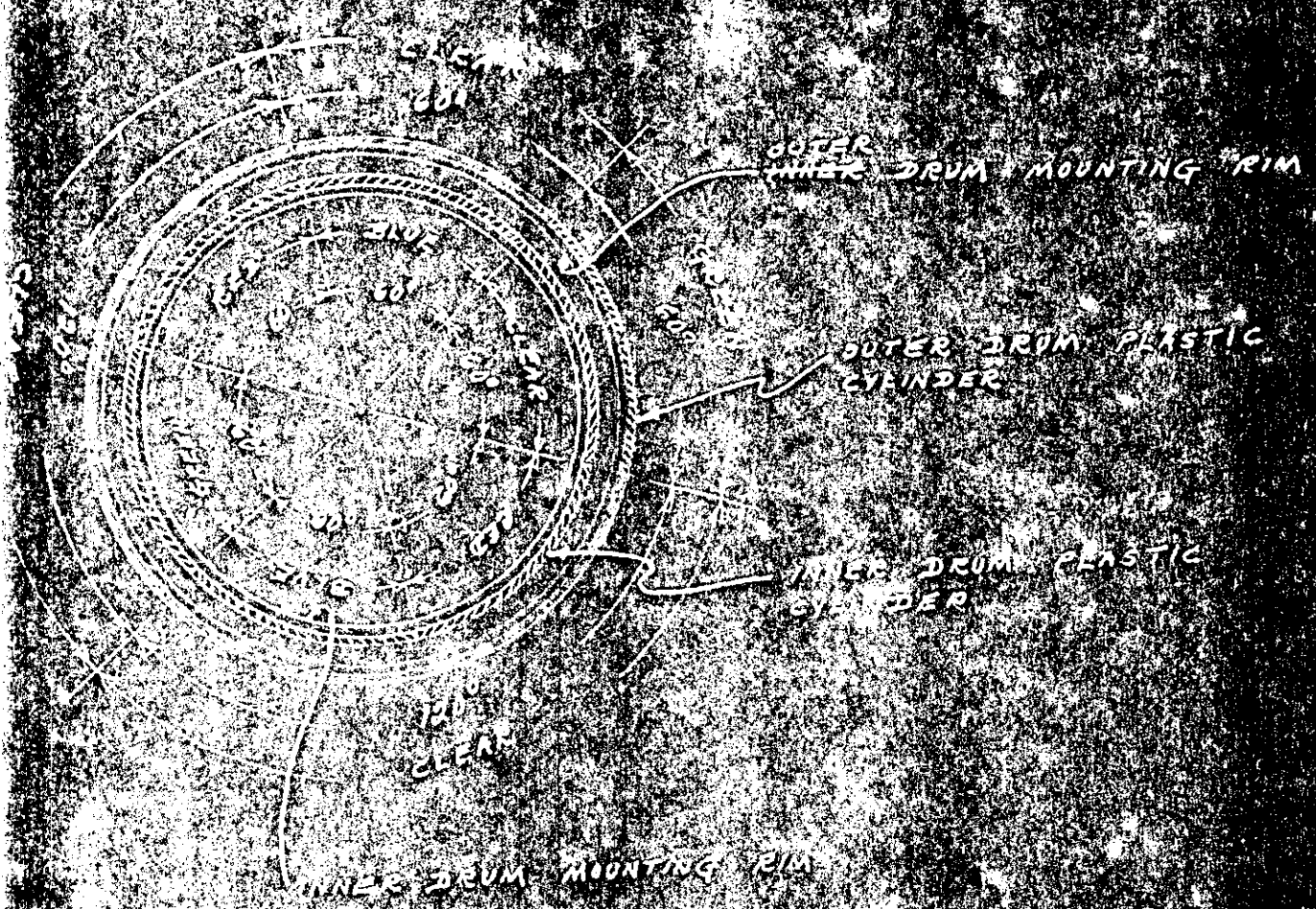
$$\frac{H}{A} = \frac{1001.04}{1000} = 1.001 \text{ ft.} = \text{Load on coil (1)}$$

Letting the area be 1000 ft.²

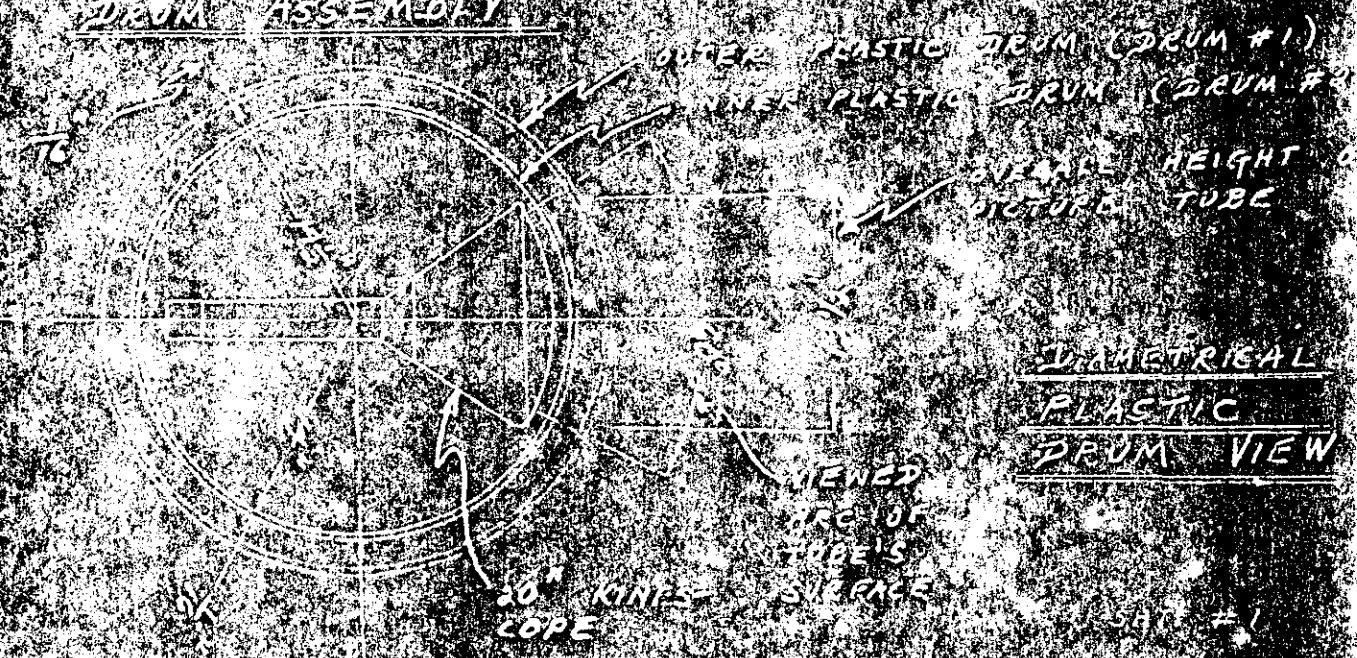
$$\frac{H}{A} = \frac{1001.04}{1000} = 1.001 \text{ ft.} = \text{Load on coil (2)}$$

The amount required for the principal components, such as the air will be required to be present in part of the heating requirements.

LAYOUT SKETCHES FOR 20" TUBE



SCHEMATIC SHOWING ARRANGEMENT
OF FILTER SECTORS ON DOUBLE
DRUM ASSEMBLY



FILTER SECTION "A"

GRIND JOINING EDGES OF LUCITE SHEETS TO INDICATED BEVEL XS; LEAVE GRD EDGES ROUGH AND FILL IN WITH DENTAL POLY-METHACRYLATE POLYMER PASTE

FILTER SECTION "B"

PREPARATION OF LONGITUDINAL SEAMS BETWEEN FILTER SECTIONS BOTH DRUMS

GRIND BUFF & POLISH PERIPHERAL SURFACE OF WELD

6- EQUI-SPACED 1/8" DIA. #2-19 INCH SCREWS PER SECTOR TO DRIVEN END RING

16 LUCITE BRG DRIVERS

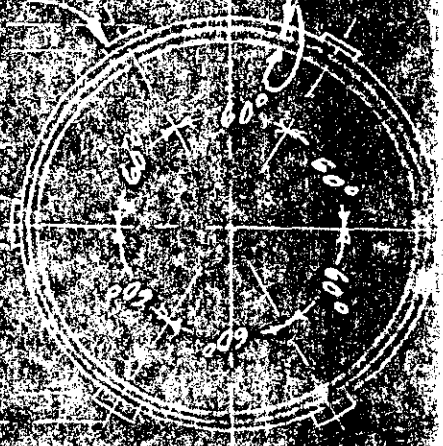
LUCITE END 1/8" THK 1/4" LG. WELD TO DRUM INS

DRIVEN END

FILTER SECTION

FILTER SECTION

FILTER SECTION



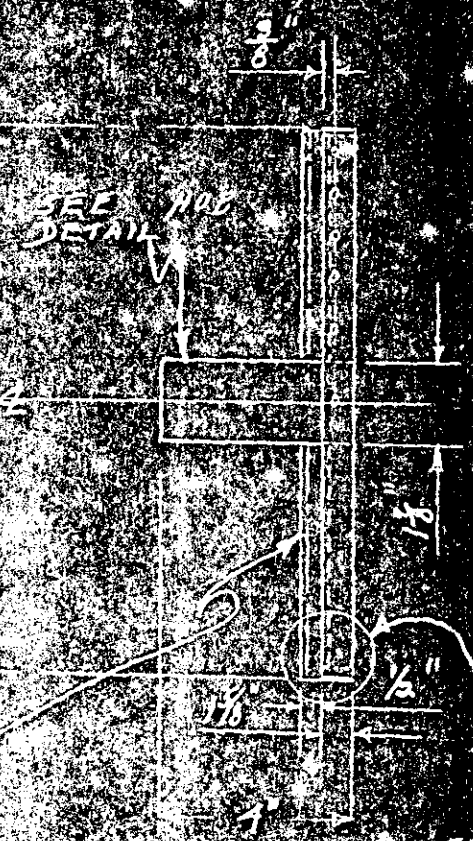
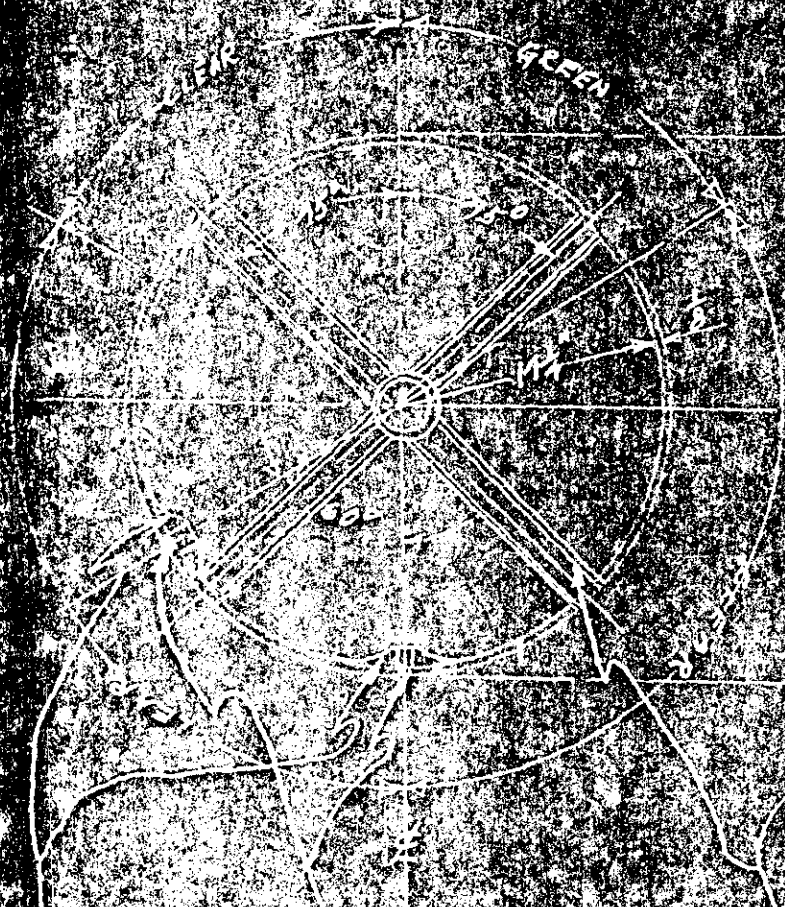
18 1/2" 14 1/8" 6.2"

EXTERNAL PROJECTED HEIGHT OF EXTERNAL FILTER SECTION

18 1/2"

DRUM #2 (SIDE ELEVATION & R.H. END VIEWS)

5/16" DIA



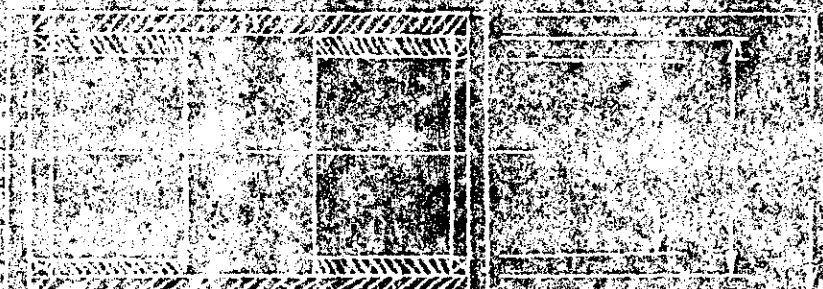
SEE HUB
DETAIL

SEE
DETAIL
1/4"

PAUL GRAB
DEVICE (SEE
DETAIL)

1/4" DEPTH X 1/2" RISE
1/16" IS NEEDED TO
RAISE HUB

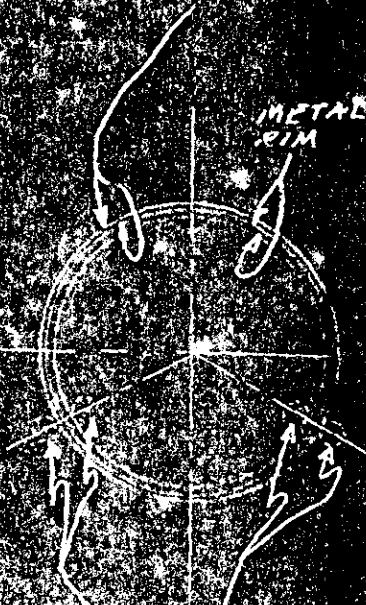
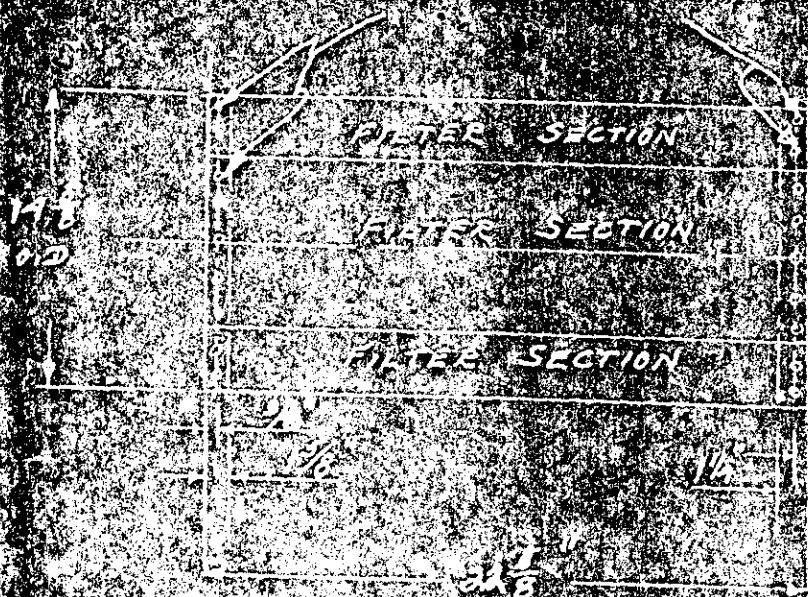
1/4" DEPTH
SEE PAUL GRAB
DEVICE DETAIL



0- END-SPACED 3/8" R.D.
 100 MACH. SCREENS PER
 100 SECTOR TO END-RINGS

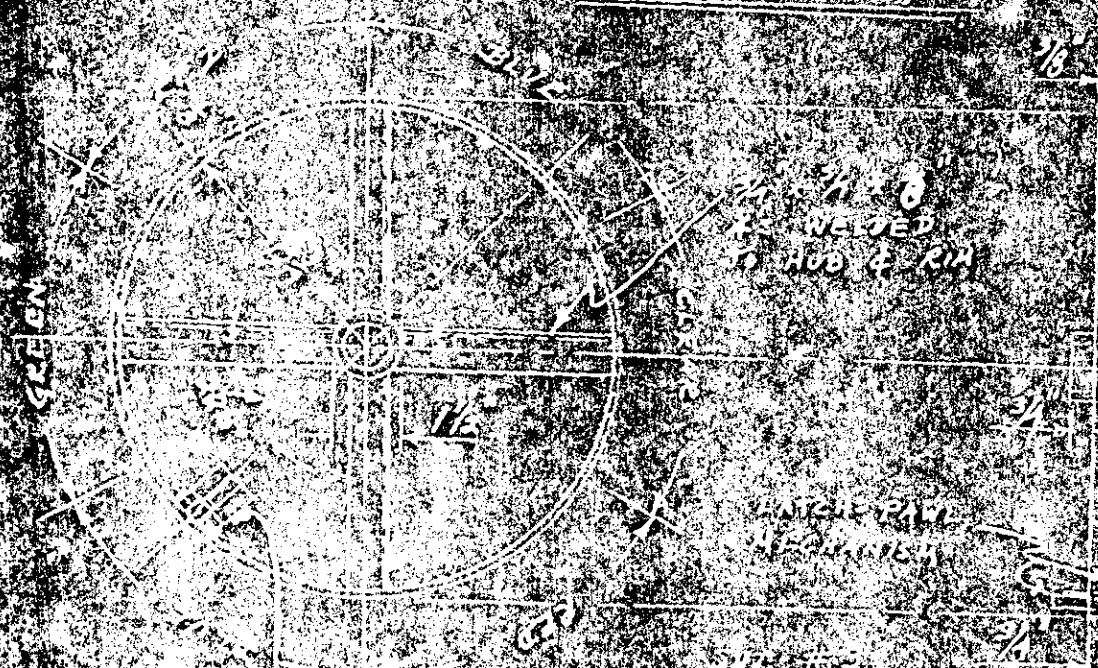
PLASTIC DRUM

METAL END RIM



R.H. GUIDE ROLLER ASSEMBLIES

DRUM #1 (SIDE ELEVATION & R.H. END VIEWS)



DRILL & TAP CIRCUMFERENCE FOR 1/8\"/>

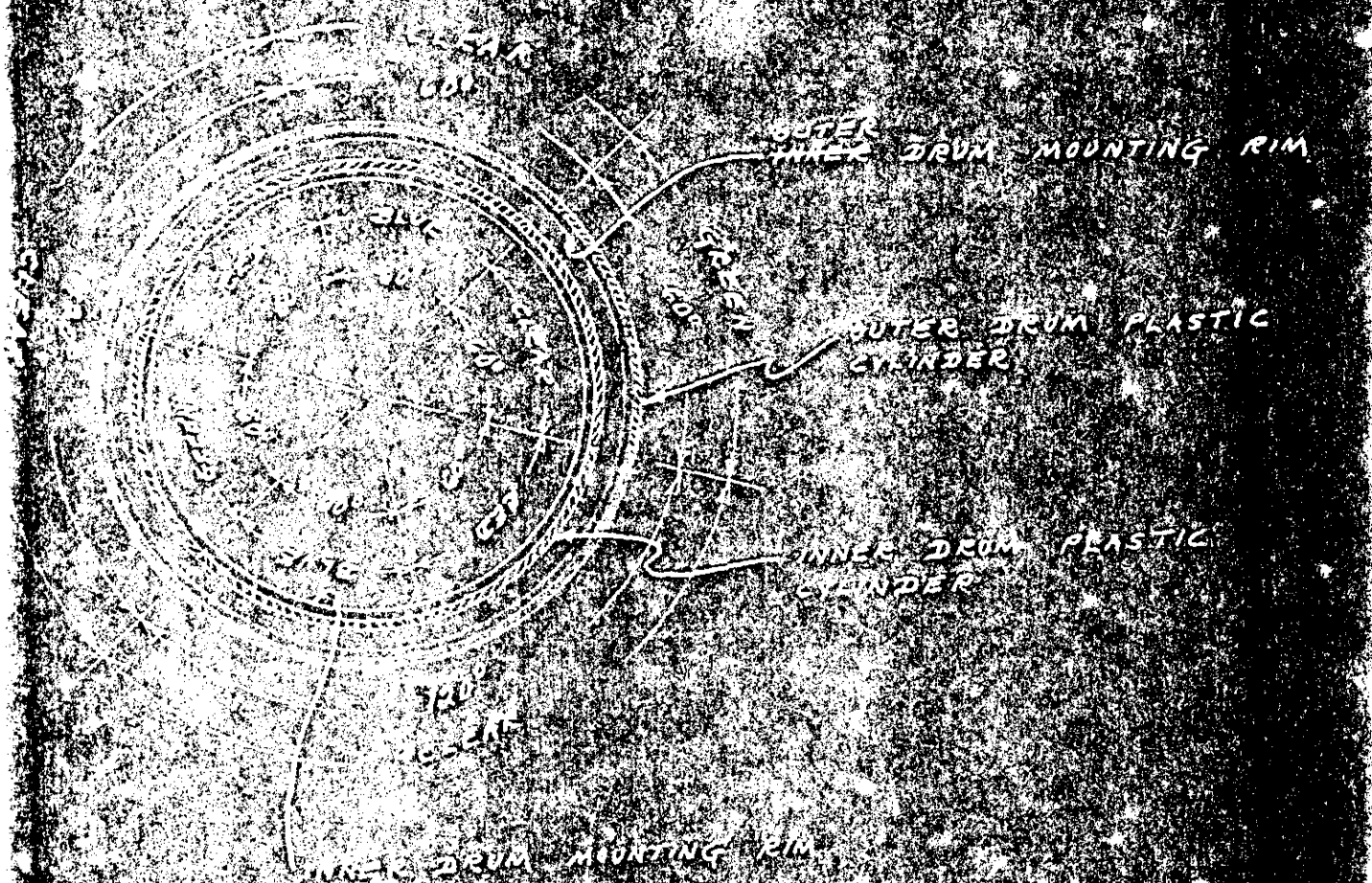
BORE HUB FOR 1 1/8\"/>

ANGLE RAY MECHANISM

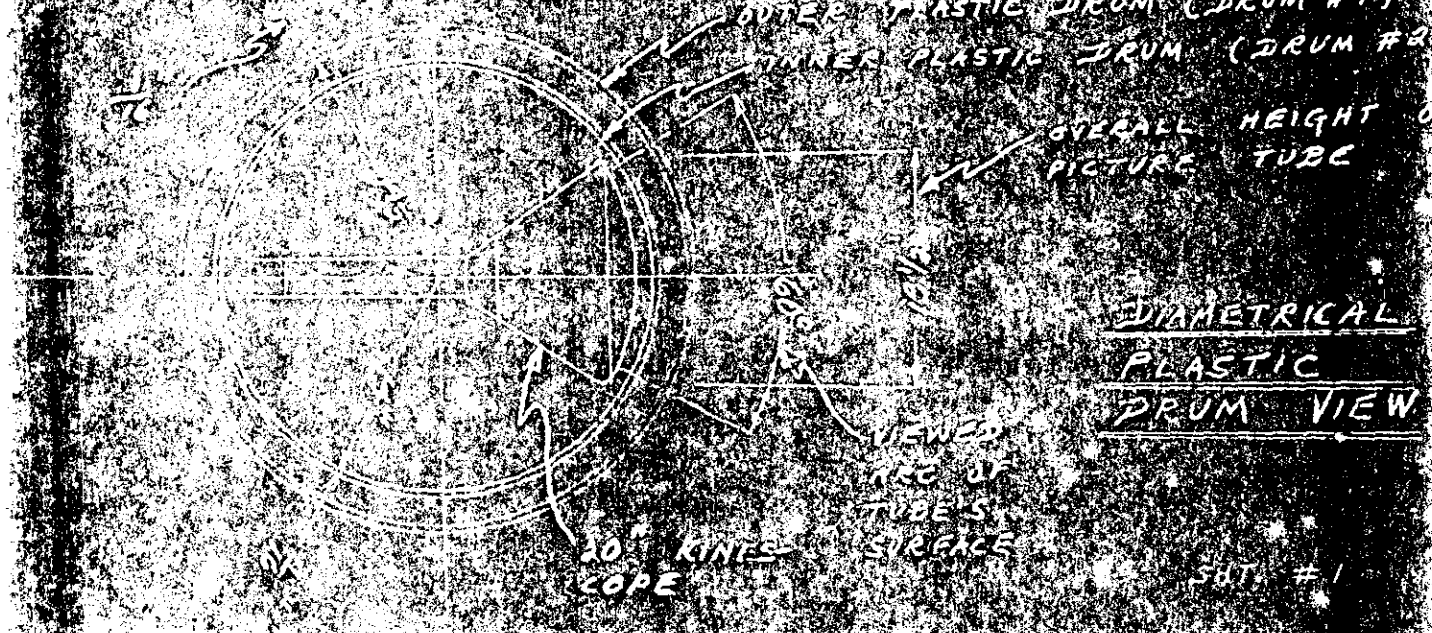
ANGLE RAY MECHANISM (SEE DRAWING)

DRUM #2 DRIVEN END RING

SKETCHES FOR 20" TUBE



SKETCHES SHOWING ARRANGEMENT OF FILTER SECTORS ON DOUBLE DRUM ASSEMBLY



FILTER SECTION "A"

GRIND ADJOINING EDGES OF LUCITE SHEETS TO INDICATED BEVEL 45; LEAVE GRD EDGES ROUGH AND FILL IN WITH DENTAL POLY-METHACRYLATE POLYMER PASTE

FILTER SECTION "B"

PREPARATION OF LONGITUDINAL SEAMS BETWEEN FILTER SECTIONS BOTH DRUMS

GRIND OFF & POLISH PERIPHERAL SURFACE OF UNWELD

6 LUCITE BRG BLOCKS

LUCITE END R5 1/8" THK 3/4" LG. WELD TO DRUM INS

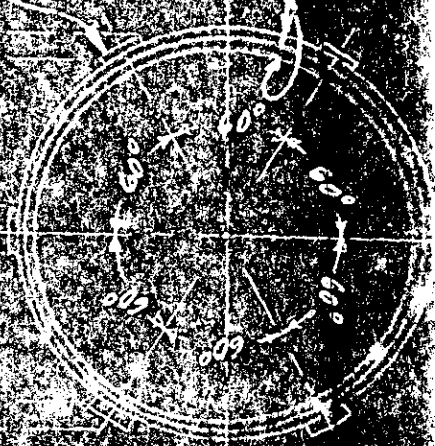
6 EQUIDISTANT 3/8" RD. HD. MACH. SCREWS PER SECTOR TO DRIVEN END RING

DRIVEN END

FILTER SECTION

FILTER SECTION

FILTER SECTION



28 1/2" 14 1/8" O.D.

EXTERNAL PROJECTED HEIGHT OF CHAMFER FILTER SECTION

18 1/2"

DRUM #2 (SIDE ELEVATION & R.H. END VIEWS)

DRUM #2

6-EQUI-SPACED 3/8" R.H.
H2 MACH. SCREWS PER
60° SECTOR TO END RINGS

PLASTIC J

MET
RING

FILTER SECTION

FILTER SECTION

FILTER SECTION

1/8" R.H.
1/8"

1/8" R.H.
1/8"

1/8" R.H.
1/8"

1/8" R.H.
1/8"

R.H. GUIDE R
ASSEMBLIES

DRUM #1 (SIDE ELEVATION & R.H.
END VIEWS)

DI
TA
FE
PO
SC
PE

BOB
FOR
SHAPE

WELDED
HUB & RIM

3/8"

3/4"

1/8"

3/4"

MECHANISM (SEE
FIGURE)

DRUM #2, DR
END-RING



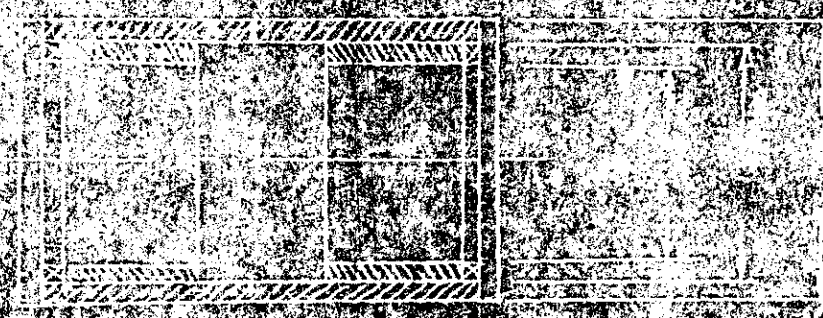
SEE HUB
DETAIL

SEE
DETAIL
HUB

PAVING TO
DRILLS (SEE
DETAIL)

1/4\"/>

1/4\"/>



To Joe F.

Re. Reception Job

Go on. Study the enclosed papers.

Photostat same on premises retaining photos.

Mail immediately signals to Port Jervis,
encl. passed, att. NORMAN.

Send photostat copy to SIXES 4102, only.
If he's gone on vacation or is going on vacation,
I will wait on him until he comes back, then
my own men going come to him. But I will
ask him to put, if possible, sufficient time in, in order
the get started.

Ask NORMAN to get Patent work started on this.

To Joe F

Re Project Job

Get no. only the enclosed papers.

PHOTOSTAT SAME on premises, returning photos

MAIL IMMEDIATELY signals to Port Jervis,
marked personal, att. NORMAN

Get photostat copy to SIGNEE LIOZ, only

If he's gone on vacation or is going on vacation
I want work on same until he comes back, then
we can give something to him. But I want
like him to put, if possible, sufficient time in, in order
to get it started.

Put NORMAN to get latest work started on this

BULKY EXHIBIT

Date received 6/30/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained Warden E. E. Thompson

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Ultimate disposition to be made of exhibit Retained

Estimated date of disposition - To be decided at conclusion of case

List of contents:

125. Two letters addressed to

OSCAR THALER,
45 Crosby Street
New York City

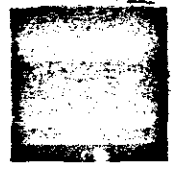
73

100-95068-1B
SEARCHED INDEXED
SERIALIZED FILED
JUL 1 1951
FBI - NEW YORK
JUL 1 1951
JUL 1 1951

W. R. Thacker

1871-1872

1873-1874



TELEVISION AND RADIO

Liquidation Sale Satisfies Pathe

CHICAGO, June 24.—"Complete satisfaction" with results of the liquidation sale of 2 million dollars worth of Pathe and Freed-Eisemann television sets and radios was expressed today by Sidney Joffe, Pathe Television Corp., president.

"I'd bring what's left of the stock to the music show, but I don't expect to have much left," Mr. Joffe declared.

Majestic Offers Special TV Deal To Retailers

Firm Giving Promotional Allowance on 17-Inch Sets

CHICAGO, June 21.—A new television buy was offered dealers this week by the Majestic Radio & Television division of the Wilcox-Gay Corp. Included in the special deal are a 17 inch leatherette table model and a 17 inch mahogany console set, both 1951 models. According to Leonard Ashtach, Majestic president, who would not quote list prices of the sets, the dealers pay "regular prices" for the sets but receive a promotional allowance.

Mr. Ashtach reported that 2,000 units of the table model have been sold since the deal was offered Monday and "almost as many" units of the console.

The special offer will continue until 5,000 units of each set have been sold.

Lacy's, Washington, D. C., was one of the first takers of the field and Hudson-Ross, Chicago, also bought the sets. Quantities sold to these retailers could not be learned.

Meek Adds 14-Inch Model at \$139.95

CHICAGO, June 18.—John Meek Industries has added a 14-inch picture tube television receiver to retail at \$139.95, which was said by John S. Meek, president, to be \$20 under the nearest competitive set in the industry.

The new set has a leatherette table-top cabinet similar to the company's earlier model 616T, 16-inch table set, and has a standard chassis with continuous tuner. The model, identified as MM-614-TL, is in production for immediate delivery.

"We are adding this low cost unit as a 'sales starter' for both distributors and retailers," Mr. Meek said.

TOP EXECUTIVE

GENERAL MANAGEMENT, SALES

With only two companies during last 20 years. Very successful. Advanced from bottom in plant to General Sales Manager, and Vice President, multi-million dollar companies. Now, at 48, interested in another challenge with industrial products, reorganization, or other aid to improve its profit standing. Well acquainted with key government, industry and finance executives. Negotiated numerous prime and sub-contracts. Team builder and cooperator. Confidential inquiry invited.

Z 7568 Times

HOW TO BUILD A SALES FORCE WITH THE MAN

WHO BUILT ONE OF THE COUNTRY'S BEST

Sales Executive with over 23 years' experience in every phase of both industrial and consumer sales development for one of America's largest companies. Exceptionally well qualified for management and direction of existing sales force, or for building new sales organization where selection and training of men are vital to success. Also ideal for company sales representative contracting large buyers and negotiating big contracts. About 50, single, willing to work or travel anywhere. Salary secondary to interesting and challenging opportunity.

Z 7602 TIMES

cooperation for my chief, management team or as assistant to top executive. Married; no children. -Z 7595 Times.

Joseph H. H. Druff

phila, other

lines ahead

close to a

downs.

Despite th

has brought

spring levels

that any fund

do so, because

cost of wool

foods. It was

Other, more

nomine split

planned for

that "any"

standing

ity that d

directors f

prices. A

we

and

the

the

the

the

the

the

the

the

the

the

the

the

the

the

the

the

the

WIN 2 to MEXICO

with all expenses paid!

That's what Pan-American and Emerson are offering Emerson dealers for the best Pan-American Portable window displays. Get your entry blank and window material from your Emerson distributor now!

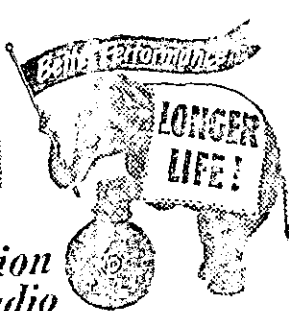
3-Way Pocket Portable Model 584, \$39.95 (INCLUDING BATTERIES)

Pocket Portable Model 640, \$24.95 (INCLUDING BATTERIES)

TESTED Television and Radio

NEW YORK 11, N. Y.

Ver.



11
 (NORMAN, S. 1102) - Norm. ART. - Labeled "CBS - Chamber,
 25, ... about the year" in Retailing 6/27/51 - Paragraph 4
 I find this problem very SIMPLE. I've been a golden
 but I must have IMMEDIATELY the working samples models

(L. L. R. J. K. H. K. H. D) - Note Article labeled "C. B. C. C.
 June. Product 25, or color sets this year in Retailing &
 Sales, "but the firm will ask distributors kindly not
 line produced by the manufacturer.

(Rec. 11. only)
 NORMAN, S. 1102 - I can't imagine your job in
 for being quiet like color television products.
 I want only the engineers who are work-
 ing to be told only what is really going on about
 know. I don't want to know the competition
 NORMAN & Schioz. The fact that it has in-
 kept quiet (Daddy shutting his mouth off) he
 knows back to well & so caused some peo-
 ple upset. However, everyone will refer to the
 project as the "project" only.

How many of the air conditioning units
 will be in the air? But some will be partly? I
 get the impression it is? When does Starratt go
 to work? When the ... for men? Women.
 Is NORMAN SHIPPIING AIR Conditioning units for
 UNIT TEST with MORCANTON? Does L. Chiving? Bud-
 rock? Keeping Brester Mort. at bay? File of Brester
 How is AARON MACH. business?

→ MAKE sure no one will not try to kill you
P.2 - 61

F.A. - Confirming previous note, please come on SAT.
afternoon (leaving at 1400 - 1500) MUCH Thanks for
I know you'll be able to get in. Tell things
only if you are questioned; that you can't make
the week.

(come in with Him).
J.F. - Please Have Spick see me as soon as you
has S.E.A's sentence been reduced to 9 mo. & 17 days
to 8 mo. (8 mo. sentence = 8 Mo. minus 40 DAY
while 9 Mo, 17 DAY sentence = same minus 1 Mo. & 17 DAY
a flat 8 mo. - If the former he would get on
a July 3rd, if latter on Aug. 11th. Of course, if
gets back the 15 days soon enough, he would get
out in either case 15 DAYS earlier.) - What's
on Designation V.A. L.K.? Did you get a message for
N.A.M. on same? - C.F. - to come on an
other day but TUES. - LT. LYNN is on the TOES.
- Met the "devil". I am listed in table
was delivered to (Name & address given to N.A.M.) - (6
bottom Page 2 memo - 6/16/51 - I specified a
P.L. & your free console. No Bill unless & until
say so. Also said deliver an antenna, he
would install himself. Therefore arrange a set
at your convenience. - What's the latest on
the drawing, Army lease at Somerville, & Tele. by
Note that 149th Air Conditioning Unit advertised
1/14 is over 1/2 H.P. & a piece of junk. - You
arrange installation & service for customer. ASK NOR.

To JEF:

Re: "Crosby" Job

GUARD Only the enclosed papers.

PHOTOGRAPH same on previous retaining photostat

MAIL IMMEDIATELY original to PORT Jervis,

marked personal; att. NORMAN

Give photostat copy to SIDNEY LIOZ, only.

If he's gone on vacation or is going on vacation,
I won't work on same until he comes back, then
no sense in even giving same to him. But I want
like him to put it off until, sufficient time in, in order
this get started.

Push NORMAN to get Patent work started on this.

DRUM TYPE COLOR WHEEL FOR BLACK- & WHITE & COLOR TV

Let us consider a drum composed of 6-slots (2 series of the prism) and let us assume that this drum will be used for a 20" as we will assume

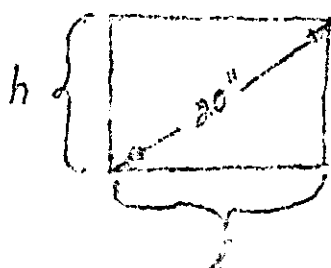


FIG. I

$$1.25h = L$$

then

$$(1.25h)^2 + h^2 = 20^2$$

$$h^2 = \frac{400}{2.56} = 156.2$$

$$h = 12.5"$$

$$L = 1.25(12.5) = 15.6"$$

would be the dimensions of the tube. For each slot to "cover" the prism would be necessary that

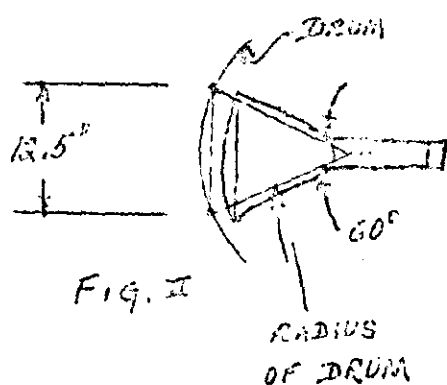


FIG. II

RADIUS
OF DRUM

of the drum.

Let us now suppose the drum is formed a section shown in Fig. 3, in which the slots curved members "fitting" into a retainer rim. These slots are to consist of $\frac{1}{16}$ " thick. of glass sheet, and their length were to be 17", then each would have a volume of

$$2\pi R^2 \left[\frac{60}{360} \right] t = \frac{2\pi (12.5)(17)(60)}{360}$$

$$13.9 \text{ in.}^3$$

and a specific gravity of 1.18, then

$$\frac{62.5 \frac{\text{lb}}{\text{ft.}^3}}{1728 \frac{\text{in.}^3}{\text{ft.}^3}} \cdot 1.18 \cdot 13.9 \text{ in.}^3 = 0.59$$

would be the weight of each slot, where:-

62.5 $\frac{\text{lb}}{\text{ft.}^3}$ is taken as the density of glass

In the standard CBS color disc, 9 discs (3 series of the primary three) are at 1440 rpm. This would set a speed of

$$\frac{9}{6}(1440) = 2160 \text{ rpm for the 6-slot drum}$$

This would mean an angular velocity of

$$\frac{1770 \frac{\text{rev.}}{\text{min.}} (2\pi \frac{\text{rad.}}{\text{rev.}})}{60 \frac{\text{sec.}}{\text{min.}}} = 150.8 \frac{\text{rads.}}{\text{sec.}}$$

The centrifugal force acting on each slot would then be:-

$$F_c = \frac{W}{g} \omega^2 r$$

$$= \frac{0.594 \text{ lb.}}{32 \frac{\text{ft.}}{\text{sec.}^2}} \cdot \left[150.8 \frac{\text{rad.}}{\text{sec.}} \right]^2 \frac{12.5 \text{ in.}}{12 \frac{\text{in.}}{\text{ft.}}}$$

$$= 440 \#$$

and both retainer rings would therefore be said to act under a load

$$440 \frac{\#}{\text{slot}} (6 \text{ slots}) = 2640 \#$$

together, and

$$\frac{2640 \#}{2 \text{ retainer rings}} = 1320 \frac{\#}{\text{ring}}$$

To hold the tensile stress in each ring to $\frac{1}{5}$ of an assumed ultimate value of 76,000 #/in.² with a $\frac{5}{8}$ " wide ring would require a

$$\frac{1320 \#}{0.75 \text{ in.} (2)} = 14,000 \frac{\#}{\text{in.}^2}$$

$$\frac{1320 \#}{0.75 \text{ in.} (76,000 \frac{\#}{\text{in.}^2})} = 0.1258" = t$$

and the slot must also be reviewed as a uniformly loaded beam with a simply supported end and end:-

$$W = wL$$

$$M = \frac{wx}{2} (L-x) = EI \left(\frac{d^2 y}{dx^2} \right)$$

$$\frac{w}{2} (L-x^2) = EI \left(\frac{d^3 y}{dx^3} \right)$$

$$\frac{w}{2EI} \left(\frac{Lx^2}{2} - \frac{x^3}{3} \right) + C_1 = \frac{dy}{dx}$$

But $\frac{dy}{dx} = 0$, when $x = \frac{L}{2}$, and so:-

$$\frac{w}{2EI} \left(\frac{L^3}{8} - \frac{L^3}{24} \right) + C_1 = 0$$

$$C_1 = - \frac{w}{24EI} \left(\frac{L^3}{2} \right) = - \frac{wL^3}{48EI}$$

$$\frac{dy}{dx} = \frac{w}{24EI} \left(\frac{Lx^2}{2} - \frac{x^3}{3} \right) - \frac{wL^3}{48EI}$$

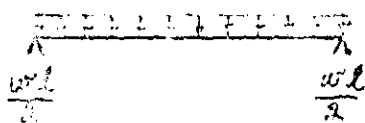


Fig. II

$$y = \frac{w}{2EI} \left(\frac{Lx^3}{6} - \frac{x^4}{12} \right) - \frac{wL^3x}{24EI} + C_2$$

But, since $y = 0$ when $x = 0$, then

$$C_2 = 0$$

and

$$y = \frac{w}{2EI} \left(\frac{Lx^3}{6} - \frac{x^4}{12} - \frac{L^3x}{12} \right)$$

At $x = \frac{L}{2}$, it is clear that (y) would have its maximum value, $(y)_{\max}$ would be given by:-

$$y_{\max} = \frac{w}{2EI} \left(\frac{L^4}{48} - \frac{L^4}{192} - \frac{L^4}{24} \right)$$

$$= -\frac{5wL^4}{384EI} = -\frac{5WL^3}{384EI}$$

This gives us a form for computing the deflection, and the stresses, in the plates when the rotor has up to full design speed. It is now necessary to find the value of (I) for the plates.

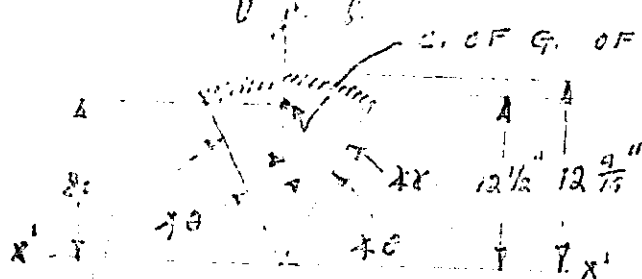


Fig. II

It is clear that the mean radius $r = 12 \frac{1}{2}$ inches and $r_{\text{mean}} = 12 \frac{9}{16}$ inches (which is $12 \frac{17}{32}$ inches) would be the radius of gyration of the plate indicated in Fig. II with respect to the axis $x-x'$. Therefore the x-x'-sectional area of the plate is approximately

$$\frac{(2\pi r_{\text{mean}}) 48}{360} =$$

$$\frac{1}{16} (2\pi) (12 \frac{17}{32}) (60) = 0.822$$

sq. in. (I) with respect to the $x-x'$ axis would be

$$A k^2 = 0.822 (12 \frac{17}{32})^2 = 129 \text{ in.}^2$$

The center of gravity of the plate would be given by:-

$$y_0 = \frac{r_{\text{mean}} \sin \theta}{\sin \theta} = \frac{(12 \frac{17}{32}) (\sin 90^\circ)}{\sin 90^\circ} = \frac{12 \frac{17}{32} (0.5)}{0.5236} = 1.2$$

If (I_0) is the moment of inertia of the plate section about its own axis of gravity, then

$$I_{xx'} = I_0 + A y_c^2$$

and so

$$129 \text{ in.}^4 = I_0 + 0.822 (11.95)^2$$

$$129 - 0.822 (142.5) = 129 - 117.5 = 11.5 \text{ in.}^4$$

From this, it follows that

$$y_{\max} = -\frac{5WL^3}{384EI} = -\frac{5(740)(17)^3}{384(2)(10^6)(11.5)} = 0.00122 \text{ in.}$$

which is acceptable if it does not involve an excessive stress.

$$y_{\max} = \frac{5WL^3}{384EI}$$

and

$$M_{\max} = \frac{wL^2}{8} = \frac{WL}{8}$$

Therefore

$$y_{\max} = \frac{WL}{8} \cdot \frac{5L^2}{48EI} = \frac{5ML^2}{48EI}$$

But

$$M = SZ$$

where

M = Moment induced in the beam — in-lb.

Z = Sectional modulus of the beam — in.³

S = stress induced in the beam — #/in.²

and

$$\frac{I}{c} = Z$$

where

c = distance of the extreme fibre from the neutral axis of the beam

and hence

$$y_{\max} = \frac{5(S)(\frac{I}{c})L^2}{48EI} = \frac{5SL^2}{48Ec}$$

By this equation,

$$0.00122 \text{ in.} = \frac{5(12 \frac{7}{8} - 11.5)(17^2)S}{48(2)(10^6)} = \frac{5(1.375)(17^2)S}{96(10^6)(1.375)}$$

$$\frac{1.032(0.00122)(96)(10^6)}{5(1.375)(289)} = S = \frac{8.38}{1.375} \text{ #/in.}^2$$

ONE-PIECE SHAFT

3' 4'

REVOLVING
DRUG #1

REPLYING
TO THE

1. The first group of people who are interested in the results of the study are the researchers themselves. They want to know if the study was successful in achieving its goals and if the data collected is reliable and valid.

Fig. VI



FIG. VIII

To approximate the combined weights of the Drums, let us proceed as follows:

12 disks - 17" dia.

$$\frac{2\pi r^2 60}{360} = \frac{2\pi (12.5)^2 (60)}{360} = 13.1" \text{ wide}$$

and $\frac{1}{8}"$ thick

would weigh

$$\frac{12(17)(13.1)(0.0625)(62.5)(1.18)}{172.8} = 7.17\#$$

and, if we estimate each end-ring at 3#, then the disks would weigh 12# in total, to give a total weight approximately 20#. This could be said to have a radius of gyration of approximately 13", giving the Drum a Σmr^2 of:

$$\Sigma mr^2 = 20 \left(\frac{13}{12} \right)^2 = 23.5 \text{ ft.-lb.}^2$$

For such a drum to attain a velocity of $150.8 \frac{\text{revs.}}{\text{sec.}}$,

$$\frac{23.5}{2(32)} (150.8)^2 = 15,700 \text{ ft.-lb.} = 8,350 \text{ ft.-lb.}$$

of energy is required in the form of electrical energy. But it is evidently, not a large motor, and it would be desirable to reduce this figure. The value of the indicated figure, but as this is to reduce the weight of the motor, particularly the weight at the indicated manner of operation, let us limit for the 4-end-rings in total. In that case,

$$\frac{11.7}{2} (150.8)^2 = 7,240 \text{ ft.-lb.} = 3,620 \text{ ft.-lb.}$$

of energy is required electrical energy, and if this were supplied in a

$$\frac{3620}{7240 \text{ ft.-lb.}} = \frac{105}{(60 \text{ revs.})(550 \text{ ft.-lb./rev.})} = 0.248 \text{ HP}$$

motor would be required.

In bringing the Drum around, for a stop, let us assume 2 Drums as stipulated. Then the negative acceleration of

$$a = \frac{v}{t} = \frac{2(150.8 - 0)}{60} = 5.03 \frac{\text{revs.}}{\text{sec.}}$$

is indicated, and the Torque-rating of the brake would have to be

$$\frac{10.17}{32} (5.03) = 523 \text{ ft.-lb.}$$

Were this to be applied via a mechanical brake, this would mean, applied on a 13" radius, a

$$\frac{15,975 \text{ ft-lb.} \left(12 \frac{\text{in.}}{\text{ft.}}\right)}{(13 \text{ in.})} = 14,777 \text{ #}$$

braking-force. If an eddy-current brake were to be used, it would be one in which a

$$\frac{36.20}{72.40 \text{ (ft-in.)}} = \frac{60.3}{291.3 \frac{\text{ft-lb.}}{\text{sec.}}}$$

energy consumption is planned. The theoretical electrical rating of the motor would then have to be:-

$$\frac{60.3}{291.3 \frac{\text{ft-lb.}}{\text{sec.}}} \left(0.746 \frac{\text{H.P.}}{\text{ft-lb.}}\right) = 0.0835 \text{ KW}$$

but because eddy current brakes are quite inefficient, the actual brake rating would have to be substantially larger. A mechanical input applied to the output shaft of the driving motor also discloses considerable

The question arises of applying the braking force until a minimum speed is obtained, and then leaving it to the positive pin to bring the drum to a full-stop. The combined positive and displacement of the drum from drum #2. Assume the use of a 1/4" diameter round pin with a cantilever length of 2". By formula (for cantilever beams)

$$M = PL^2 = 52 = 5 \frac{I}{E}$$

$$f = \frac{PL^3}{3EI}$$

or in other words

$$f = \frac{SL^2}{9Ec}$$

Using this formula, we see that for a stress limit which is 75% of the elastic limit, and taking the elastic limit to be 50,000 psi, then for a material for which $E = 2.6 \times 10^6$

$$f = \frac{0.75 (30,000 \frac{\text{lb.}}{\text{in.}^2}) (2 \text{ in.})^2}{3 (2.6 \times 10^6 \frac{\text{lb.}}{\text{in.}^2}) \left(\frac{1}{4} \text{ in.}\right)} = 0.00924 \text{ in.}$$

Quite obviously, the pin would be working as a spring storing up energy, and so, if $P(K)$ represents the force stored in the spring per inch

deflection, then

$$W (\text{work stored in the spring}) = \int_{y=0}^{y=y} Ky = \frac{K}{2} y^2$$

where y = the limiting deflection of the spring. Thus, if we re-arrange equation

$$f = \frac{Pe^3}{3EI}$$

to the form

$$\frac{3EI}{L^3} = \frac{P}{f} = K = \frac{3\pi E d^4}{L^3}$$

we find that

$$K = \frac{3\pi (26 \times 10^6 \text{ psi}) (1/4)^4}{2^3} = 119,500 \text{ #/in.}$$

and so this, the work stored by a deflection of 0.00924" would be

$$\frac{1}{2} (119,500 \text{ #/in.}) (0.00924)^2 = 5.08 \text{ in.-lbs.}$$

or

$$\frac{5.08 \text{ in.-lbs.}}{12 \frac{\text{in.}}{\text{ft.}}} = 0.423 \text{ ft.-lbs.}$$

Therefore, the would limit the velocity of the drum to

$$0.423 = \frac{10.17}{2(32)} \omega^2$$

$$\left[\frac{2(32)}{10.17} \right]^{1/2} \omega = [2.75]^{1/2} = 1.66 \text{ rads./sec.}$$

When the positioning pin is sent "home", this would mean that the tip of the probe would be positioned the Drum, thereby speed from 150.8 in/sec. to 1.66 in/sec., after which the pin would take care of the positioning of the Drum according to a full stop.

During the use of a 1/2 horsepower motor drive and assume that before Drum #2 is properly positioned for black-and-white recording, it is now proceed to the design of its second positioning

The velocity of the Brown #2 assembly at the end of the above-mentioned 120° can be derived by applying the ratio of: - The specified motor, compared required motor, to the acceleration on which the computer is based. Thus, the computer required motor would raise the speed of the Brown Assembly from zero to 156.8 radians/sec. in 60 sec., or acceleration of

$$156.8 = \frac{1}{2} a (60)$$

$$\frac{2(156.8)}{60} = 5.13 \text{ rads./sec.}^2$$

Using a 0.125 HP motor in the place of the 0.115 HP computer required motor may take

$$\frac{(0.125 \text{ HP})}{(0.115 \text{ HP})} [5.13 \text{ rads./sec.}^2] = 5.98 \text{ rads./sec.}^2$$

is the acceleration which the specified motor would apply. The arc of travel constitutes a travel of

$$\frac{120}{360} (2\pi) = \frac{2}{3} \pi \text{ radians}$$

The above-given acceleration of 5.98 rads./sec.² would be applied to an assembly with a $\Sigma \text{ m r}^2$ of 10.17 lb.-ft.², while in the motor of 0.115 HP alone roughly one-half of this $\Sigma \text{ m r}^2$ is involved; and the acceleration of the #2 Brown (assuming the same motor as before) would be

$$2(5.98) = 11.96 \text{ rads./sec.}^2$$

$$s = \frac{1}{2} at^2$$

$$\frac{2}{3} \pi = \frac{1}{2} (11.96) (t^2)$$

$$t = \left[\frac{2(2\pi)}{3(11.96)} \right]^{1/2} = 0.35^{1/2} = 0.592 \text{ sec}$$

Thus, the Brown #2 Brown would travel the mentioned arc; and

$$\frac{1}{2} at^2 = \frac{1}{2} (11.96) (0.592)^2 = 3.54 \text{ rads./sec.}$$

Thus, the Brown #2 Brown would travel the arc of travel. The angular position is given by the initial angular position Brown #2 Brown plus the angular displacement. Thus two positions

of the two functions which the latch serves: - (1) firstly, it serves to stop and position Drum #2 with respect to Drum #1 when black-and-white viewing is intended; and (2) it is the means by which Drum #1 is motivated along with Drum #2 in color-viewing. In stopping Drum #2 after ~~it~~ has Drum #1 has already been positioned, it must absorb the flywheel energy of Drum #2. This would mean, since E_{max} for each Drum has been taken at 5.085 lb.-ft.², that

$$\frac{(5.085 \text{ lb.-ft.}^2)}{(2)(32 \frac{\text{ft.}}{\text{sec.}^2})} (3.54 \text{ rads./sec.}) = 0.382 \text{ ft.-lbs.}$$

of energy would have to be absorbed. By reference to the previous calculation concerning the pin which positions Drum #1, it is clear that a member with a sectional modulus equal to a $\frac{1}{4}$ " round would more than suffice for this service, if it were no longer than the aforementioned pin. According to the second criterion for the design of the latch member, it would be required at a maximum to transmit a torque equal to

$$\frac{(10.17 \text{ lb.-ft.}^2)}{(32 \frac{\text{ft.}}{\text{sec.}^2})} (5.085 \text{ rads./sec.}) = 1.671 \text{ ft.-lb.}$$

or

$$(1.671 \text{ ft.-lb.}) (12 \frac{\text{in.}}{\text{ft.}}) = 22.45 \text{ in.-lb.}$$

~~At a design stress limit of~~ since the latch is located on about a 15" radius from the axis of rotation, the torque indicated above implies a load of

$$\frac{22.45 \text{ in.-lb.}}{15 \text{ in.}} = 1.728 \text{ lb.}$$

applied to the end of the latch. Were the latch 2" lg., this would mean the inducing of a bending load of

$$1.728 (2) = 3.456 \text{ in.-lb.}$$

which is, in fact, insignificant, and worthy of no further computations.

This brings us to the question of the shafting by which the Drums are motivated. On reconsideration of the loads involved, it is practical, from a superficial observation, to think in terms of a cantilever shafting mounting of the Drums from one end as per the figure below:-

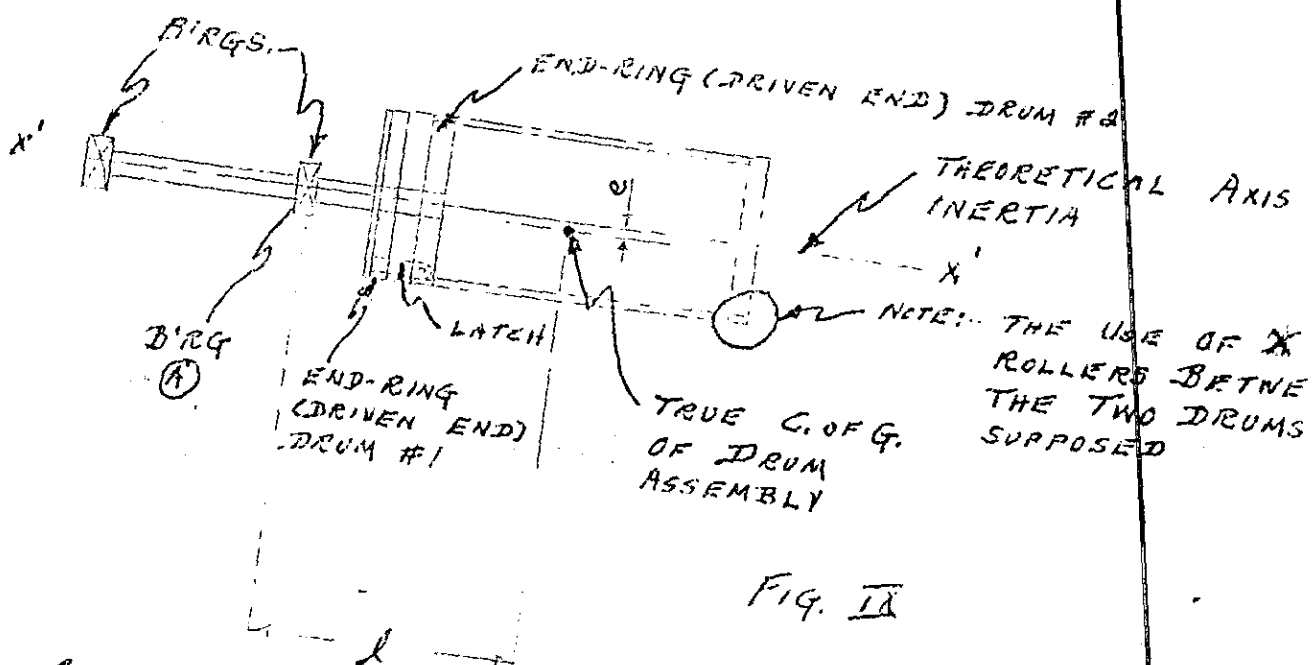


FIG. 1A

As portrayed above, the double-drum assembly is considered as a single concentrated load on a cantilever shaft, with the length of the shaft being taken as equal to the ^{horizontal} span between Brg. (A) and the true center of gravity of the combined drum assembly. The use of spacer-rollers as indicated contributes towards the validity of this viewpoint.

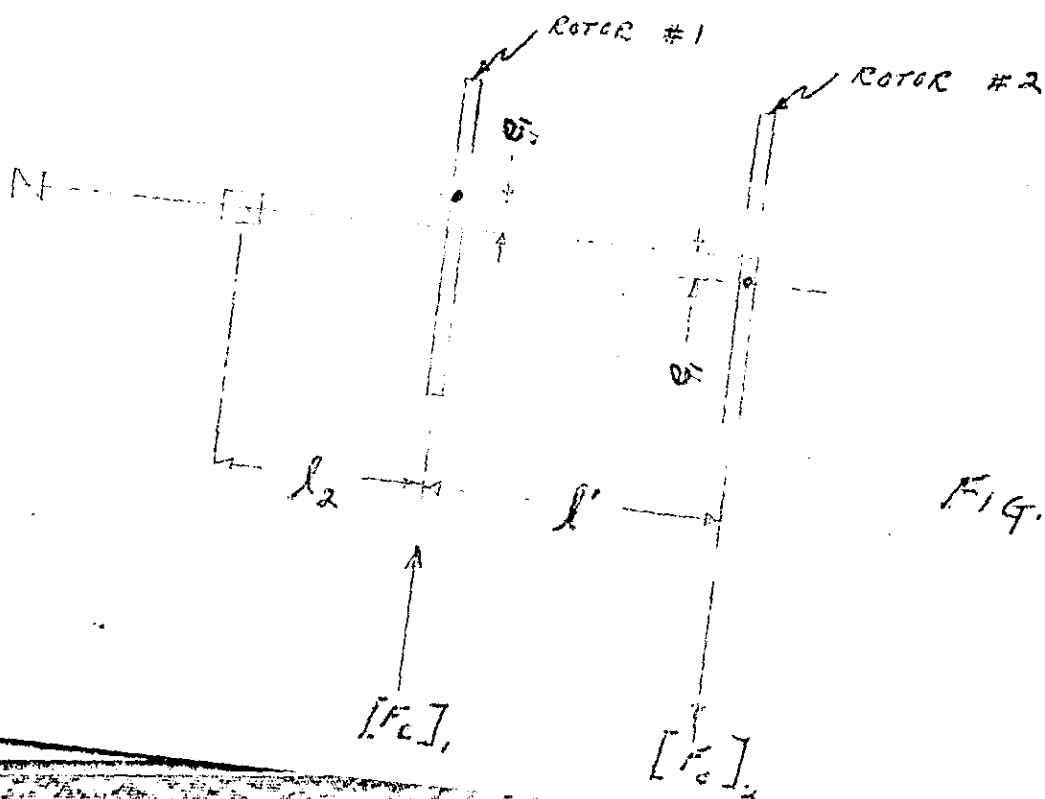
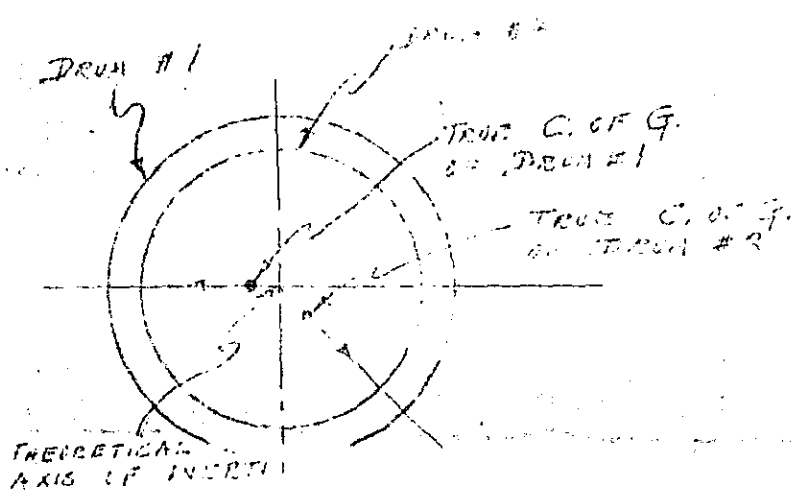


FIG. 10



SCHEMATIC END VIEW
OF ASSEMBLY (DRUMS)

FIG. XI

The figure taken above is, fundamentally, a simplified and enlarged one. It is in operation to the view of the shaft, to carry the distinct concentrated loads. Concerning the shaft the carrying two distinct concentrated loads, there is some for one, two possibilities (assuming that each drum has been fastened to identical rollers as to bearing). The possibilities are illustrated in Figs. 10

1. The shaft is in the situation in which the action of identical weights is identically opposite solution. Section there are mounted on the same shaft;

2. The shaft is in the situation in which the two rollers of identical weight have their identical oscillation acting in different axial planes.

Analyzing the situation presented by Fig. 1, it is observed since the oscillations of the rollers are identical, each must begin with a twist or centrifugal force on the shaft, as given by:

But as is (I_1) and (I_2) are not equal, the rollers, in cases where they are identically opposed oscillations, they will produce a rotational moment (or rotational couple) of magnitude:

$$\frac{W}{g} \omega^2 e l$$

For as long as the rotational couple exists, the rollers will each have a tendency of the shaft to the rollers. The left of $(l_2 + l/2)$ to an upward rotation, and every rotation to the right of $(l_2 + l/2)$ to a downward rotation. But obviously the mentioned position of the rollers would present different reactions to the couple, and would consequently result in

direction of deflection from the horizontal axis of inertia of different cross section $x = x_2 + l'$. Since the different magnitudes would be the moment of (x) or (F_{c_2}) , the result would be directly proportional to the distance from the deflection pictorially below:

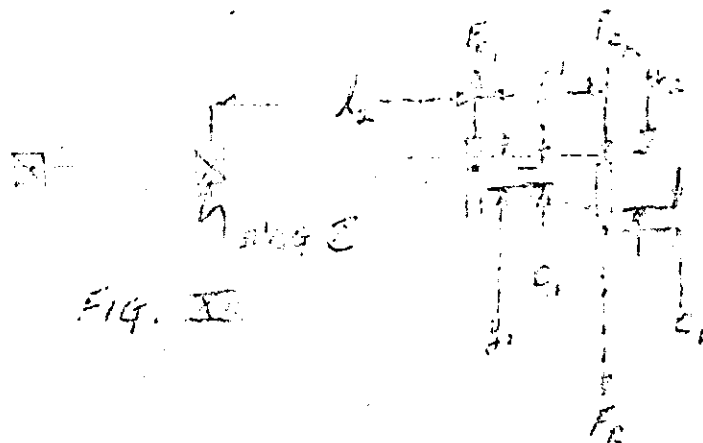


Fig. II

Therefore, a situation in which the forces (F_{c_1}) and (F_{c_2}) can be reduced according to

$$\frac{(F_{c_2})(l_2 + l') - (F_{c_1})l_2}{(l_2 + l')} = F_R$$

Therefore, the force (F_R) acting on a beam of $(l_2 + l')$ length. Its moment acting on any section of the beam would be

$$M_x = (F_R)(l_2 + l' - x) = EI \frac{d^2y}{dx^2}$$

Therefore, the beam deflection, would take the form

$$y = -\frac{F_R}{EI} \left(\frac{(l_2 + l')x^2}{2} - \frac{x^3}{6} \right)$$

Therefore, according to the deflection, a K-value

$$K = \frac{EI}{(l_2 + l')^3} \left[\frac{(l_2 + l')^3}{6} - \frac{(l_2 + l')^2}{2} \right]$$

Therefore, the deflection would be

$$y = \frac{F_R}{K}$$

and

$$F_{c2} = \frac{W}{g} (v_{c2} + c_1) \omega^2$$

Moreover, since

$$F_{c2} + F_{c1} = K g_2$$

we may write

$$\frac{W}{g} (g_1 - c_1) \omega^2 + \frac{W}{g} (c_1 + g_2) \omega^2 = K g_2$$

also we have

$$\omega^2 (g_1 + g_2) = \frac{K g_2}{W} g_2$$

$$\frac{\omega^2 g_2}{\frac{K g_2}{W} g_2} = \frac{g_2}{g_2} = \frac{\omega^2}{\frac{K g_2}{W}} = 1$$

3. Implications of the final equation are:-

- 1) as (ω^2) approaches $(\frac{K g_2}{W})$ in value, (g_2) would attain extremely large values, becoming infinite when $\omega^2 = \frac{K g_2}{W}$ (i.e. the shaft would fail).
- 2) since (g_2) is expressed in terms of (g_1) with $[\frac{K g_2}{W} - 1]^{-1}$ as a multiplier of (g_1) , it is clear that when $\omega < (\frac{K g_2}{W})$ approaches the limit in magnitude, then the portion of the shaft beneath Rotor #1 is the critical section; while, as (ω^2) approaches $(\frac{K g_2}{W})$, the critical section becomes

$$g_2 = \frac{g_1}{1 - \frac{K g_2}{W}}$$

means that the portion of the shaft above Rotor #2 is the critical portion.

It will be apparent by Fig. 11 that only one of the two rotors, being a small distance apart, would be subjected to two rotors. It is a concentrated load, or the weight of a concentrated load is not to be placed around the support of the shaft supporting the two rotors. The (g_2) is obtained, also, from (g_1) , the shaft becomes a fixed end at the base of the shaft and is not the dynamic or

(10) (11) in favor of the set down by the normal static
 relationship. It concludes the whole thing. From the dynamic
 relationship between (10) and (11) it would seem that any attempt to open
 it up is quite than the first increase of speed. In fact, there is
 open to some extent as the first increase of speed. I
 in fact, the first increase of speed is concentrated in
 an initial increase of speed with the set down as established
 "large amount of work" required.

P. 10, 11, 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, 23, 24, 25, 26, 27, 28, 29, 30, 31, 32, 33, 34, 35, 36, 37, 38, 39, 40, 41, 42, 43, 44, 45, 46, 47, 48, 49, 50, 51, 52, 53, 54, 55, 56, 57, 58, 59, 60, 61, 62, 63, 64, 65, 66, 67, 68, 69, 70, 71, 72, 73, 74, 75, 76, 77, 78, 79, 80, 81, 82, 83, 84, 85, 86, 87, 88, 89, 90, 91, 92, 93, 94, 95, 96, 97, 98, 99, 100, 101, 102, 103, 104, 105, 106, 107, 108, 109, 110, 111, 112, 113, 114, 115, 116, 117, 118, 119, 120, 121, 122, 123, 124, 125, 126, 127, 128, 129, 130, 131, 132, 133, 134, 135, 136, 137, 138, 139, 140, 141, 142, 143, 144, 145, 146, 147, 148, 149, 150, 151, 152, 153, 154, 155, 156, 157, 158, 159, 160, 161, 162, 163, 164, 165, 166, 167, 168, 169, 170, 171, 172, 173, 174, 175, 176, 177, 178, 179, 180, 181, 182, 183, 184, 185, 186, 187, 188, 189, 190, 191, 192, 193, 194, 195, 196, 197, 198, 199, 200, 201, 202, 203, 204, 205, 206, 207, 208, 209, 210, 211, 212, 213, 214, 215, 216, 217, 218, 219, 220, 221, 222, 223, 224, 225, 226, 227, 228, 229, 230, 231, 232, 233, 234, 235, 236, 237, 238, 239, 240, 241, 242, 243, 244, 245, 246, 247, 248, 249, 250, 251, 252, 253, 254, 255, 256, 257, 258, 259, 260, 261, 262, 263, 264, 265, 266, 267, 268, 269, 270, 271, 272, 273, 274, 275, 276, 277, 278, 279, 280, 281, 282, 283, 284, 285, 286, 287, 288, 289, 290, 291, 292, 293, 294, 295, 296, 297, 298, 299, 300, 301, 302, 303, 304, 305, 306, 307, 308, 309, 310, 311, 312, 313, 314, 315, 316, 317, 318, 319, 320, 321, 322, 323, 324, 325, 326, 327, 328, 329, 330, 331, 332, 333, 334, 335, 336, 337, 338, 339, 340, 341, 342, 343, 344, 345, 346, 347, 348, 349, 350, 351, 352, 353, 354, 355, 356, 357, 358, 359, 360, 361, 362, 363, 364, 365, 366, 367, 368, 369, 370, 371, 372, 373, 374, 375, 376, 377, 378, 379, 380, 381, 382, 383, 384, 385, 386, 387, 388, 389, 390, 391, 392, 393, 394, 395, 396, 397, 398, 399, 400, 401, 402, 403, 404, 405, 406, 407, 408, 409, 410, 411, 412, 413, 414, 415, 416, 417, 418, 419, 420, 421, 422, 423, 424, 425, 426, 427, 428, 429, 430, 431, 432, 433, 434, 435, 436, 437, 438, 439, 440, 441, 442, 443, 444, 445, 446, 447, 448, 449, 450, 451, 452, 453, 454, 455, 456, 457, 458, 459, 460, 461, 462, 463, 464, 465, 466, 467, 468, 469, 470, 471, 472, 473, 474, 475, 476, 477, 478, 479, 480, 481, 482, 483, 484, 485, 486, 487, 488, 489, 490, 491, 492, 493, 494, 495, 496, 497, 498, 499, 500, 501, 502, 503, 504, 505, 506, 507, 508, 509, 510, 511, 512, 513, 514, 515, 516, 517, 518, 519, 520, 521, 522, 523, 524, 525, 526, 527, 528, 529, 530, 531, 532, 533, 534, 535, 536, 537, 538, 539, 540, 541, 542, 543, 544, 545, 546, 547, 548, 549, 550, 551, 552, 553, 554, 555, 556, 557, 558, 559, 560, 561, 562, 563, 564, 565, 566, 567, 568, 569, 570, 571, 572, 573, 574, 575, 576, 577, 578, 579, 580, 581, 582, 583, 584, 585, 586, 587, 588, 589, 590, 591, 592, 593, 594, 595, 596, 597, 598, 599, 600, 601, 602, 603, 604, 605, 606, 607, 608, 609, 610, 611, 612, 613, 614, 615, 616, 617, 618, 619, 620, 621, 622, 623, 624, 625, 626, 627, 628, 629, 630, 631, 632, 633, 634, 635, 636, 637, 638, 639, 640, 641, 642, 643, 644, 645, 646, 647, 648, 649, 650, 651, 652, 653, 654, 655, 656, 657, 658, 659, 660, 661, 662, 663, 664, 665, 666, 667, 668, 669, 670, 671, 672, 673, 674, 675, 676, 677, 678, 679, 680, 681, 682, 683, 684, 685, 686, 687, 688, 689, 690, 691, 692, 693, 694, 695, 696, 697, 698, 699, 700, 701, 702, 703, 704, 705, 706, 707, 708, 709, 710, 711, 712, 713, 714, 715, 716, 717, 718, 719, 720, 721, 722, 723, 724, 725, 726, 727, 728, 729, 730, 731, 732, 733, 734, 735, 736, 737, 738, 739, 740, 741, 742, 743, 744, 745, 746, 747, 748, 749, 750, 751, 752, 753, 754, 755, 756, 757, 758, 759, 760, 761, 762, 763, 764, 765, 766, 767, 768, 769, 770, 771, 772, 773, 774, 775, 776, 777, 778, 779, 780, 781, 782, 783, 784, 785, 786, 787, 788, 789, 790, 791, 792, 793, 794, 795, 796, 797, 798, 799, 800, 801, 802, 803, 804, 805, 806, 807, 808, 809, 810, 811, 812, 813, 814, 815, 816, 817, 818, 819, 820, 821, 822, 823, 824, 825, 826, 827, 828, 829, 830, 831, 832, 833, 834, 835, 836, 837, 838, 839, 840, 841, 842, 843, 844, 845, 846, 847, 848, 849, 850, 851, 852, 853, 854, 855, 856, 857, 858, 859, 860, 861, 862, 863, 864, 865, 866, 867, 868, 869, 870, 871, 872, 873, 874, 875, 876, 877, 878, 879, 880, 881, 882, 883, 884, 885, 886, 887, 888, 889, 890, 891, 892, 893, 894, 895, 896, 897, 898, 899, 900, 901, 902, 903, 904, 905, 906, 907, 908, 909, 910, 911, 912, 913, 914, 915, 916, 917, 918, 919, 920, 921, 922, 923, 924, 925, 926, 927, 928, 929, 930, 931, 932, 933, 934, 935, 936, 937, 938, 939, 940, 941, 942, 943, 944, 945, 946, 947, 948, 949, 950, 951, 952, 953, 954, 955, 956, 957, 958, 959, 960, 961, 962, 963, 964, 965, 966, 967, 968, 969, 970, 971, 972, 973, 974, 975, 976, 977, 978, 979, 980, 981, 982, 983, 984, 985, 986, 987, 988, 989, 990, 991, 992, 993, 994, 995, 996, 997, 998, 999, 1000.

$$W = 11.17 \text{ ft}$$

$$L = 1.4 \text{ ft}$$

$$S = 15.11 \text{ ft/sec}$$

$$C = 15.8 \text{ ft/sec}$$

$$E = \frac{1}{2} \pi r^2 \rho \omega^2 \text{ (for rate diameter)}$$

$$E = \frac{1}{2} \pi (1.4)^2 (15.11)^2 = 0.14$$

$$E_1 = 2.5 (10^4) \text{ ft/sec}$$

$$E_2 = 2.5 (10^4) \text{ ft/sec}$$

$$E_3 = 2.5 (10^4) \text{ ft/sec}$$

$$E_4 = 2.5 (10^4) \text{ ft/sec}$$

$$E_5 = 2.5 (10^4) \text{ ft/sec}$$

$$E_6 = 2.5 (10^4) \text{ ft/sec}$$

$$E_7 = 2.5 (10^4) \text{ ft/sec}$$

$$E_8 = 2.5 (10^4) \text{ ft/sec}$$

$$E_9 = 2.5 (10^4) \text{ ft/sec}$$

$$E_{10} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{11} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{12} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{13} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{14} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{15} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{16} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{17} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{18} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{19} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{20} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{21} = 2.5 (10^4) \text{ ft/sec}$$

$$E_{22} = 2.5 (10^4) \text{ ft/sec}$$

$$L = \frac{1}{3} AC - B^3 - \frac{1}{3} C = 0 - 0 + \frac{0.73}{3} = 0.143$$

$$L = \frac{1}{3} \left[h + (h^2 + L^2)^{1/2} \right] + \frac{1}{3} \left[- (h^2 + L^2)^{1/2} \right] =$$

$$\frac{1}{3} \left[0.004 + (0.0016 + 0.1019)^{1/2} \right] + \frac{1}{3} \left[0.004 - (0.0016 + 0.1019)^{1/2} \right] =$$

$$\frac{1}{3} [0.004 + 0.102] + \frac{1}{3} [0.004 - 0.102] =$$

$$0.102 + 0.077 = 0.176$$

$$u = \frac{C}{3} = 0 + 0.176 = 0.176$$

$$v = \frac{B}{3} + L = 0 + 0.176 = 0.176$$

$$W = 4u^3 + 3v - 12gl = 4(0.176)^3 + 3(0.143) - 12(0) =$$

$$= 4(0.031) + 0.429 = 0.124 + 0.429 = 0.573$$

Now, the four roots would be:-

$$d_1 = -A + u^{1/2} + (v + u^{1/2})^{1/2}$$

$$d_2 = -A - u^{1/2} + (v - u^{1/2})^{1/2}$$

$$d_3 = -A + u^{1/2} - (v + u^{1/2})^{1/2}$$

$$d_4 = -A - u^{1/2} - (v - u^{1/2})^{1/2}$$

and also,

$$d_1 = -C + 0.176^{1/2} + (0.176 + 0.573^{1/2})^{1/2} = 0.72 + (0.176 + 0.573)^{1/2}$$

$$= 0.72 + 0.8475 = 1.5675$$

Now, the four roots of the equation in the system of temperature - composition values would be,

$$d_1 = 0.9d = 0.4345$$

$$d_2 = 0.9d = 0.4345$$

$$d_3 = 0.9d = 0.4345$$

$$d_4 = 0.9d = 0.4345$$

and, thus the above value for composition, being (d) as follows

$$L = \frac{1}{3} \left[h + (h^2 + L^2)^{1/2} \right] + \frac{1}{3} \left[- (h^2 + L^2)^{1/2} \right] =$$

$$\frac{1}{3} [0.004 + 0.102] + \frac{1}{3} [0.004 - 0.102] =$$

$$= \frac{1}{2} [0.204 - \frac{1}{2} (0.121)] = [0.204 - 0.062]^{1/2} =$$

$$= [0.142] = 0.071$$

$$u = 0.071$$

$$v = 0.071$$

$$w = 7(0.071)^2 + 0.43 = 7(0.005) + 0.43 =$$

$$0.035 + 0.43 = 0.465$$

$$L_1 = 0.071^{1/2} + (0.071 + 0.15^{1/2})^{1/2} = 0.276 + (0.071 + 0.15)^{1/2}$$

$$= 0.276 + 0.471^{1/2} = 0.276 + 0.686 = 1.136$$

Checking,

$$L^3 - 0.8L - 0.43 = 0$$

$$1.66 - 0.8(1.136) - 0.43 = 0$$

$$1.66 - 0.9088 - 0.43 \approx 0$$

Again, noting

$$L = \frac{1}{2} [h + (h^2 + k^3)^{1/3}] + \frac{1}{2} [h - (h^2 + k^3)^{1/3}] =$$

$$\frac{1}{2} [0.204] + \frac{1}{2} [-0.121] = 0.102 - 0.062 = 0.04$$

$$u = 0.04$$

$$v = 0.04$$

$$w = 7(0.04)^2 + 0.43 = 7(0.0016) + 0.43 =$$

$$0.0112 + 0.43 = 0.4412$$

$$L_1 = 0.04^{1/2} + (0.04 + 0.156^{1/2})^{1/2} =$$

$$0.2 + (0.04 + 0.39)^{1/2} = 0.2 + 0.67^{1/2} =$$

$$0.2 + 0.825 = 1.025$$

Checking,

$$L^3 - 0.8L - 0.43 = 0$$

$$1.11 - 0.8(1.025) - 0.43 = 0$$

$$1.11 - 0.82 - 0.43 = 0$$

Since the design is to be within 0.1% of peak-to-peak accuracy, the design is 1% & 2% of peak-to-peak design factors checked and found to be correct.

is previously found the torque in accelerating the Green I.
 gear - 22.5 in-lb - Torque to "shock torque" to 6
 1.5 times the value, according to 58 of "Shifting From A
 Dynamic viewpoint",

$$22.5 \left[\frac{1.5}{1} \right]^{1/3} = 22.5 \left[\frac{22.5(1.5)}{22.5} \right]^{1/3} =$$

$$0.227 \left[\frac{33.75}{12} \right]^{1/3} = 0.227(1.415) = 0.321"$$

shaft would be required to yield not more than a 1 1/20 skin
 of shaft to the shaft, in line, say eg. 58 of "Shifting From
 A Dynamic viewpoint",

$$\frac{16 M_c}{\pi d^3} = 55$$

if again we set $M_c = 22.5$ "shock torque" and $d = 1.125$ " (as
 previously suggested)

$$\frac{16(1.5)(22.5)}{\pi (1.125)^3} = \frac{2.16(22.5)}{\pi (1.42)} = 121 \text{ #/in.}^2$$

would equal the shear stress due to torsion. The combined
 stress due to torsion and bending would then be:-

$$\left[15000^2 + 121^2 \right]^{1/2} = \left[22.25(10^6) + 141(10^4) \right]^{1/2} =$$

$$15000 \text{ #/in.}^2$$

and since, a 1 1/2" diameter shaft multiplies the principle of
 stress, the required diameter of shaft of reference speed is
 multiplied by the reference speed in ft/min by $\left[\frac{1.5}{1} \right]^{1/3}$ acco
 58 of "Shifting From A Dynamic viewpoint", line

$$K = \frac{32 I}{\pi^2} = \frac{(22.5(10^6))(\pi (1.125)^4)}{\pi^2 (1.42)} =$$

$$\frac{76(10^6)(\pi)(1.5)}{64(2700)}, \text{ } 0.227 \text{ in.}$$

then,

$$\left[\frac{1.5}{1} \right]^{1/2} = \left[\frac{22.5(1.5)}{22.5} \right]^{1/2} = \left[33.75 \right]^{1/2} = 914.$$

per

$$y = \frac{2}{\frac{2}{1.035} - 1}$$

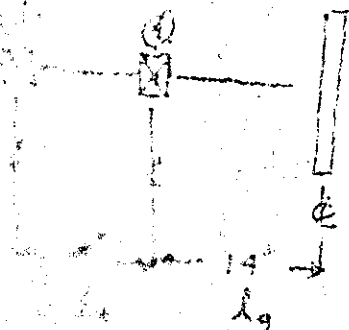
in per Eq. (10) of "Refining Iron & Steel" by Pratt,

$$y = \frac{2}{\left(\frac{2}{1.035}\right) - 1} = \frac{2}{2.15 - 1} = \frac{2}{1.15}$$

where $e = 0.14$, then

$$y = \frac{2.14}{1.15} = 1.861$$

in terms of the fraction of the bearing and bearing spacing - assume
bearing (center distance) between the two main bearings:



The computed shafting requirement, at
speed of 15,000 rpm, was 1.035". The
shaft which a shaft would withstand a
given stress would be:-

$$N = 52 = 5\pi \cdot 1^3 / 32 =$$

$$\frac{(1.035 - 1.135)^3}{32} = \frac{15000(\pi)(1.12)}{32}$$

1.50 in. - lbs.

1.50 in. = 1.50 in. Brg. (B)

1.50 in. = 1.50 in. Brg. (A)

The shafting stress would be
the highest computation.

237000 50 570.175 150 20" TOBE

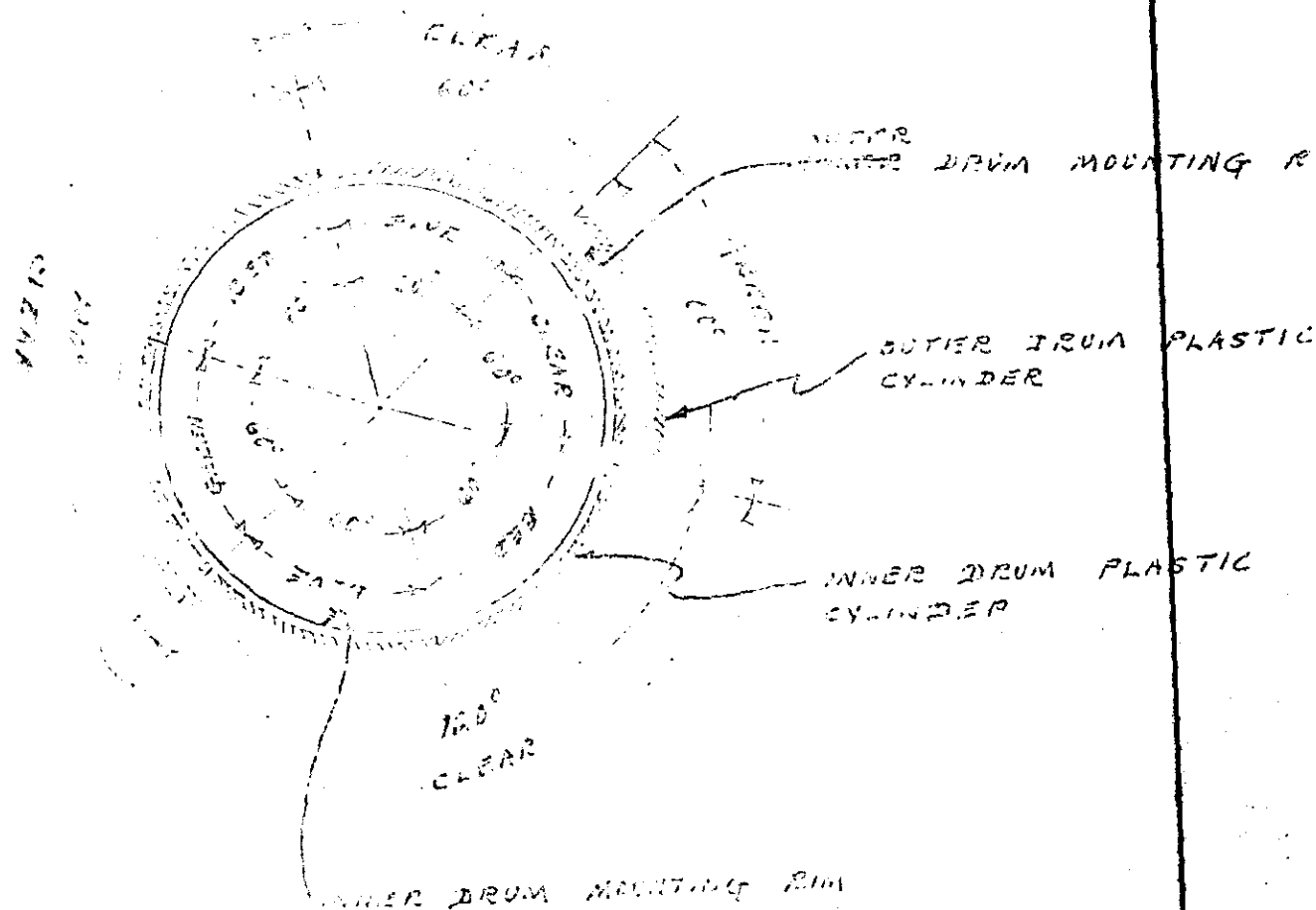
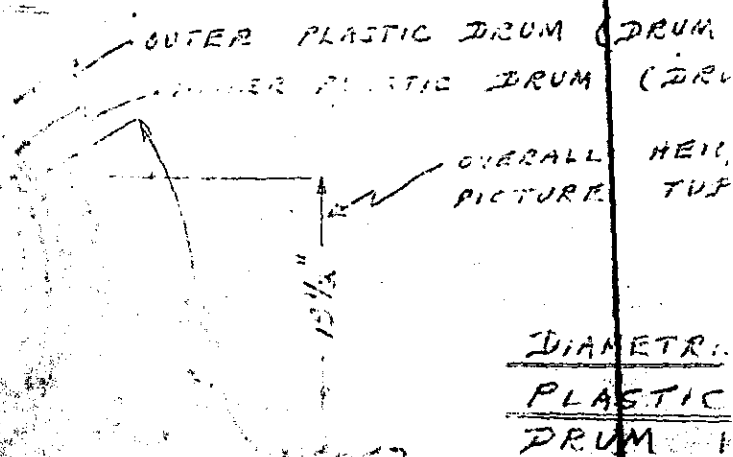


DIAGRAM SHOWING ARRANGEMENT
OF SECTORS ON DOUBLE-
ASSEMBLY



DIAMETER
PLASTIC
DRUM

574

FILTER SECTION "A"

GRIND ADJOINING EDGES OF SHEETS TO INDICATED BEVEL
LEAVE GRIND EDGES ROUGH, &
FILL IN WITH DENTAL POLY-
METHACRYLATE POLYMER PASTE

FILTER SECTION "B"

PREPARATION OF LONGI-
TUDINAL SEAMS BETWEEN FILTER
SECTIONS BOTH DRUMS

6-LUCITE 1/4"
BLOCKS

LUCITE
RG. 1/4"
3/4" LG.
TO DR.

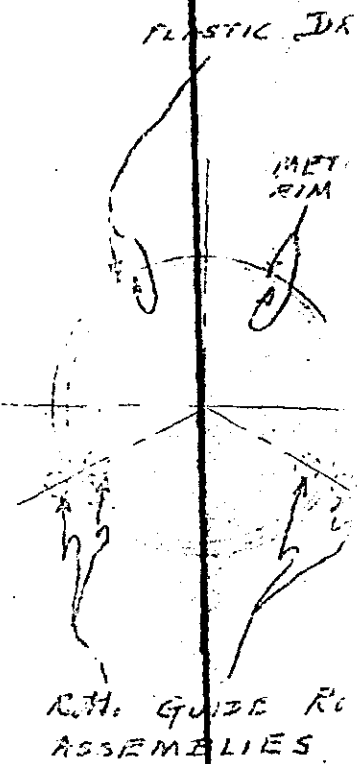
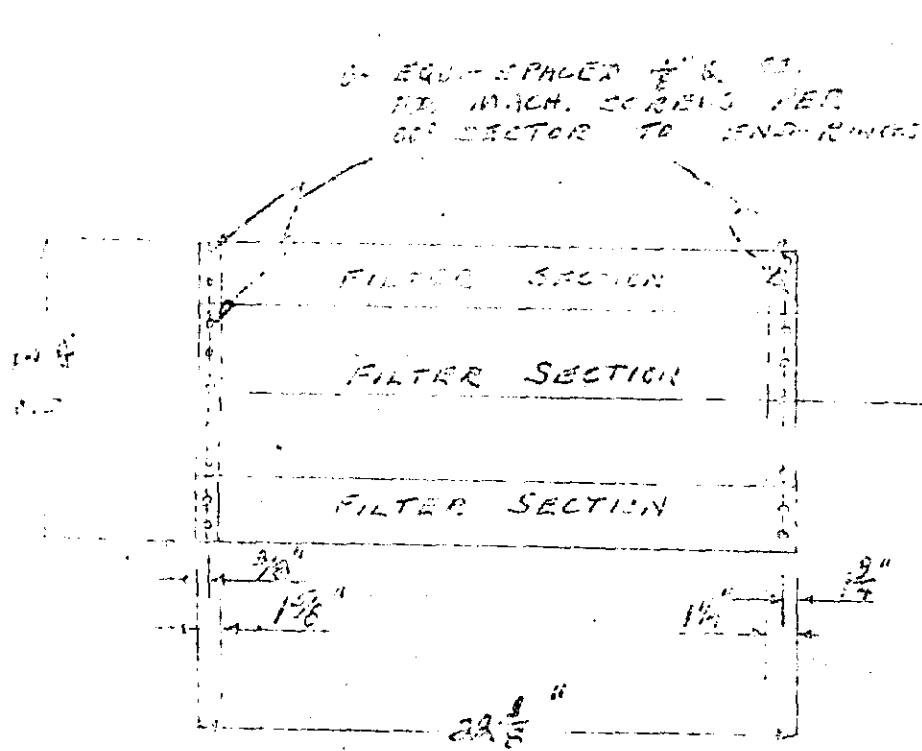
DRIVEN END

FILTER SECTION

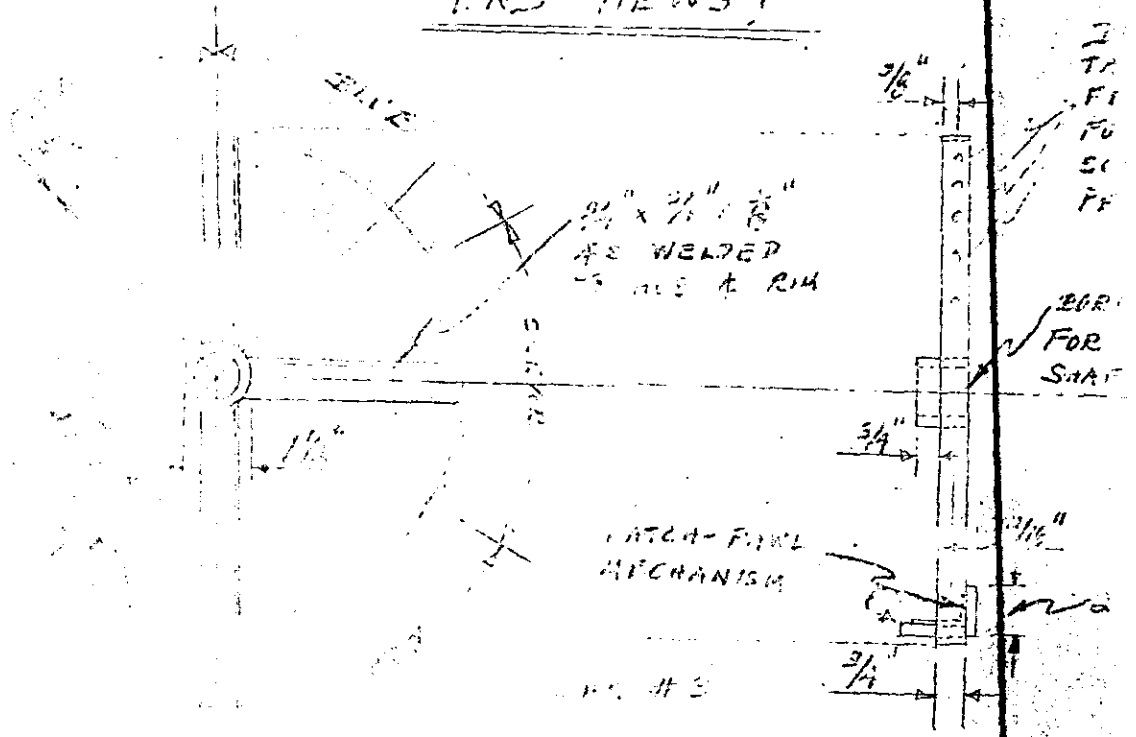
DRUM #2

ELEVATION

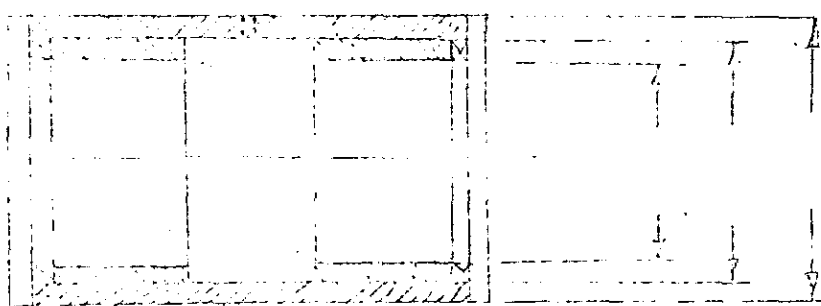
END



DRAW #1 (SIDE ELEVATION & R.H.
 END VIEWS)



DRAW #2 DRI
 END-PING



FD-141
(1-13-48)

BULKY EXHIBIT

Date received 7/9/51

ABRAHAM BROTHMAN

100-95068-1B
(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Ultimate disposition to be made of exhibit Retained

Estimated date of disposition To be decided at conclusion of case.

List of contents:

128. Two photostatic copies of thesis dated 7/6/51 together with two photostatic copies of drawing entitled "Switching Circuit for Double-drum Arrangement".

7A
100-95068-1B

SEARCHED INDEXED
SERIALIZED FILED
JUL 11 1951
FBI - NEW YORK

8/2

Carton Caps:-

Units (1) thru (4)
and computer shall replace the material
previously sent and recently misplaced. Unit (17)
in the delay count for the automatic switching and diagram
arrangement. Full explanation follows. Monthly
A

OBJECTIVES

The design proposed in this book is intended for use in the "color wheel" composition. The design is a preliminary sketch of the design. The design is a preliminary sketch of the design. The design is a preliminary sketch of the design.

- 1) generally, the design is a preliminary sketch of the design.
- 2) generally, the design is a preliminary sketch of the design.
- 3) generally, the design is a preliminary sketch of the design.

4) generally, the design is a preliminary sketch of the design.

FUNDAMENTAL PRINCIPLES OF THE PROJECTED DESIGN

A guiding principle of the projected design "color wheel" is that the design is a preliminary sketch of the design. The design is a preliminary sketch of the design. The design is a preliminary sketch of the design.

The design proposed in this book is a preliminary sketch of the design. The design is a preliminary sketch of the design. The design is a preliminary sketch of the design.

[illegible]

[illegible]

result obtained, the complete specimens of the two series for
 section series, covering the period 1880-1881, showing the
 proper adjustment of the two series for the same date, and the
 result of the two series, showing the result of the adjustment.

The other important factor in the treatment of the patient with the commonest source of low back pain is a proper means of sleeping. First a correct selection of the mattress with the proper height of the matter and correct position of the joints. The joint rotation of the properly matched beds and the mattress must be assured. When the patient is sleeping in a bed, and an area that for back and neck issues, both the mattress and the pillow and the intervention must be assured. Sleep, and stretching and a proper mattress positioning mechanism is indicated. The effect of the proper sleep includes joint and stretching, sleeping, and positioning exercises.

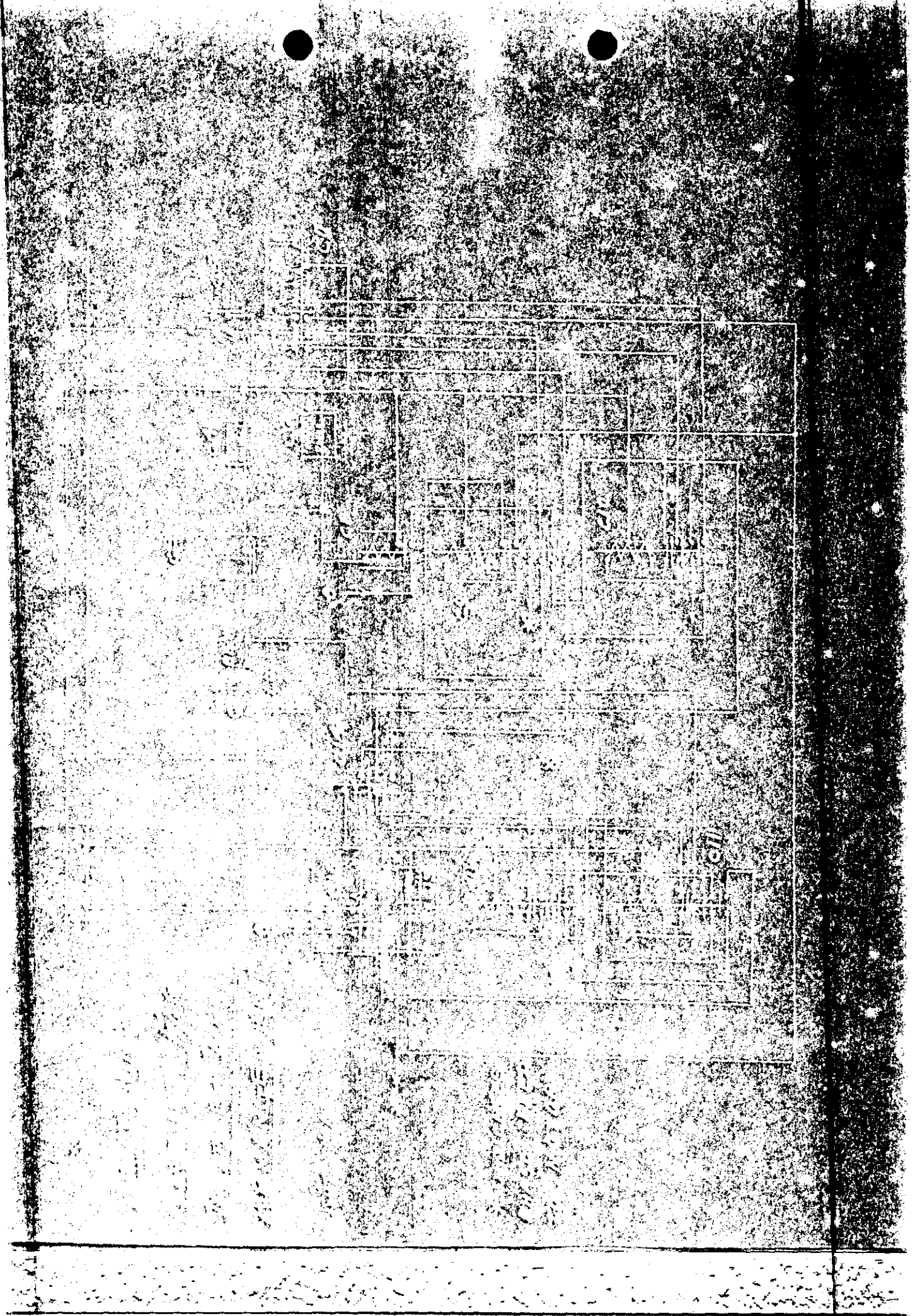
The sketching, signing and postmarking, -
which will be apt to require 15 min. to 1 hr. per specimen, -
as well as the following further details -

up the already stated amount (see also 100) in the
main column, and the already stated amount to the
other drum.

the design of the one fabric - ending up the other, then
with the end of inner fabric - starting from a proper
alignment of the two pieces for black and white weaving

... (see also [15], [16], and [17])
... (see [15] and [16]) which is
... (see [15] and [16]) shown as 60°
... (see [15] and [16]) be ejected from the
... (see [15] and [16]) the action of the ...-actuated plunger
... (see [15] and [16]) that all the ... held ... and the
... (see [15] and [16]) is rotated thru a 300°
... (see [15] and [16]) held stationary by
... (see [15] and [16]) plunger, and that the
... (see [15] and [16]) the ... in the ...
... (see [15] and [16]) that he engaged in
... (see [15] and [16]) the actual ... of
... (see [15] and [16])

(to be continued)



Carbon Copies:-

Slats (3) thru (4)

and comparison slats replace the material
previously sent and evidently misplaced. Alt. (17)
is the slip sheet for the automatic switching and diagram
arrangement. Full explanation follow Monkey
A

July 1951

OBJECTIVES

The design projected on Sketch Sheet (1) is the one intended for service in the "color wheel" component of the color wheel receiver. In preparing objectives have been kept in mind the laying down the preliminary design which this sketch is intended to embody -

- a) namely, the drawing which has been the intended color wheel receiver in the larger type of C.R. tubes;
- b) namely, the goal has been to make both black & white and color reception on the same C.R. tube;
- and
- c) finally, another goal has been to produce the objective set down in (1) and (2) without having to go to an entirely appearing cabinet design.

FUNDAMENTAL PRINCIPLES OF THE PROJECTED DESIGN

A guiding principle of the generally employed "color wheel" is that which holds that the diameter of the wheel must be the diameter of the given glass tube. The consideration, and the problem which it entails in both mechanical design and cabinet design, has at the bottom of the thought that the "color wheel" is limited as to the size of screen which it will accommodate on a practical basis.

The design projected on Sketch Sheet (1) is the one which relates to the use of a "color drum" (or "color reflector"). The screen or reflector in this case, then, is the means whereby the "color wheel" is introduced. By "color wheeling" is meant to make to the fact that the conventional "color wheel" must rotate about a center which

... actually more than
the viewed screen.]
... illustrate
... between the C.R.
... It will be
... to subtend
... the length of the color-
... that minimum distance
... and which provide
... the practical supporting and
... it is
... the length of the
... distributed
... of the viewed screen
... the color-
... that the drum
... the same C.R.
... consisting of two concentric
... the two shells is
... of the double-drum
... color viewing on the
... of 5 properly-segmented
... of the drum are
... of 5 equal-
... filter-section,
... the inner filter-section of the outer-drum complete the
... established by the inner drum filter-
... section.

See the top
view on the
#1

(1) The two drums be capable of having their relative positions altered so that, for color-viewing, the one filter-section of the outer drum properly complements the color-sequence established by the 5 filter sections of the inner drum, - while, for black and white viewing, the filter-section of the inner drum is complemented by any of the clear pictures of the outer drum.

Such an ability, the complementary positioning of the two drums for color-viewing involves the joint rotating of both drums; while the proper alignment of the two drums for black-and-white reception is based on both drums remaining stationary.

It thus appears in (a), (b), (c) and (d) above, together with the remarks which follow (a), means that a positive means of aligning the 5 color-sections of the inner wheel with the 1 color-section of the outer wheel must be provided, means that the joint rotation of the properly-matched color-sections of both wheels must be insured when color-viewing is desired, and, means that, for black-and-white viewing, both the respective positioning of the inner, and the outer drums should be insured. Obviously, sliding and a proper complementary positioning mechanism is indicated. Therefore, the proposed device involves first, a rotating, aligning, and positioning mechanism.

The rotating, aligning, and positioning mechanism, - which will be referred to as the C or P mechanism, - is illustrated in the following fashion:

- a) The outer drum is mounted on a shaft which is the inner drum, and the relatively inner drum is the outer drum.
- b) The alignment of the 5 color-sections of the outer drum with the 1 color-section of the inner drum - readily from a proper alignment of the two drums - is insured by the viewing

ing (see also [14], [15], [16], [17], and [18])
 that the latch-pawl (shown in [15] and [16]) which is
 located in the grab (shown in [17] and [18]) shown as 60°
 off the vertical centerline on [14] be ejected from the
 grab-slot by the action of the solenoid-actuated plunger
 (shown in [15]). That the latch-pawl and the
 inner drum of which it is a member be rotated thru a 300°
 arc of travel while the outer drum is held stationary by
 the continuously-engaged solenoid-actuated plunger, and that the
 latch-pawl member of the outer drum then be engaged in
 the grab-slot of the grab shown on the vertical centerline of
 [14].

(To be continued)

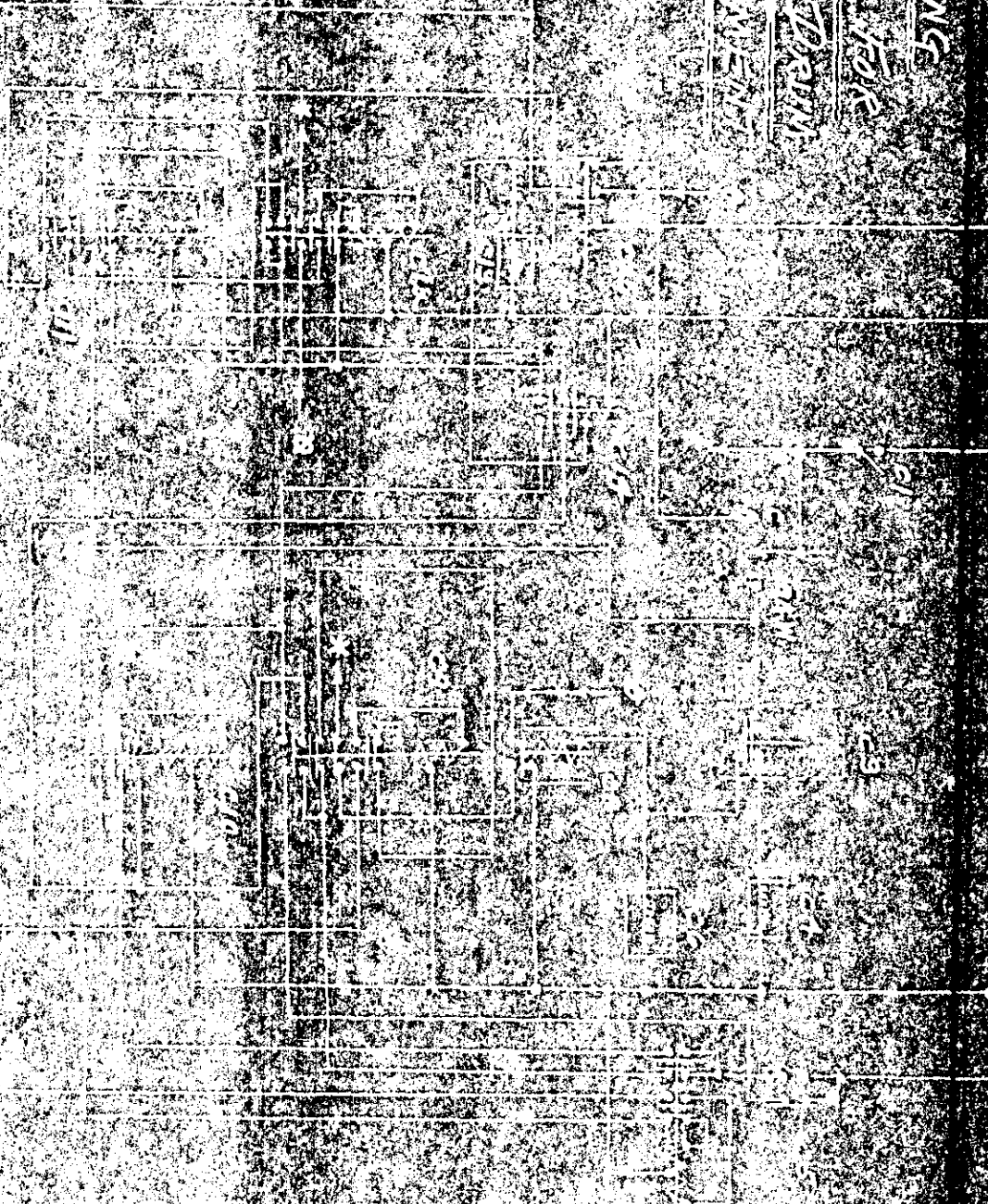
SWITCHING

EXHIBIT 100K

MOBILE 100K

EXHIBIT 100K

EXHIBIT 100K



BULKY EXHIBIT

Date received 7/27/51

AD RAHMAN BROTHMAN

100-95068-1B
(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained USA-SDNY

Address _____

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

127. Photostatic copy of decision of Circuit Court of appeals in case entitled US v BROTHMAN & MOSKOWITZ.

75
100-95068-1B
8
GME

UNITED STATES COURT OF APPEALS

FOR THE SECOND CIRCUIT

No. 290—October Term, 1950.

(Argued June 14, 1951)

Decided July 26, 1951.)

Docket No. 22039

UNITED STATES OF AMERICA,

Appellee.

—v.—

ABRAHAM BROTHMAN and MIRIAM MOSKOWITZ,

Appellants.

Before:

SWAN, Chief Judge, AUGUSTUS N. HAND and L. HAND,

Circuit Judges.

Appeal from the United States District Court for the
Southern District of New York.

From judgments of conviction and sentence after trial
upon an indictment charging both defendants with con-
spiracy to obstruct justice and defendant Brothman alone
with the substantive offense, the defendants have appealed.
Affirmed on conspiracy count; reversed on substantive count.

JOHN McKIM MINTON, *Attorney for appellant
Brothman*; William F. McNulty, *in counsel*.
WILLIAM L. MESSING, *Attorney for appellant
Moskowitz*.

IRVING H. SAYEOL, *United States Attorney, for
appellee*; Bruno Schachner, Roy M. Cohn,
John M. Foley and Stanley D. Robinson,
*Assistant United States Attorneys, of
counsel*.

SWAN, *Chief Judge*:

These are appeals from judgments of conviction and sentence upon an indictment which charged both appellants with the crime of conspiracy, 18 U. S. C. § 383 (1946 ed.), and Brothman alone with the substantive offense of endeavoring to persuade a witness to give false testimony before a federal grand jury, 18 U. S. C. § 241 (1946 ed.). Brothman was sentenced to consecutive terms of 2 and 5 years and fines of \$10,000 and \$5,000 on the respective counts. Moskowitz was sentenced to 2 years' imprisonment and fined \$10,000. Brothman's appeal raises a single issue, namely, failure to prove venue of the substantive offense. The appeal of Moskowitz challenges the sufficiency of the evidence to prove her participation in the conspiracy, and asserts prejudicial error in the prosecution's summation.

We address ourselves first to the conspiracy count. In the summer of 1941 a federal grand jury in and for the southern district of New York was conducting an investigation of possible violations of the espionage laws. Brothman and one Gold were summoned to appear as witnesses before this grand jury. The conspiracy count charged that both

appellants together with Gold, who was named as a conspirator but not as a defendant, agreed that Brothman should give false testimony before the grand jury, should inform Gold thereof, and Gold should likewise give false testimony consonant with Brothman's. The case against the appellants was made largely by the testimony of Gold. Moskowitz does not question the sufficiency of the evidence to prove that such a conspiracy existed between Brothman and Gold, but contends that she was not shown to have been a party to it. An examination of the record convinces us beyond doubt that the contention is groundless. Without discussing the evidence in detail it will suffice to refer to a few incidents which indicate that she repeatedly assisted in making up the false stories of the two main actors. After Gold had been interviewed by agents of the Federal Bureau of Investigation, he recounted in the presence of Brothman and Moskowitz what he had told the agents, and Brothman remarked that he had made "a very fine choice of a story." The inference that the story was false must have been obvious to Moskowitz. She was also present when Gold refused to tell Brothman about his espionage activities because Brothman "was already deeply enough involved." When Brothman was considering testifying before the grand jury to a story different from that he had originally told the F. B. I. agents Moskowitz expressed concern and told Gold she was going to tell Brothman to try to stick to the original story; and she later told Gold that she and attorney Needleman persuaded Brothman to do so. Finally, on the night before Gold was to testify, Moskowitz said that she wished to go home early "so that Al and Brothman and I would have plenty of time to match our stories before my appearance before the grand jury the next morning."

The next contention of appellant Moskowitz is that she was prejudiced by repeated statements in the prosecutor's

summation that the defense had failed to contradict the government's testimony. It is conceded that as a general rule a reference to the testimony for the prosecution as uncontradicted is not an indirect comment on the defendant's failure to testify, but the appellant contends that an exception exists where the only persons who could contradict the testimony are the defendants themselves. Assuming *arguendo* that such an exception should be recognized, we do not think that the appellant's case falls within it. The prosecutor's comments were general and made without express reference to Moskowitz. It is possible to explain them as covering occurrences as to which contradiction could have come from others than this appellant. For example, the comment to which objection was first interposed was the following: "The truth of the testimony offered here by Miss Bentley, Gold and others is conclusively established by the failure of the defense to produce one solitary word contradicting any of this testimony." In overruling the objection the court stated: "I will deal with that later properly myself." And in his charge the judge instructed the jury that they may not "infer guilt nor even draw a single unfavorable inference against the defendants because they did not take the stand." We think this was all that was required.²

We turn now to Brothman's appeal. The court's charge limited the substantive crime to endeavoring to influence Gold to give false testimony, and the jury was told that the Government did not have to prove the success of the

² See *London v. United States*, 3 Cir., 296 F. 101; *Barnes v. United States*, 8 Cir., 8 F. 2d 832.

³ See *Leffowicz v. United States*, 2 Cir., 273 F. 681, 683, cert. den. 257 U. S. 637; *United States v. Shapiro*, 2 Cir., 103 F. 2d 775, 776; *United States v. Di Carlo*, 3 Cir., 64 F. 2d 15, 17; *United States v. De Vito*, 2 Cir., 52 F. 2d 26, 30, cert. den. 284 U. S. 678; *Boehm v. United States*, 8 Cir., 123 F. 2d 791, 810.

endeavor. Concededly all of Brothman's "endeavors" to influence Gold's testimony took place in the eastern district of New York, although Gold's testimony was given in the southern district. The contention on appeal is failure of proof of venue. At the close of the prosecutor's case, Brothman moved for a directed verdict on count 2 on the ground that the evidence was insufficient. This motion was renewed at the end of the entire case. The Government's only answer to the appellant's argument is that Brothman waived his constitutional privilege to be tried where the crime was committed by going to trial in the southern district without objection. Where the indictment discloses lack of venue, going to trial without objection to venue is a waiver. *United States v. Jones*, 2 Cir., 162 F. 2d 72, 73. There is a dictum in *United States v. Michelson*, 2 Cir., 165 F. 2d 732, 734, aff'd, 335 U.S. 469, that the same result may follow if the defendant is warned of the defect during the course of the trial. In the case at bar Brothman could not know that venue would not be proved until the prosecutor's evidence was closed; he then moved for a directed verdict. We may assume *arguendo* that he argued the motion and said nothing about failure to prove venue; he might be held to have waived the defect. But the motion was denied without argument being heard. In *United States v. Jones*, 7 Cir., 174 F. 2d 746, Judge Minton (now Mr. Justice Minton), speaking for the court, held that a motion for acquittal made at the conclusion of all the evidence properly raised the question of venue in the court below. Such a motion need not specify the grounds therefor. We agree with the Seventh Circuit decision. Accordingly Brothman's conviction on count 2 must be reversed. The conviction of both appellants on the conspiracy count is affirmed.

RECORD PRESS—12-16-48 William St.—New York 38, N. Y.—REctor 2-2638
35-727-512 □ USA-2362

BULKY EXHIBIT

Date received 7/20/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

128. Photostatic copy of paper entitled "Drawing #1" together with envelope addressed to N. GABORLULT, Pres., Techniflex Corp, Port Jervis, NY
129. Photostatic copy of paper entitled "Drawing #2" together with envelope addressed to OSCAR THALER, 3107 Bedford Avenue, Brooklyn, NY.
130. Photostatic copy of drawing showing various views and positions of a color television tube.

76

100-95068-1B

SEARCHED	INDEXED
SERIALIZED	FILED
AUG 2 1951	
FBI - NEW YORK	

[Signature]

Ms. A. 9. 2. 1. 1. 1.

Ms. A. 9. 2. 1. 1. 1.

Ms. A. 9. 2. 1. 1. 1.

Ms. A. 9. 2. 1. 1. 1.

BULKY EXHIBIT

Date received 7/30/51

ABRAHAM BROTHMAN

100-95063-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal House of Detention

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 131. Photostatic copy of paper entitled "Drawing #3."
- 132. Photostatic copy of paper entitled "Drawing #4."
- 133. Photostatic copy of paper entitled "Drawing #5."
- 134. Photostatic copy of paper entitled "The Mirroscope for 20" Rectangular C R Tube.
- 135. Photostatic copy of envelope addressed to N. GABRIELT.

100-95063-1B

SEARCHED	INDEXED
SERIALIZED	FILED
AUG 2 1951	
FBI NEW YORK	

[Handwritten signature]

Dist. 1 - The broken up component of the
sally, including assembly

Dist. 2A - Set. Broken up of bush assembly

Dist. 2B - Pin Section of bush

Dist. 2C - Bush - part of bush

Yard of pin to alternate bush

Dist. 2D - Section of bush holder
+ bush fragment of pin to alternate bush
with the bush and pin

Dist. 2H - Outer Pin (L.H.)

Dist. 2M - Pin (L.H.)

Dist. 2P - Pin

Dist. 2V - Pin

Dist. 2K - Pin

Dist. 2N - Pin

1. Dist. 2 - Pin

2. Dist. 2 (L.H.) - Pin

3. Dist. 2 - Pin

4. Dist. 2 - Pin

5. Dist. 2 - Pin

6. Dist. 2 - Pin

7. Dist. 2 - Pin

8. Dist. 2 - Pin

9. Dist. 2 - Pin

10. Dist. 2 - Pin

11. Dist. 2 - Pin

12. Dist. 2 - Pin

- 8. Contact zone formed from 1/2" wide soft
mudstone with elongated dark brown to grey
sandy streaks 3 1/2' apart
- 9. 6' long Allen shale unit seen
from same horizon as shaft
- 10. 1' thick yellow (possibly more or less with
mudstone) and black (possibly granular) pit
of shale from 10' to 12' thick pit
- 11. 1' thick yellow shale with 2' and 2'
sandy streaks
- 12. 1' thick yellow shale with 2' and 2'
sandy streaks
- 13. 1' thick yellow shale with 2' and 2'
sandy streaks
- 14. 1' thick yellow shale with 2' and 2'
sandy streaks
- 15. 1' thick yellow shale with 2' and 2'
sandy streaks
- 16. 1' thick yellow shale with 2' and 2'
sandy streaks
- 17. 1' thick yellow shale with 2' and 2'
sandy streaks
- 18. 1' thick yellow shale with 2' and 2'
sandy streaks
- 19. 1' thick yellow shale with 2' and 2'
sandy streaks
- 20. 1' thick yellow shale with 2' and 2'
sandy streaks
- 21. 1' thick yellow shale with 2' and 2'
sandy streaks
- 22. 1' thick yellow shale with 2' and 2'
sandy streaks
- 23. 1' thick yellow shale with 2' and 2'
sandy streaks
- 24. 1' thick yellow shale with 2' and 2'
sandy streaks
- 25. 1' thick yellow shale with 2' and 2'
sandy streaks

1. See Item "E3"
2. $\frac{3}{4}" \times \frac{3}{8}" \times \frac{1}{8}"$ aluminum angle spacers
3. $\frac{1}{4}" \times \frac{1}{4}" \times \frac{1}{16}"$ aluminum angle rivets
4. Indicates the positions of the 6 equispaced Kennedy plates on the assembled unit.
5. Aluminum Nut (machine from 4" O.D. & $1\frac{1}{2}"$ I.D. tube stock, or from a 4" mild steel pipe)
6. 6 equispaced (on a $3\frac{1}{2}"$ O.D.) holes, drilled and tapped for $\frac{1}{8}"$ head machine screws $\frac{1}{8}"$ lg.
7. 6 - $\frac{1}{8}"$ round head machine screws, $\frac{1}{8}"$ lg.
8. 1000 Series, $1\frac{1}{2}"$ shaft size, ball bearing (6) (running fit into housing)
9. Aluminum cover plate (though indicated as a $\frac{1}{8}"$ thick plate, a $\frac{1}{16}"$ thick plate would more than suffice)
10. ditto (3)
11. 2 - $\frac{1}{8}"$ diameter $\times \frac{5}{16}"$ lg. cap screws & nuts
12. $\frac{1}{4}" \times \frac{1}{4}" \times \frac{1}{16}"$ aluminum angle end ring (R.H.) - ring to have $25\frac{1}{2}"$ O.D.
13. roller support member for R.H. end of unit driven, - 6 equispaced units, - see Dwg. #1
14. Outer Drive End Ring (R.H. side)
15. Split V-belt Block (see Dwg. #3)
16. Mild steel anchor member for stationary shaft "fixed support" point (see Dwg. #5)
17. S.A.E. 1020 standard steel tube stock. Stationary shaft machined as per Dwg. #5
18. Roller shaft component of C.R. Tube Support Assembly, - of standard S.A.E. 1020 tube stock

19. $\frac{1}{2}'' \times \frac{1}{2}'' \times 16''$ by attaching anchor member (16) to hollow shaft (17)
20. Tugue member of anchor (see DWG. # 5)
21. $\frac{1}{2}'' \times \frac{1}{2}'' \times \frac{3}{4}''$ by cap screws and bolts - 2 ang.
22. Iron anchor plate to which (16) is tied (see DWG. # 5)
23. $1 \times 1 \times \frac{1}{2}''$ angle iron to which (22) is welded (see DWG. # 5)
24. $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{2}''$ angle iron leg of R.H. and A-Frame (see DWG. # 5 for details and true relation of A-frame members to one another and to drum)
25. Koston Riv. Works 3-2226-16 Plain Cylindrical Root-Ring bearings, one each and as indicated, machined to friction fit with interior of (17) and exterior of (26)
26. Outline of tube, indicating clearance of Outer Drive and - ring R.H. spoke from tube
27. $\frac{1}{2}'' \times \frac{1}{2}'' \times \frac{1}{2}''$ by attaching Bracket to Hollow Shaft Member of C.R. Tube Support Assembly
28. $2 \times \frac{1}{2}'' \times \frac{3}{4}''$ by cap screws and bolts
29. $\frac{1}{2}''$ Mild Steel plate, R-inforced as indicated in Tube Support (Note Detail)
30. $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{2}''$ angle iron stiffener, welded down length of the underside of (29)
31. $\frac{1}{2}'' \times \frac{3}{4}'' \times \frac{1}{2}''$ angle iron stiffener, running roughly half-way across the underside of support plate (29) at each of the two points of support by Bracket
32. $1 \times 1 \times \frac{1}{2}''$ horizontal member of bracket
33. Bracket (see Bracket Detail)
34. Pressed Steel Clip to which Forming and Deflection Cords Bracket is attached

35. $1" \times 1" \times \frac{1}{8}"$ vertical member of Bracket
36. $\frac{3}{8}" \times \frac{7}{8}" \times \frac{1}{8}"$ stiffener across width of underside of plate, welded to plate and to (30) as indicated in Front-End Elevation View of Tube Support Detail
37. In (31) and (35)
38. Angle of Tube Strap Member to Support Plate
39. Cover Area Tube Strap Member. (See Front-End Elevation View of Tube Support Plate)
40. Hub of bracket, of $2\frac{3}{4}"$ O.D. $\times 1\frac{1}{2}"$ I.D. S.A.E. 1020 standard steel tube stock
41. Keyway for $\frac{1}{2}" \times \frac{1}{8}" \times 1\frac{1}{2}"$ key as per (37)
42. $1" \times 1" \times \frac{1}{8}"$ each arm of bracket
43. $\frac{1}{8}"$ thick stiffener plate welded to angle arms & hub
44. collapsed soft rubber tubing forming soft shoulder for bottom side of C.R. Tube
45. Plywood for following contour of underside of tube
46. rubber lining for tube for (39)
47. flange (39)
48. Nut for standard carriage Bolt and wing-nut fastening between (39) and leg member of strap

1. Shoulder bearing against inner race of ball bearing in Outer Drive R.H. End Ring hub [NOTE: Shaft, at its reduced diameter, to be a running fit into inner race]
2. Keyway for $\frac{1}{2}$ " x $\frac{3}{8}$ " key fixing Stationary Shaft against rotation in pillow block [NOTE: Keyway to extend for $4\frac{1}{2}$ " in length from indicated R.H. end of shaft]
3. Drill and Tap for $\frac{3}{8}$ " set screw which threads into Stationary Shaft. Set of set screw not tapped hole to be "free fit". [NOTE: Lower $\frac{1}{4}$ " of set screw to be machined down to $\frac{1}{8}$ " and to fit snugly into corresponding hole (D) in Hollow Shaft. Shoulder on set screw because of machined down end to seat tightly against inner Hollow Shaft]
4. Keyway for $\frac{1}{2}$ " x $\frac{3}{8}$ " x $1\frac{1}{2}$ " key between Stationary Shaft and Stationary Shaft Anchor
5. Set screw, Allen Bolts $\frac{7}{16}$ " x $\frac{1}{2}$ " of description in (D) rather than as indicated
6. Keyway in Stationary Shaft Anchor matching (D)
7. End view of Anchor to have a snug fit into Stationary Shaft
8. Square Shoulder Anchor
9. Drill for $\frac{1}{4}$ " x $\frac{1}{4}$ " hole passing thru
10. $\frac{1}{4}$ " x $\frac{1}{4}$ " drill for set screw going as indicated in Item # 3 above
11. Keyway for $\frac{1}{2}$ " x $\frac{3}{8}$ " x $1\frac{1}{2}$ " key between Bracket Hub and Hollow Shaft
12. Pin Assembly
13. Split Pillow Block support for R.H. End of Drive Assembly
14. $1\frac{1}{2}$ " x $1\frac{1}{2}$ " x $\frac{1}{2}$ " top member of A-frame (the studs "LB" and "LC")
15. ditto (C)

16. Frame legs to weld (1) is tied
17. 1" x 1" x 1/8" horizontal member to weld (1) is welded (see items "L3" and "L4")
18. Mount Plate (see item "L4") [NOTE: Actually ^{each} gusset plate will be 2 triangles as required by item "L3"] - 1/8" R
19. Mount Plate (see items "L4" and "L3") - 1/8" R
20. 1" x 1" x 1/8" horizontal member serving to stiffen and tie together two ends of uprights, and as a base to which the counting down force detection element is attached
21. 24" x 1/8" x 1/8" x 1/8" iron uprights
22. End Pad (see Detail "F")
23. T.V. Clamps to be tied to uprights by way of clamps
24. Mount Plate (see item "L4")
25. Mount Plate (see item "L4")
26. Balls for 1/8" x 1/8" bolts

MR. N. GABORIAULT 7075

TECHNIFLEX CORP

PORT JERVIS, NEW YORK

PERSONAL

BULKY EXHIBIT

Date received 8/3/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, N C

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 136. One photostatic copy of paper entitled "Drawing # 6.
- 137. One photostatic copy of paper entitled "Drawing #7.
- 138. One photostatic copy of drawing entitled "The Miriascope for a 20" Rectangular C R Tube Drawing #6.
- 139 One photostatic copy of drawing entitled " The Miriascope for a 20" Rectangular C R Tube Drawing #7.

100-95068-1B
SEARCHED INDEXED
SERIALIZED FILED
AUG 22 1951
FBI - NEW YORK

1. B. 1020 x 1020 x 1020 I.D. Mount Bearing (Belt-Drive) - [NOTE: See "The Belt Drive Unit", ④, which is an identical Mount Bearing as shown in order that the basic construction of the drive bearing is identical.]
2. 1/2" x 1/2" x 1/2" steel shaft, welded as indicated to one leg of the support
3. 1/2" x 1/2" x 1/2" steel shaft
4. 1/2" x 1/2" x 1/2" steel shaft for rear bracket to which roller is anchored
5. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
6. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
7. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
8. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
9. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
10. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
11. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
12. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
13. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
14. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
15. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
16. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
17. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces
18. 1/2" x 1/2" x 1/2" steel shaft for roller & belt - 2 pieces

19. $\frac{1}{2}$ " mild steel flange, welded to inside of one leg of (3) and to baseplate. [NOTE:- (3) should be similarly stiffened in the other direction as well.]
20. Keyway for $\frac{1}{2}$ " x $\frac{1}{2}$ " x $1\frac{1}{2}$ " by key between Main Drive Shaft and the hub of the Inner Drum Driven-End End Ring
21. Allen Headed Set Screw used to fix commutator holder into end of Main Drive Shaft. [NOTE:- With the set screw engaged, the top of set screw is beneath the root of the indicated ^{shaft} threads. Threading of the shaft is to be done after the hole for the set screw has been drilled and tapped.]
22. 16 threads per inch, medium fit - to - locking up nut. [NOTE: Locking up nut to be driven with a lock-washer against the inner race of the $1\frac{1}{2}$ " shaft-size bearing.]
23. Keyway for $\frac{1}{2}$ " x $\frac{1}{2}$ " x $\frac{3}{8}$ " by key between gear (2) and Main Drive Shaft
24. Commutator & brush assembly for relay circuit
25. $1\frac{1}{2}$ " shaft size ball bearing pillow block
26. Drive motor (further information, next communication)
27. Output shaft of drive motor, here taken to be $\frac{1}{2}$ " x $2\frac{1}{2}$ "
28. Helical gear (specified on Eng. # 1) on output shaft of motor
29. " " " " " " " " Main Drive Shaft
30. $1\frac{3}{4}$ " shaft size ball bearing pillow block
31. $\frac{1}{2}$ " x $2\frac{1}{2}$ " cap screw threaded into baseplate (43)
32. ~~$\frac{1}{2}$ " mild steel flange~~ outboard bearing for output shaft of Motor Drive
33. $1\frac{1}{2}$ " x $2\frac{1}{2}$ " cap screw and bolt to baseplate (42)
34. spokes of Outer Drum Driven-End End Ring

35. Spokes of Inner Drum Driven End End Ring
36. Hub " " " " " " " "
37. $\frac{1}{2}$ " x $\frac{1}{2}$ " x $\frac{1}{2}$ " lg. key between Main Drive Shaft and Inner
Drum Driven End End Ring
38. $1\frac{1}{2}$ " x $1\frac{1}{2}$ " x $\frac{1}{2}$ " structural steel top horizontal member of L.H. A-frame
39. $\frac{3}{4}$ " x $\frac{3}{4}$ " x $\frac{1}{2}$ " " " " " " " " "
40. Horizontal member of A-frame lower base for baseplate (42)
41. " " " " " " " " " "
42. $\frac{1}{2}$ " A mild steel baseplate for L.H. end assembly
43. Template for $1\frac{1}{2}$ " shaft size pulley block
44. Cap screw and Nut for connecting motor to baseplate (47) - 1 sq.
45. $\frac{1}{2}$ " x $\frac{1}{2}$ " x $\frac{1}{2}$ " structural steel & stiffener for baseplate (47) - 2 sq.
46. $\frac{1}{2}$ " A mild steel gusset lying (47) to baseplate (42)
47. $\frac{1}{2}$ " A mild steel baseplate for Drive Motor
48. $\frac{1}{2}$ " x $\frac{1}{2}$ " cap screw threading into baseplate (47) to tie (48) to (43)
49. $\frac{1}{2}$ " x $\frac{1}{2}$ " x $\frac{1}{2}$ " lg. cap screw and Nut lying baseplate (42) to knu-
base (40)

22. $\frac{1}{8}$ " R mild steel baseplate for attachment of Brake Assembly (11)
23. $\frac{1}{8}$ " R " " stiffener plates for (23)
24. 1" x 1" x $\frac{1}{8}$ " structural steel & as horizontal member of L. H. A-frame
25. $\frac{1}{8}$ " R mild steel gussets - 2 req., running between (19) and (24)
26. foot plate - see details of R. H. A-frame
27. $\frac{1}{8}$ " R mild steel gusset plate running between bottom plate of Position "3" fixture and one leg of (19)
28. $\frac{1}{8}$ " R mild steel vertical baseplate of Position "3" fixture
29. $\frac{1}{8}$ " R mild steel gusset between bottom plate and (28) of Position "3" fixture
30. front gusset plate, identical with (29)
- * NOTE - The true shape of (27) and the true position of (29) with respect to the main axis of (19) are to be such as to satisfy the orientation axis indicated for the fixture in Item "F.A."
- * 31. $\frac{1}{8}$ " R mild steel ^{topside} gusset running between (33) and one leg of (19)
- * 32. $\frac{1}{8}$ " R mild steel bottomside gusset running between (33) and the other leg of (19)
33. bottom plate member of Position "A" attachment fixture
34. front gusset running between (33) and (35)
35. vertical baseplate of Position "A" attachment fixture
- * NOTE - The true shape of (31) and (32) are to be such as to satisfy the orientation axis indicated for the fixture in Item "F.A."

BULKY EXHIBIT

Date received 7/30/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit Incabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

140. Two photostatic copies of drawing entitled "The Miriascope for a 20" Rectangular C.R. Tube, Drawings 4 & 5" together with photostatic copy addressed to N. GABORIAULT, Pres, Techniflex Corp, Port Jervis, NY

100-95068-1B

SEARCHED	INDEXED
SERIALIZED	FILED
AUG 23 1951	
FBI - NEW YORK	

79

BULKY EXHIBIT

Date received 8/13/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit retain

List of contents:

- 141. Two photostatic copies of letter dated 8/10/51 to J.F. & S.E.A.
- 142. Two photostatic copies of paper entitled "Errata, Addenda, & Comments.
- 143. Two photostatic copies of pages numbered 112-117.
- 144. Two photostatic copies of paper entitled Drawing #8 together with drawing.
- 145. Two photostatic copies of paper entitled Drawing #9 together with drawing.

100-95068-1B

SEARCHED INDEXED
SERIALIZED FILED
AUG 14 1951
FBI - NEW YORK

80

8/10/51

To: J.F.
S.E.A.

Re: Synchronizing Arrangements
for C.B.S. color-TV

Today
A note which I received from Name today indicated that perhaps my message relative to the construction of a special motor for C.B.S. color-wheel or color-drive units had been misconstrued. I may have talked with Jack, he conveyed to me the thought that S.E.A. was thinking in terms of a special combination of a synchronous and an induction motor (a specially constructed motor) which would "lock" to the vertical scanning pulse via any of a number of mechanical linkages. In the message I gave Name, I expressed my opinion against such a project both from a technical and from a commercial point of view. I am inclined towards servo-type link between the vertical pulse and the Drive Motor, but, as differentials have been used, I have seen that C.B.S. does, I believe that the driving or forcing section of the servo should operate something like a variable in its operating characteristics than a controllable reluctance. The thought on which I wanted a decision was whether to take the time now to design a servo of the type I have in mind, or whether I should leave this till later and proceed with Jack's orders with the design of a larger size (1 1/2" or 3" motor-wheel - say a color-wheel for a 14" tube) immediately. I believe that the servo which I have in mind, as well as being an eddy current (a very light eddy current) is superior to a standard motor would be especially suited to the device I have designed.

Please discuss this with S.E.A. and let me have your views. I was informed today that drawings 6, 7, 8, & 9 sent Friday of last week Wednesday of this week in two equal shipments have not arrived. Retained on these drawings is most essential to the development of the device. Please see that the finished device, as well as the drawings and working revisions of the original designs are contained on these

8/10/51

To: J. F.
S. E. A.

RE: Synchronizing Arrangements
for C.B.S. color-TV

Today

A note which I received from Harrie today indicated that perhaps my message relative to the construction of a special motor for CBS color-wheel or color-drum drive had been misconstrued. In my last talk with Jack, he conveyed to me the thought that S. E. was thinking in terms of a special combination of a synchronous and an induction motor (a specially constructed motor) which would "dead lock" to the vertical scanning pulse via any of a number of drive servo linkages. In the message I gave Harrie, I expressed my opinion against such a project both from a technical and from a commercial point-of-view. I am inclined towards servo-type link between the vertical pulse and the Drive Motor, but, as differentiated from the servo I have seen that CBS uses, I believe that the driving or guiding section of the servo should operate something a bit more stable in its operating characteristics than a saturable reactor. The thought on which I wanted a decision was whether I should take the time now to design a servo of the type I have in mind, or whether I should leave this till later and proceed according to Jack's orders with the design of a larger size (the 32" color-wheel - say a color-wheel for a 14" tube) immediately. I believe that the servo which I have in mind, and which employs an eddy current (a very light eddy current) to operate against a standard motor would be especially suited to the drive I have designed.

Please discuss this with S. E. and let me have your own opinion. I was informed today that drawings 6, 7, 8, & 9 sent Friday of last week Wednesday of this week in two special express have not arrived. Material contained on these drawings is most essential to the drive in construction. Please see that the finished device accords these drawings. Important revisions of the original designs are contained on these.

ERRATA, ADDENDA, & COMMENTS

RE: PAGES 101-111.

IMPORTANT

[NOTE: Check relay C9 on Dwg. #9. The set of contacts in C9 delivering phase supply to the Drive Motor should be a normally-closed set. If Dwg. #9 indicates otherwise, it should be revised in this regard.]

DIFFERENCES BETWEEN THE ORIGINALLY-SUBMITTED CONTROL CIRCUIT & THE ONE GIVEN ON DWG. #9:

A proposed control circuit for the Microscope was submitted as Sheet #19 of the original group of sketches, and, this originally-submitted control circuit was the basis of the document, pages 101-111, entitled "Description of the Drive Alignment Control Circuit" since the Microscope Control Circuit as submitted on Dwg. #9 differs in some respects from that given on Sheet #19, the descriptive material given on pages 101-111 will not correspond exactly to the facts of the latterly-submitted circuit. Therefore, this document is submitted to amend and correct pages 101-111 wherever this is required.

The Microscope Control Circuit as given on Dwg. #9 differs from that given on the above-mentioned Sht. #19 in the following principal respects:-

- a) ^{on Dwg. #9} The signal from the downstream side of the normally-open set of load contacts in the Indicator Relay C3 is passed to the timing relay C8 and to the ^{EC} solenoid of

Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on Sht. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

b) on Diag. #9, C15 is indicated as a mechanically-held relay; while on Sht. #19 it appears as a conventional relay;

c) on Diag. #7, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 2 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On Sht. #19, C9 appears as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

d) in accordance to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

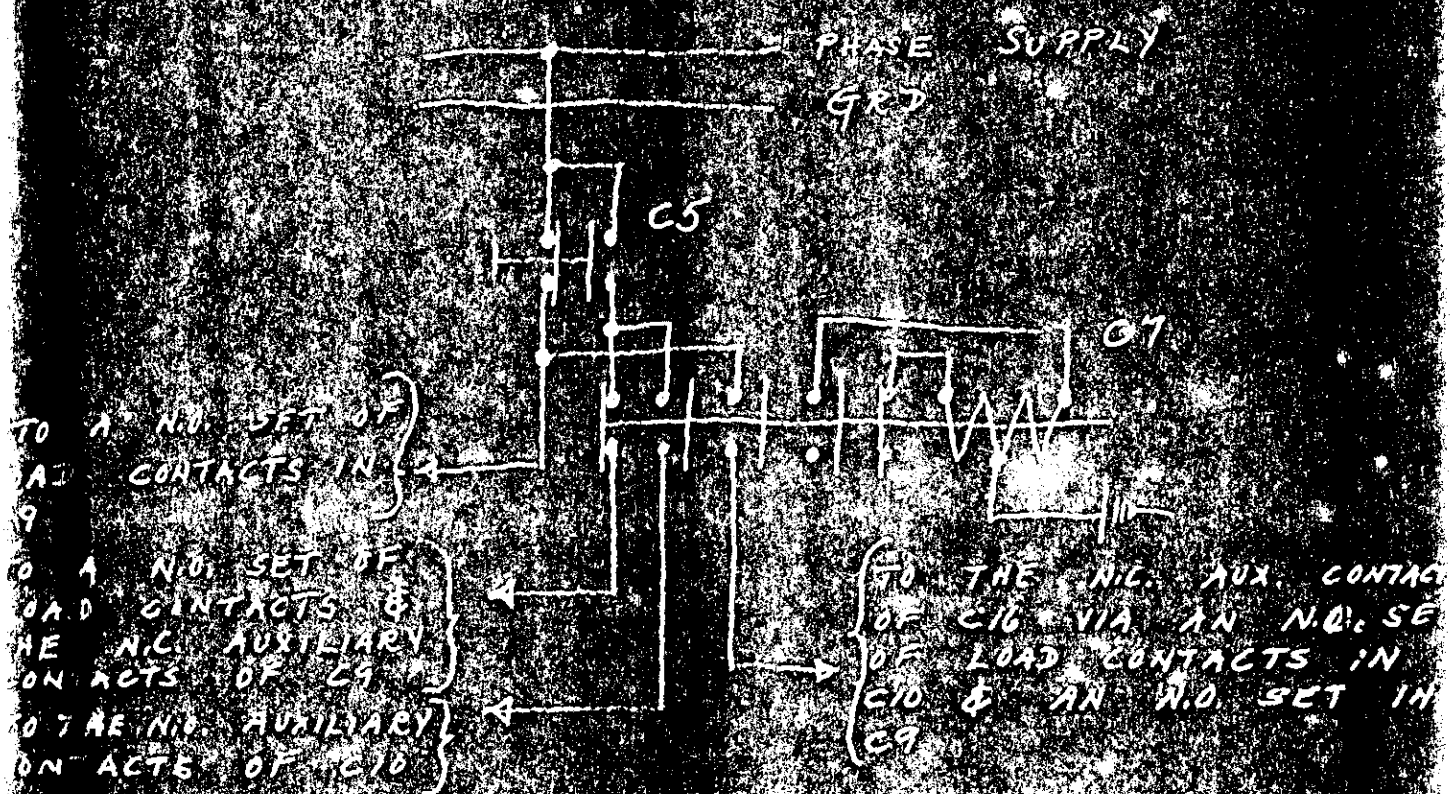
The addition of C16 to the circuit as per (c) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the frame for "black and white" viewing has been achieved. By no means, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated, and, further, any disturbing effects due to the a continued feeding of these equipment elements is eliminated.

Associated with the addition of C16 to the "black and white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that -

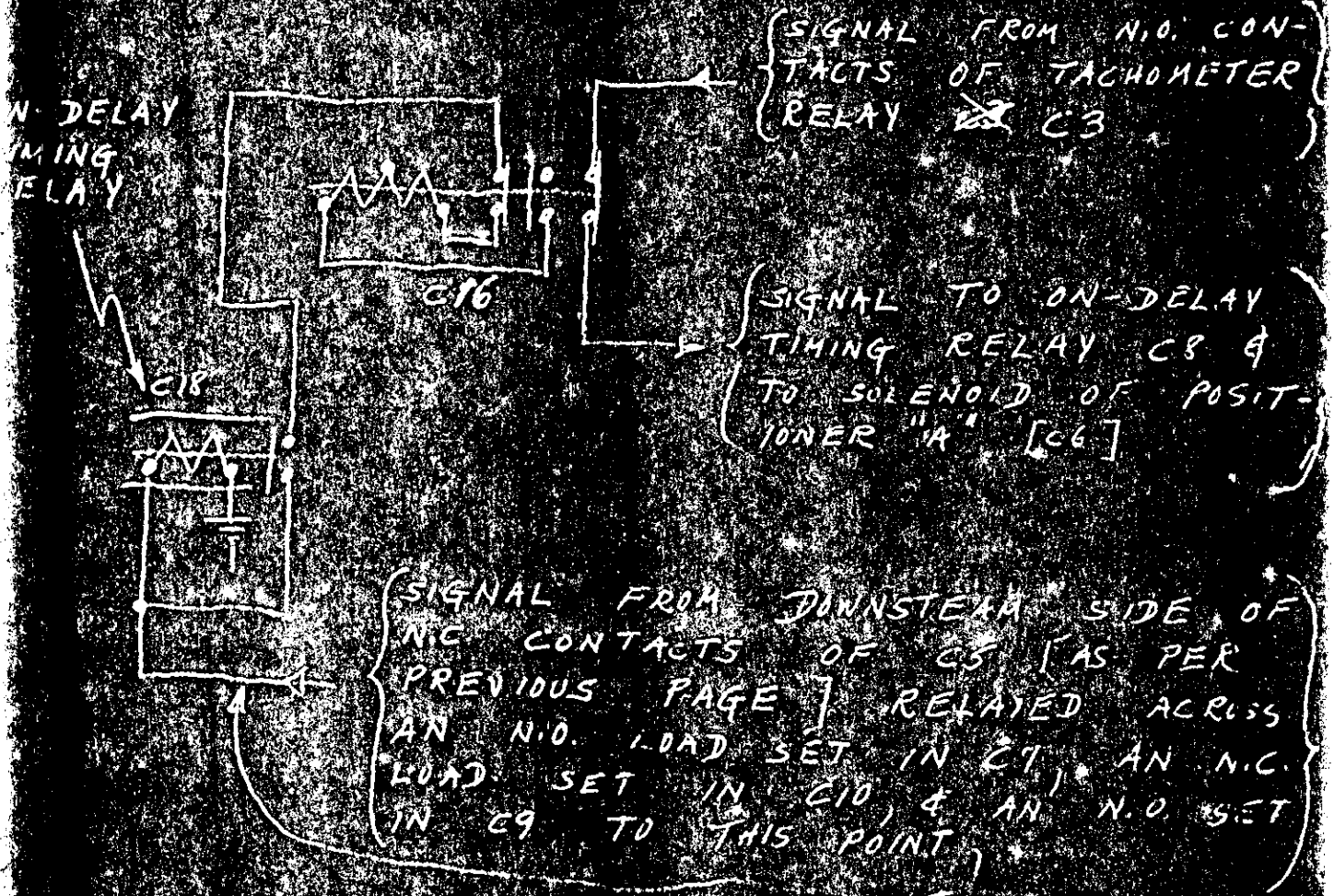
- A. when the arresting of the Drum Assembly and the disengagement of the latch-pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
- B. after C9 is engaged following the events mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the driving motivation of Drum #2 above results in the return of the latch-pawl to a position where it no longer trips the actuator of the Permet Limit Switch, C7 is engaged.

Studying the Mosaic Control Circuit as given on Diag. # 9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from phase supply, and after transmission ~~is~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically-held relay C16. The necessary conditions for the opened path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a sequel to item (C) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C5 to the normally-open set of auxiliary contacts in C10 occurs when the latch-pawl of Drum #2 has already moved the approach block of Knob "B" during the Drum's travel towards its black-and-white viewing required position. It will also be found in the "Description . . .", pages 101-111, that the movement of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a locking of the latch-pawl

in the grab slot of Knob "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear slot in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which which engages C16 (and consequently disengages C6 [the arrival of Positioner "A"]) occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the window in the cabinet. To obviate this possibility, it would be possible practical to derive the same signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Div. #9. This scheme is illustrated below:-



By the scheme illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly arresting action of the plunger of Positioner "A", would await the completion of the locking action between the Drums. This means, as well, that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the 'window' would be obtained from introducing a time-delay factor between the completion of the afore-mentioned locking action and the retraction of the Plunger of Positioner "A" from the drill hole of Knob "A". If this were done, then a way of doing it would be as indicated below:-



Of the matter raised on page 202, only one has thus far not been discussed, and this is Item (b) dealing with relay C15. On Mt. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Diag. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important: -

1. Mt. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9, to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the place side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color viewing. However, since the engagement of C14 is dependent on C15 being disengaged, it follows that the engaging of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a chattering relationship between C14 and C15. This is the prime reason for the change shown on Diag. #9.

2. The second reason lies in the inadvisability of C15, or any other relay, being continuously energized during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15 a mechanically-held relay, the permanent engagement of C15 prior to

the disengagement of C14 is assumed; and, once, the engagement of C15 is established, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned condition that no member of the switching circuit be capable of "clattering" or demand a continued feed of power during any viewing cycle, other than - possibly - the Facsimile Relay.

As C15 is now specified, its engagement follows the completion of the drum-re-alignment action, for the engagement signal is transmitted along the following path:

- a) the signal originates at the downstream side of the H.C. contacts of C5, which means that the latch-pawl of Drum #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C9, which means that C9 must be engaged - and this condition is satisfied since C9's position is reversed only after C15 is engaged;
- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C9 to the upstream side of an H.O. set in C13, which means that C13 must be engaged for the further relaying of the signal - and this is satisfied since C13 is engaged as long as C2 is in its vector position and C15 is disengaged;
- d) the signal as of (c) is applied from the downstream side of the N.O. set in C13 to the upstream side of an H.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal

— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum # 2 is brought to a given state of 'left' by the approach block of knob "A"

and,

e) the signal as of (d) is relayed from the downstream side of the N.C. load set in C12 to an N.O. load set in C11, which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum # 2 past the departure block of knob "B" during the travel of Drum # 2 towards its color-aligned position with Drum # 1, and further C11 maintains its engaged position until the next black-and-white relaying alignment is signalled.

The signal as of (e) is then applied to C15. Since the 'left' of the latch-pawl by the approach block of knob "A" imminently precedes the locking of Drum # 2 into its color alignment position with Drum # 1, it follows that C15 is engaged only as color-alignment of the two drums is achieved or is imminently about to be achieved. By the refinement of the Control Circuit given on Page 115, it would follow that C15 would ~~also~~ engage to release Positioner "B", disengage C14, and return C9 and C7 to their disengaged positions, only after ^{the} color-alignment of the two drums has been achieved.

This too (b) on Page 202 is explained!

TWO IMPORTANT CONSIDERATIONS:

Two important considerations underlying the projected design of the Control Circuit. These are:-

- a) the type of mechanically-held relay used
- b) the timing behind the release of Section "A" after black-and-white alignment has been achieved.

It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate chatter and electrical disturbances to the operation of the TV circuit when the functional demands on any given relay demands the continued engagement. This set of qualifications more or less define the type of relay which is required. Explicitly, it would be required that:-

1. the holding of the relay in engaged position be accomplished either by a mechanical or a magnetic latch
2. a second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged positions are extremely common; and, the fact of the same — mechanical held relays — is derived from the original use of such mechanical latches. More recently, it has been common to replace mechanical latches by permanent magnets which hold the relay-plunger once the plunger is drawn against the permanent magnet pole-face. The latter type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to improper operation when the baseboards to which they are attached are jammed.

Finally as regards the mechanically-held relays used, it

should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other which acts to disengage or de-latch the relay — should be signalled thru auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'dragging effect' incorporated in them to assure the completion of the engaging stroke against a spurious or 'chattering' making action.

If the construction scheduled for the models permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Positioner "A" after black-and-white alignment of the Drive has been achieved, it has been held here that the inertia of the Drive Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drive Assembly alignment and positioning in front of the picture window has been achieved. The further argument that a continued energizing of the Positioner solenoid might lead to chattering and also the electrical disturbances to the T.V. circuit in normal operation led to one of two solutions:-

A. Better construct the Positioner solenoids along mechanically-held lines;

B. hold any given Drive Assembly position on the basis of the inertia and friction forces named above.

The latter was chosen for the reason of the costs involved in the former alternative.

* NOTE:- Will regard to item (1), see page 204 and 205

ERRATA, ADDENDA, & COMMENTS

RE: PAGES 101-111

* * * * *

IMPORTANT

[NOTE:- Check relay C9 on Dwg. #9. The set of contacts in C9 delivering phase supply to the Drive Motor should be a normally-closed set. If Dwg. #9 indicates otherwise, it should be revised in this regard.]

* * * * *

DIFFERENCES BETWEEN THE ORIGINALLY-SUBMITTED CONTROL CIRCUIT & THE ONE GIVEN ON DWG. #9 -

A proposed control circuit for the 'Microscope' was submitted as Sheet #19 of the original group of sketches, and, this originally submitted control circuit was the basis of the document, pages 101-111, entitled "Description of the Drive Alignment Control Circuit" since the 'Microscope Control Circuit' as submitted on Dwg. #9 differs in some respects from that given on Sheet #19, the descriptive material given on pages 101-111 will not correspond exactly to the facts of the latterly-submitted circuit. Therefore, this document is submitted to amend and correct pages 101-111 wherever this is required.

The 'Microscope Control Circuit' as given on Dwg. #9 differs from that given on the above-mentioned Sht. #19 in the following principal respects:-

- a) ^(see Dwg. #9) The signal from the downstream side of the normally-open set of load contacts in the Tachometer Relay C3 is passed to the timing relay C5 and to the ^{terminal} of

Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on ltr. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

b) on Dwg. #9, C15 is indicated as a mechanically-held relay; while on ltr. #19 it appears as a conventional relay;

c) on Dwg. #9, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 3 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On ltr. #19, C9 appeared as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

d) in correspondence to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

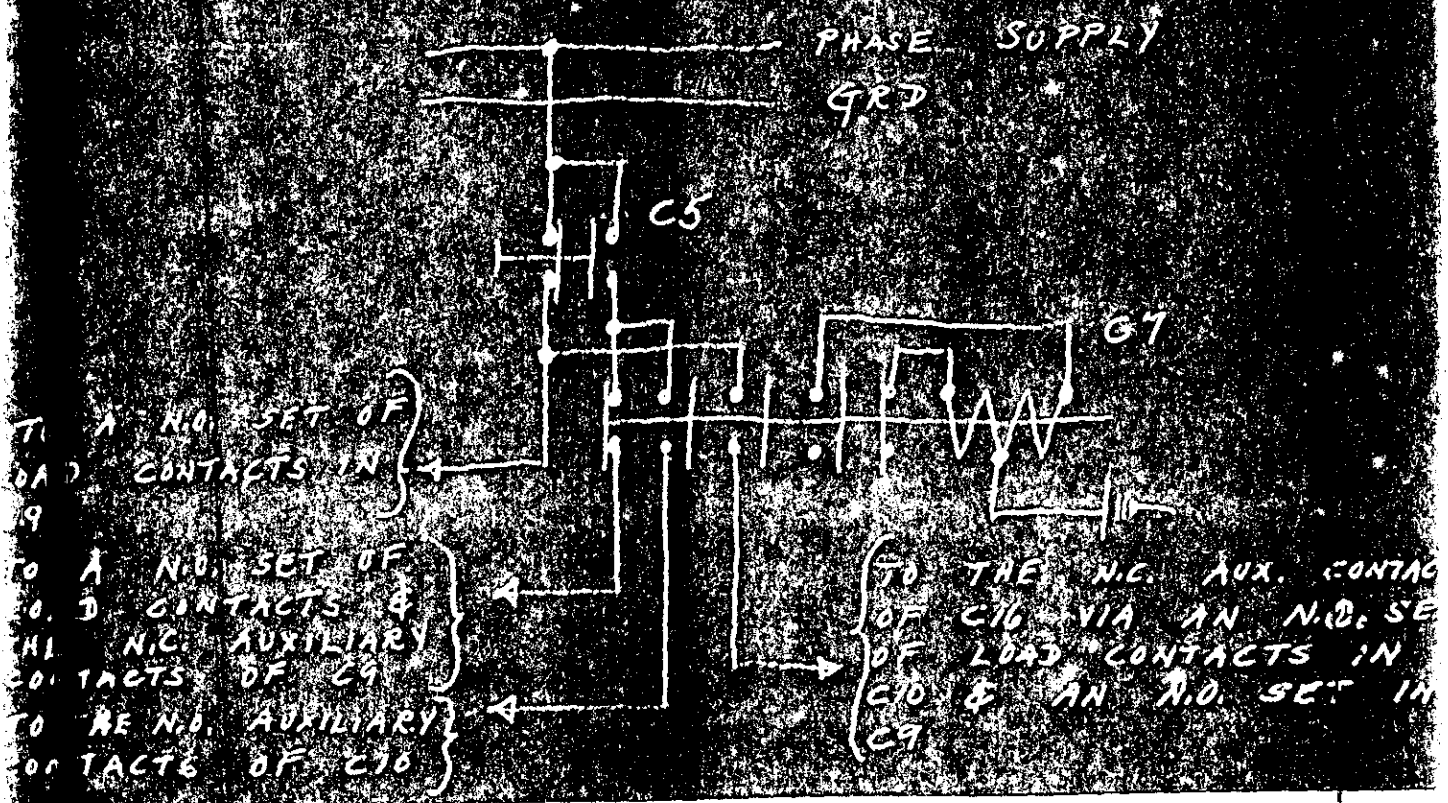
The addition of C16 to the circuit as per (a) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the drums for "black-and-white" sewing has been achieved. By so doing, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated; and, further, any disturbing effects due to the continued feeding of these equipment items is eliminated.

Associated with the addition of C16 to the "black-and-white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that -

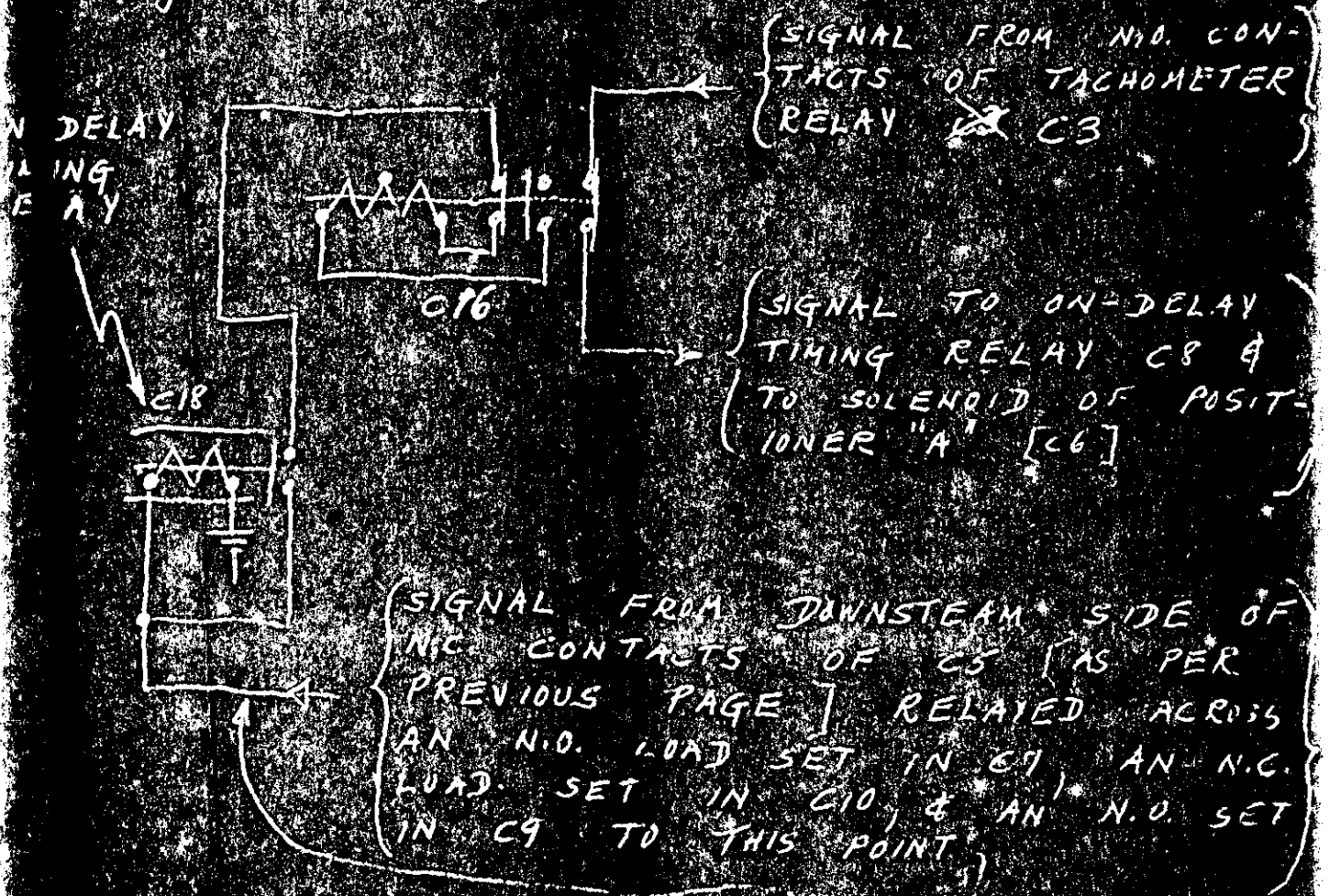
- A. when the resetting of the Drum Assembly and the disengagement of the latch-pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
- B. after C9 is engaged following the event mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the ensuing rotation of Drum #2 alone results in the return of the latch-pawl to a position where it no longer trips the actuator of the Permit Limit Switch, C7 is engaged.

Studying the Microscope Control Circuit as given on Diag. #9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from phase supply, and after transmission ~~of~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically-held relay C16. The necessary conditions for the open path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a result to item (1) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C9 to the normally-open set of auxiliary contacts C10, occurs when the latch-pawl of Drum #2 has already latched the approach block of Knob "B" during the Drum's travel towards its black-and-white viewing required position. It will be found in the "Description..." , pages 101-111, that the latching of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a blocking of the latch-pawl

in the grab slot of Knob "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear station in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which which engages C16 (and consequently disengages C6 [the solenoid of Positioner "A"]) occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the 'window' in the cabinet. To obviate this possibility, it would be possible practical to draw the prime signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Divg. #9. This scheme is illustrated below:-



By the scheme illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly - arresting action of the plunger of Positioner "A", would await the completion of the locking - action between the Drums. This means as well that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the window would be obtained from introducing a time-delay factor between the completion of the afore-mentioned locking-action and the retraction of the Plunger of Positioner "A" from the drill-hole of Knob "A". If this were done, then a way of doing it would be so indicated below:-



Of the matters raised on page 202, only one has thus far not been discussed, and this is Item (b) dealing with relay C15. On Sht. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Diag. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important:-

1. Sht. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9 to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the phase side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, ^{that} C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color-viewing. However, since ~~the~~ the engagement of C14 is dependent on C15 being disengaged, it follows that the engagement of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a chattering relationship between C14 and C15. This is the prime reason for the change shown on Diag. #9;
2. the second reason lies in the inadvisability of C15, or any other relay, being continuously engaged during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15 a mechanically-held relay, the permanent engagement of C15 prior to

the disengagement of C14 is assured; and, once, the engagement of C15 is established, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned conditions that no member of the switching circuit be capable of "chattering" or demand a continued feed of power during any viewing cycle, other than - possibly - the Synchronizer Relay.

As C15 is now specified, its engagement follows the completion of the drum-re-alignment action, for the engagement signal is transmitted along the following path:-

- a) the signal originates at the downstream side of the N.C. contacts of C5, which means that the latch-pawl of Drum #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C9, which means that C9 must be engaged - and this condition is satisfied since C9's position is reversed only after C15 is engaged;
- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C9 to the upstream side of an N.O. set in C14, which means that C14 must be engaged for the further relaying of the signal - and this is satisfied since C14 is engaged as long as C2 is in its "color" position and C15 is disengaged;
- d) the signal as of (c) is applied from the downstream side of the N.O. set in C14 to the upstream side of an N.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal

— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum # 2 is brought to a given state of 'lift' by the approach block of Krab "A" and,

- e) the signal as of (d) is relayed from the downstream side of the N.C. load set in C12 to an N.O. load set in C11; which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum # 2 past the departure block of Krab "B" during the travel of Drum # 2 towards its color-aligned position with Drum # 1, and further C11 maintains its engaged position until the next black-and-white relaying alignment is signalled.

The signal as of (c) is then applied to C15. Since the 'lift' of the latch-pawl by the approach block of Krab "A" imminently precedes the locking of Drum # 2 into its color-alignment position with Drum # 1, it follows that C15 is engaged only as color-alignment of the two drums is achieved or is imminently about to be achieved. By the refinement of the control circuit given on Page 115, it would follow that C15 would ~~also~~ engage to release Positioner "B", disengage C14, and return C9 and C7 to their disengaged positions, only after ^{the} color-alignment of the two drums has been achieved. This too (b) on Page 202 is explained!

TWO IMPORTANT CONSIDERATIONS:

Two important considerations underly the projected design of the Control Circuit. These are: -

- a) the type of mechanically-held relay used
- and
- b) the timing behind the release of Positioner "A" after black-and-white alignment has been achieved.

It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate chatter and electrical disturbances to the operation of the TV circuit whilst the functional demands on any given relay demands the continued engagement. This set of qualifications more or less defines the type of relay which is required. Explicitly, it would be required that: -

- 1) The holding of the relay's engaged position be accomplished either by a mechanical or a magnetic latch
- and
- 2) a second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged positions are extremely common, and, in fact, the name - mechanical held relay - is derived from the original use of such mechanical latches. More recently, it has been common to replace mechanical latches by permanent magnets which hold the relay plunger once the plunger is driven against the permanent magnet pole-face. The latter type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to improper operation when the baseboards to which they are attached are jarred.

Finally as regards the mechanically-held relays used, it

should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other, which acts to disengage or de-latch the relay — should be signalled from auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'latching effect' incorporated in them to ensure the completion of the engaging stroke against a spurious or chattering 'making' action.

If the construction schedule for the model permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Positioner "A" after black-and-white alignment of the Drum has been achieved, it has been held here that the inertia of the Drum Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drum Assembly alignment with positioning in front of the cabinet window has been achieved. The further argument that a continued energizing of the Positioner solenoid might lead to chattering and also to electrical disturbances to the T.V. circuit & normal operation led to one of two solutions:-

A. either construct the Positioner solenoids along mechanically-held lines,

B. hold any given Drum Assembly position on the basis of the inertia and friction forces named above. The latter was chosen for the reason of the costs involved in the former alternative.

* (Note) - Will refer to the (A), see page 204 and 205

(in continuation)

onto the departure block of Krab "B"; (b) a gliding of the latch-pawl down the slope of the departure block; and, (c), in consequence of (b), a return of C5's actuator to its normal position.

With the return of C5's actuator to its normal position, a signal would be caused to course from phase supply across the normally-closed set of contacts of C5, and then across a normally-open set of contacts in the still-engaged relay C9, to one of the normally-open sets of contacts of C14. &

C14, it will be recalled like C13, remains engaged as long as C2 is in the "color" position and C15 is not engaged. Therefore, the signal originating at the normally-closed set of C5's contacts is relayed across the indicated normally-open set of contacts in the now-engaged C14 to pass across the normally-open set of load contacts in the now-engaged C12, and appear finally at the upstream-side of the normally-closed set of auxiliary contacts of C11. Here, the signal results in the engagement of C11.

The engagement of C11, by the closing of its normally-open load contacts, opens a path for a succeeding signal from the normally-open set of contacts in C5 to be applied to the normally-open set of auxiliary contacts in C12. Thus, when Down #2, during the completion of the travel which is initiated when C12 engages, causes the latch-pawl to mount the approach block of Krab "A", the actuator of C5 is tripped, and a signal is caused to course from the downstream side of the normally-open contacts of C5 across the normally-open set of load contacts in the still-engaged C9, and then across a normally-open set of load contacts in the still-engaged C9, to the upstream side of one of the normally-open sets of contacts of the conventional relay C14. Since C14 is still engaged, this signal is relayed across a normally-open set of load contacts in C11 to wind up ultimately at the upstream-side of the normally-open set of auxiliary contacts of C12. The application of the signal to the mentioned set of auxiliary contacts causes an energizing of the disengaging section of the operating coil of C12, and a resultant disengagement of C12. Accordingly, the power signal to the drive motor is interrupted, and, in net effect, the motor is disengaged just as the latch-pawl mounts the slope of the approach block of Krab "A". The engagement of the latch-pawl in Krab "A" is just what is

then accomplished on the basis of the residual momentum of Drum #2

SENDING THE COLOR-VIEWING-ALIGNED DRUMS INTO ACTION:-

Once the latch-pawl drops into Grab "A"'s slot, the actuator member of C5 returns to its normal position, and, with C12 in its ~~now~~-disengaged position and C11 in its ^{still}-engaged position, a path is opened for a signal from the downstream side of the normally-closed set of contacts of C5 to the operating coil normally-closed set of auxiliary contacts of the mechanically-held relay C15. The application of the mentioned signal to the normally-closed set of auxiliary contacts of C15 leads to the engagement of C15. The signal which accomplishes this task proceeds from the downstream side of the normally-closed contacts of C5 across a set of normally-open contacts in the still-engaged relay C9 to the upstream side of a normally-open set of contacts in the conventional relay C14. From this point, it travels across the mentioned set of contacts in the still-engaged C14 to a normally-closed ^{closed} set of contacts in the ~~still~~-disengaged mechanically-held relay C12; from which point it is relayed to a normally-open set of load contacts in the still-engaged C11. The still-engaged C11 permits the mentioned normally-open set of load contacts to convey the thus-relayed signal to the upstream side of the normally-open set of auxiliary contacts of the mechanically-held relay C15. As indicated above, the eventual travel of the signal to ^{the} normally-closed set of auxiliary contacts of C15 leads to the energizing of the engaging section of the operating coil of C15, and hence to the engagement of C15.

In its part, the thus-accomplished engagement of the mechanically-held relay C15 leads to:-

- a) the application of a maintained and continuous energizing signal to the Drive Motor
- b) the discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14
- c) the sending out of a "disconnect signal" to C9 and C7

The discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14 according to (b) above takes place via the opening of the normally-closed set of load contacts in C15 when C15 is engaged. The discontinuation of phase supply to C13, the solenoid member of Positioner "B", means the retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B". This retraction of the plunger-member (see Div. #9) takes place under the action of the recoil spring member of the Positioner assembly. The retraction of the plunger-member of Positioner "B" from the drill-hole member of Knob "B" clears the impediment to the Drum Assembly's going into action which the energized Positioner constituted. The simultaneous discontinuation of phase supply to ~~Positioner "B"~~ the conventional relay C14 means the de-energizing of C14, and the breaking of the paths whereby the 'activating' signals for C11 and C12 are transmitted.

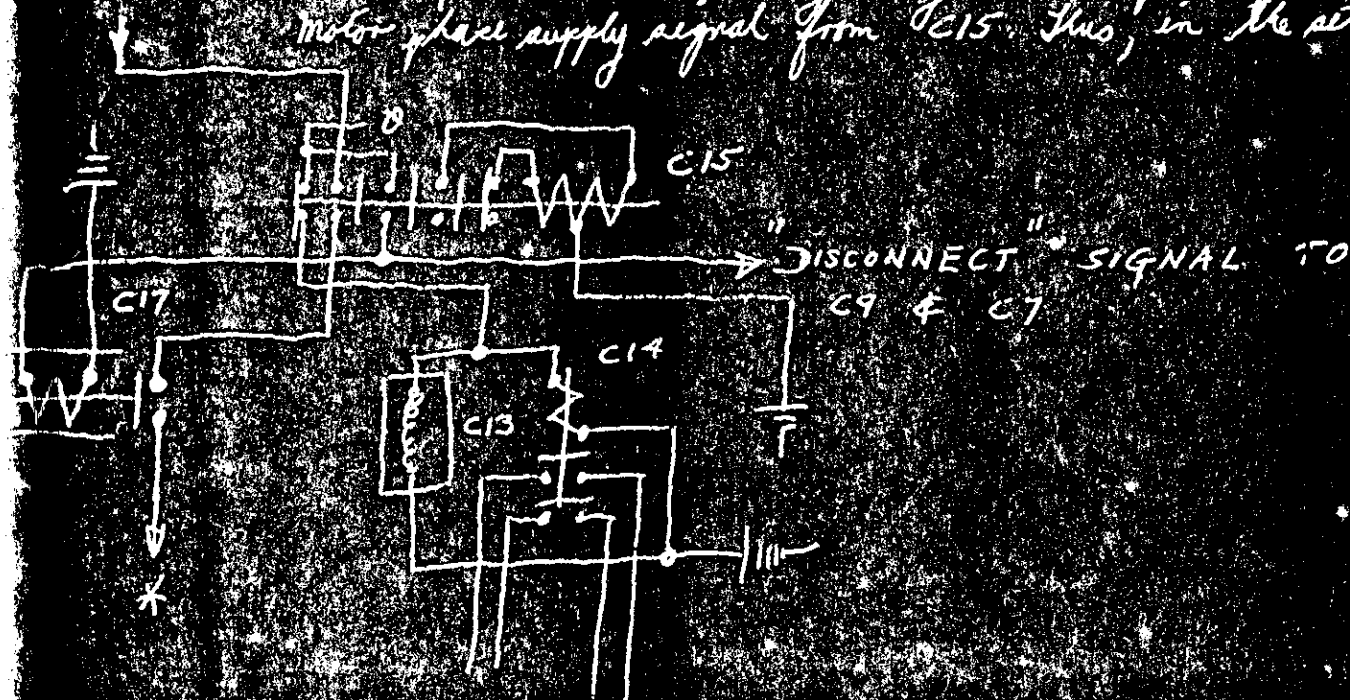
The application of a maintained and continuous energizing signal to the Drive Motor according to Item (a) above is accomplished by the 'making', or closing, of a normally-open set of load contacts in C15 when C15 engages. As noted above, since the plunger-member of Positioner "B" is withdrawn from the drill-hole member of Knob "B" simultaneously with the application of the energizing signal to the Drive Motor, both conditions for the sending of the Drum Assembly into action are accomplished with the engagement of C15:-

and

2. The ^{continuous} power supply for the Drive Motor which is required for its operation in color-viewing is supplied.

NOTE:-

The simultaneity of action which C15 establishes between the retraction of the plunger of C13 and the energizing of the Drive Motor raises the question as to whether in absence of the recoil action of plunger assembly could not result in a jamming of the plunger in the drill-hole of Grab "B" and a possible consequent stalling of the motor. To forestall such an eventuality, it might be best to place a time-delay relay in the path of the motor phase supply signal from C15. Thus, in the set-up



shown below, the on-delay timing relay C17 would delay the application of the energizing signal to the Drive Motor for a sufficient period of time to guarantee the retraction of Positioner "B"'s plungers from the drill-hole of Grab "D",

thence eliminating of questions of jamming of the plunger or stalling of the motor.

Now, let us return Item (c) above, namely the 'disconnect' signal to C7 and C9. [NOTE:- Observe that in ^{the} sketch given above a 'tap' off the signal to C7 and C9 is used to activate the on-delay timing relay C17]. By its very nature, the 'disconnect' signal to C7 and C9 is a 'clear-the-board' signal which reads the "black-and-white alignment" section of the control circuit for its next call to action. This 'disconnect' or 'clear-the-board' signal is accomplished via the closing of a normally-open set of load contacts in C15 when C15 is engaged.

In connection with the 'clear-the-board' signal from C15 to C7 and C9, it might be well to point out ^{that} a 'clear-the-board' signal for the case of the mechanically-held relay C16 is provided via a 'tap' from the color-position contact of the 2-position selector switch C2. Thus when the 2-position selector switch C2 is turned to its color-position, C16 is 'cleared' for its next service in the functioning of the "black-and-white alignment" section of the control circuit. No activation of any portion of the "black-and-white alignment" section of the control circuit follows from this since the turning of the selector switch C2 to its color-position perforce removes phase supply from the "black-and-white alignment" section of the circuit.

Finally, it should be observed that the 'clear-the-board' signal for the "color-alignment" section of the circuit [in particular for the C15 and C11 components thereof] is obtained by a 'tap' from the black-and-white position of the 2-position selector switch C2. Thus, simultaneously with the next calling of the 'black-and-white' alignment section of the circuit into action,

The rotor-alignment section of the control circuit is readied for its next call to duty.

DWG. # 8

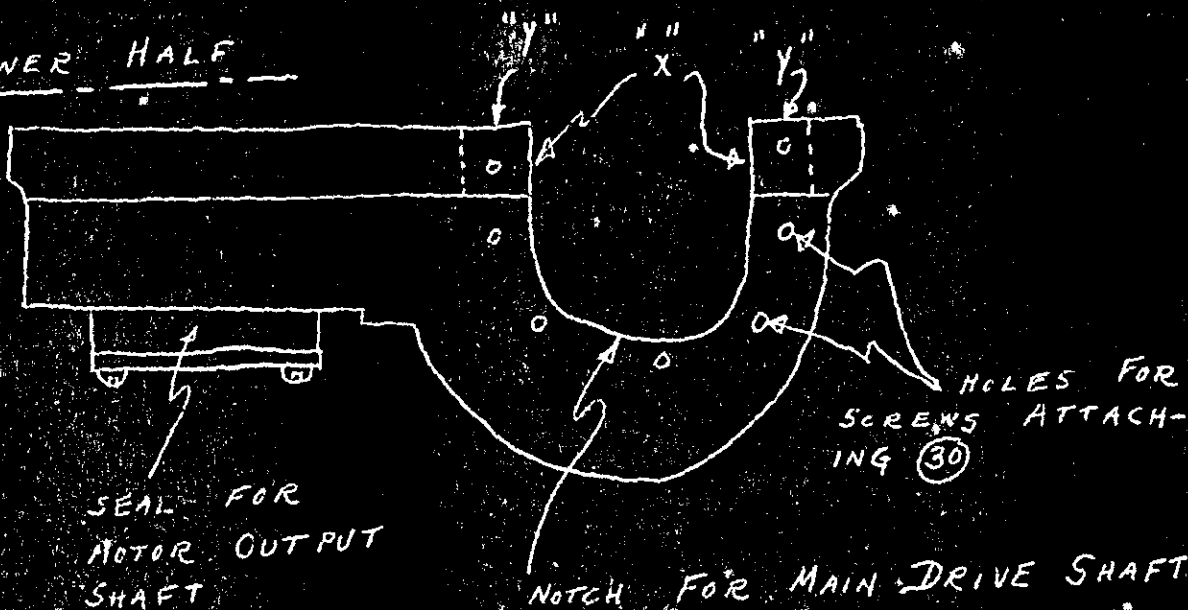
Page 1

1. $\frac{3}{4}$ " x $\frac{3}{4}$ " x $\frac{1}{16}$ " aluminum angle ring — (also see Item "JB")
2. See Item "JB"
3. " " "
4. Anchor gussets for the "support members" as per DWG. # 1
(See Items "JD", both views)
5. $\frac{3}{4}$ " x $\frac{3}{4}$ " x $\frac{1}{8}$ " aluminum angle spokes — (also see Items "JB" and "JC")
6. Nine 1600 series $1\frac{13}{16}$ " shaft-size double-sealed single row ball bearing
7. $\frac{1}{16}$ " $\frac{1}{2}$ " aluminum coverplate
8. $\frac{1}{8}$ " x $\frac{7}{8}$ " lg. rd. hd. machine screws — 6 req.
9. aluminum hub member (machine from solid round or tube stock)
10. $\frac{1}{8}$ " x $1\frac{1}{2}$ " lg. cap screw and bolt — 2 req. (See Item "JD" — Plan View)
11. mild steel support axle
12. $\frac{1}{8}$ " $\frac{1}{2}$ " aluminum anchor gussets, welded as shown to the rim — 6 equi-spaced sets req.
13. Shank of support axle — see DWG. # 1 for members completing the "support hole" for rollers per
14. $1\frac{1}{4}$ " x $1\frac{1}{4}$ " x $\frac{1}{16}$ " aluminum angle rim of Outer Drum L.H. End-Ring
15. Hole for the entry of Positioner "B"'s plunger into Hub "B"; hole is to be $\frac{7}{8}$ " at its innermost and smallest point with the peripheral metal being bevelled off as indicated to give a larger "target" for the plunger.
16. departure block member of Hub "B"
17. filter seat [NOTE:— In the immediate region of the hole member

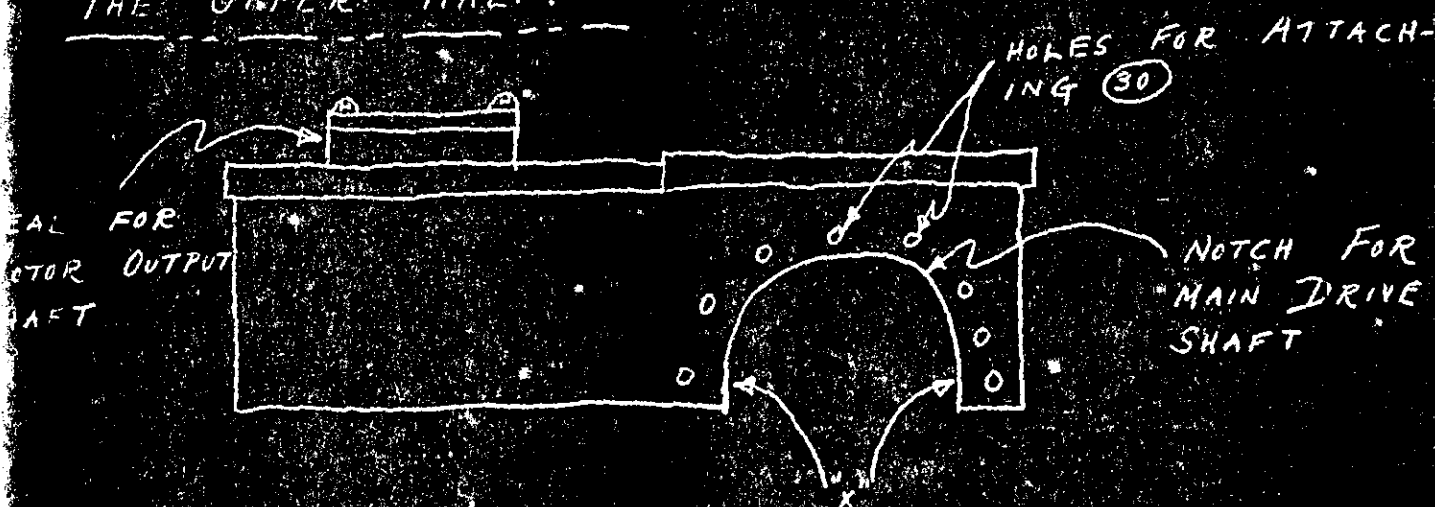
the filter slat is to be notched to permit the plunger a certain latitude in going "home" without incurring the risk of mechanical injury to the slat. The dotted-line extension of the filter slat as indicated in this detail shows the extent to which each slat covers the End-Ring for the balance of the Ring. For the indicated portion of the Ring, the dotted-line therefore shows the extent to which notching of the slat is projected. In the circumferential direction (girth direction), a $\frac{1}{2}$ " distance between the hole perimeter and the nearest portion of the notched slat is proposed.

17. The members labelled (19), when connected by brazing or welding as indicated, will form the "top portion" or "top half" of the Rear Housing. [NOTE:- The Rear Housing is composed of two halves - an 'upper half' into which the members marked (19) enter, and, a 'lower half' into which the members marked (25) enter. The 'lower-half' is flared, as indicated in the Section Elevation View, to form a "female" at its top rim, while the bottom rim of the 'upper-half' forms the "male" member of the joint. The joint should be friction-tight at all points, or should be caulked or felt-lined to achieve a reasonable degree of tightness. Both halves should be notched to permit their sliding over (27), the main drive shaft of the assembly. The so-notched sections, with the principal portions of the notches following the contours of (27), would, when assembled, form a round opening about (27) with a minimum clearance from (27). These openings are then sealed by a "thick" felt seals (31) pressed "home" against both halves by retainer rings (30). In side Elevation Views, the halves would then appear as indicated approximately below:-

THE LOWER HALF



THE UPPER HALF:-



NOTE:- The ^{immediate} portions of the notches to which "X" points is in each case a straight line tangent to the circle described by the balance of each of the notches.

"Y" in the case of the lower half, indicates regions in which the flange is eliminated to accommodate the members (30) and (31), and enable effective sealing. Both halves of the Housing to be made of 24 gage sheet steel galvanized.

20. Mild Steel Coverplate
21. Drive Motor Output Shaft
22. $\frac{1}{16}$ " ϕ \times $\frac{3}{16}$ " lg. rd. hd. mach. screws - 6 req.
23. $\frac{1}{16}$ " thk. felt rings, 4 per seal, compressed to form $\frac{3}{16}$ " thick seal
24. 18 gage sheet steel ledge for housing - size and shape to convenience
25. The members labelled (25) taken together form the 'lower-half' of the Housing. See (19)
26. Driven Gear Member of Helical Gear Train
27. Main Drive Shaft ($1\frac{3}{16}$ " ϕ at the seal points)
28. Constantly-Maintained Oil Level
29. $\frac{1}{16}$ " ϕ \times $\frac{1}{4}$ " lg. rd. hd. mach. screws (12 per retainer ring), to screw into snugly-fitting holes in Housing wall
30. $1\frac{5}{8}$ " O.D. \times $1\frac{1}{4}$ " I.D. \times $\frac{1}{16}$ " thk. mild steel retainer rings containing 12 equi-spaced holes drilled and tapped on a $1\frac{5}{16}$ " ϕ hole circle
31. 2 - $\frac{1}{16}$ " thk. felt rings $1\frac{1}{8}$ " I.D. \times $1\frac{5}{8}$ " O.D. superimposed on one another to form a $\frac{1}{16}$ " thk. felt seal
32. $\frac{1}{8}$ " \times $\frac{1}{8}$ " \times $\frac{3}{8}$ " lg. steel key between the Main Drive Shaft and the driven gear
33. the driving gear

BULKY EXHIBIT

Date received 8/27/51

ABRAHAM BROTHMAN

100-95068-1B
(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained John D. Walker

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

146. Photostatic copy of papers entitled "Notes".

80A
100-95068-1B

[Handwritten signature]

WILEY

I have been thinking of you a great deal lately, and
 wondering how you are getting on. I hope you are
 well and happy. I have been very busy lately, but
 I have managed to find some time to write to you.
 I have been thinking of you a great deal lately, and
 wondering how you are getting on. I hope you are
 well and happy. I have been very busy lately, but
 I have managed to find some time to write to you.
 I have been thinking of you a great deal lately, and
 wondering how you are getting on. I hope you are
 well and happy. I have been very busy lately, but
 I have managed to find some time to write to you.

DRIVE MOTOR ARRANGEMENTS

THE C.B.S. SYSTEM:-

It is often employed by C.B.S. to maintain synchronization of the color disc, to match the output signal from a magnetic structure which works in coordination with the color wheel against the vertical P-P path of the color receiver. This matching operation which takes place in the phase detector (discriminator or comparator) section of a servo-mechanism results in the application of the out-of-balance voltage or D.C. output of the discriminator is applied to the grid of a full frequency saturable reactor, and the saturable reactor in turn provides the voltage applied to an induction motor driving the color wheel. This servo-mechanism is conventional in its principle and will accept details of design. Like all servo-mechanisms it consists of (a) a discriminator section, (b) an anti-hunt section to provide for the stability of the drive itself against undue variations in the control signal, (c) a power output or control mechanism section which transmits the out-of-balance output signal of the discriminator into a signal operating a control mechanism which drives the induction motor. The magnetic structure which provides the out-of-balance voltage or still the drive develops the output signal in the form of an induction signal arising from the periodic variation in the magnetic field in the saturable reactor, with the magnetic field on the left half or from the other portion of the magnetic field to the right half which is used as

the reference signal. In addition to this the unit also has a feedback system which is applied to the induction motor to maintain the color wheel in synchronization. Fundamentally, the servo-mechanism operates in the same manner as a standard

of an induction motor at any given output torque and applied voltage.

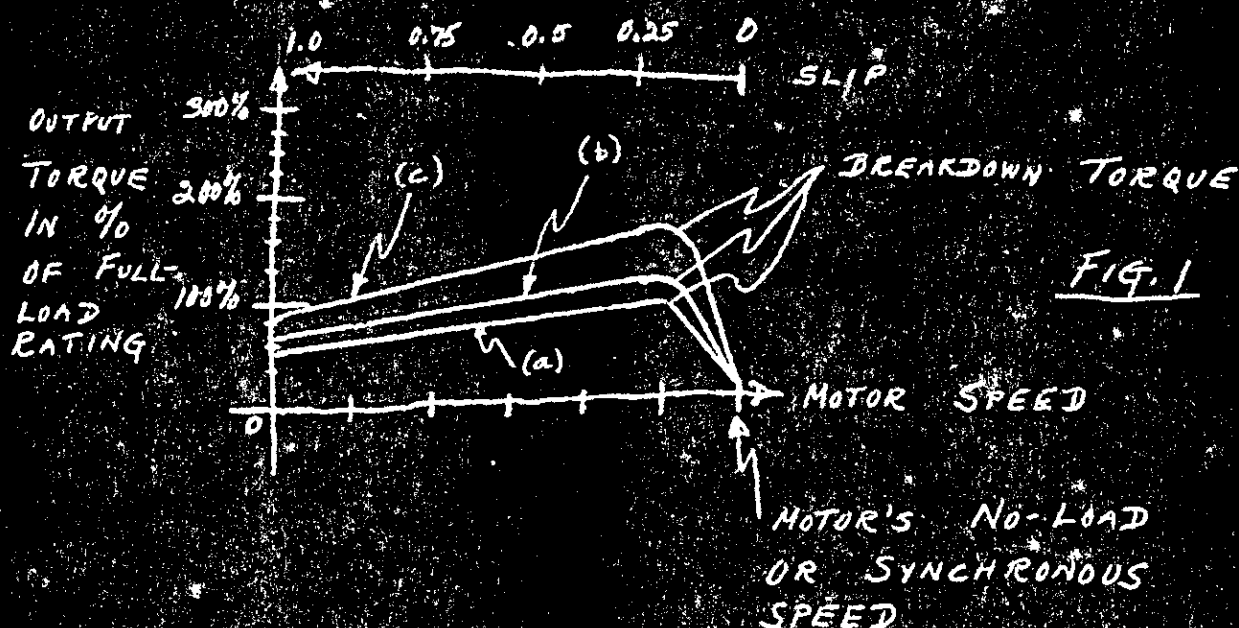


FIG. 1

Fig. 1 will illustrate the thought projected immediately above. Curves (a), (b), and (c) indicate generally the speed-torque (and for torque-slip) relationships for a polyphase induction motor where (a) holds for the lowest of three highly fixed applied voltages, (b) for an intermediate value, and (c) for the highest. If the motor is suitably within range of its designed task, then only that portion of each curve which lies between the full-load speed and the no-load speed of the motor is of interest. [NOTE - The full-load speed of the motor is that speed which corresponds to the point nearest the no-load speed at which the output-torque of the motor most efficiently approximates the fluorescent torque at the given input (given voltage) condition. Roughly speaking, this means that only that portion of each curve which lies to the right of the intercept of the breakdown torque with the motor speed axis is of interest.] In each of the cases of Curves (a), (b), and (c), it is clear that, in the indicated region of interest, the motor's speed is a highly defined function of the output torque of the motor.

the point of given applied voltage, the motor will operate at some constant speed, as is determined by the torque which it is called on to deliver.

If now we wish to draw a vertical line from any given speed lying between the motor's full-load speed and its no-load speed, and if this vertical line were to intercept each of Curves (a), (b), and (c), it is clear that to obtain the arbitrarily chosen speed it would be necessary to do either of two things:-

- a) we might adjust the input conditions to the motor (the applied voltage to the motor) to obtain some speed vs. torque curve on which the required torque corresponds to the chosen speed.
- or
b) we might ^{adjust} the driven machine so that at any arbitrarily chosen input condition to the motor, the required torque output corresponds to the desired constant speed.

In brief, the problem in driving the motor which is the motor driven portion of an CBS motor receiving unit is to establish and hold a given constant speed to a high level of accuracy and stability. The induction motor lends itself to such a service, to "constant speed service", if the input conditions to the motor are "matched" to its required output torque; -- or if the required output torque is closely regulated to a fixed input condition. CBS in its system chooses the former of the two possible alternatives, and establishes the required constant speed by adjusting the input conditions to the motor in such a fashion that the required output torque vs. speed curve is achieved.

In doing this, it employs a servo-mechanism operating a saturable reactor as the means of adjusting the input conditions (the voltage applied) to the motor.

"SOME POSSIBLE NON-SERVO MECHANISMS" :-

of the act.

In this class, some (6) alternatives have been offered :-

When the required 48-cycle A.C. is obtained by a 2-step conversion from the 144-cycle vertical pulse using a multi-vibrator and amplifier, this constitutes the 2-step conversion system.

When the required 144-cycle A.C. is obtained by a 1-step conversion from the 144-cycle vertical pulse of the act, an amplifier constitutes the 1-step conversion system.

When the required 60-cycle A.C. is obtained by a 3-step conversion from the 144-cycle vertical pulse of the act, two multi-vibrator circuits and an amplifier section constitute the 3-step conversion system.

- A. a system which provides for the feeding of a 48-cycle A.C. current to a 60-cycle, 4-pole, (1800 rpm) synchronous motor as a means of obtaining a ^{constant} output speed which is $\frac{48}{60}$ of 1800 (i.e. 1440 rpm);
- B. a system which provides for the feeding of a 144-cycle A.C. current to a 60-cycle, 12-pole (600 rpm) synchronous motor as a means of a constant output speed which is $\frac{144}{60}$ of 600 (i.e. 1440 rpm);
- C. a system which provides for the feeding of a 60-cycle A.C. current to a 60-cycle, 4-pole (1800 rpm) synchronous motor as a means of obtaining a constant 1800 rpm output which is then "gained down" mechanically to 1440 rpm;
- D. a system as per (A) except that the 48-cycle rotor pulse forms the base of the 48-cycle A.C. generating system;
- E. a system as per any of (A), (B), (C), or (D) as regards the A.C. fed to a synchronous motor.

but in which the synchronous motor works as
part of a tandem arrangement with an induction
motor, with the synchronous motor supplying
a part of the start and run energy requirements
and,

F. a system as per (A), (B), (C), or (D) as regards
generating of an A.C. feed to a synchronous motor
as per (E) as regards a tandem arrangement
an induction motor but in which the two motors
built into a common frame.

Each of the systems listed above have the following in common
(a) They propose a "lock" to a powerful and accurate signal
[the 144-cycle vertical pulse in (A), (B) and (C), and the 48-cycle
color pulse in (D)] and, in fact, a signal which gates
picture-projection of the set; and, (b) they lodge the phase
detection or discrimination functions of the CBS servo-mechanism
in the functional properties of a synchronous motor.

THE NOW-PROJECTED IDEA:-

The now-projected idea goes back to the use of an induction
motor as the Driver for a color-wheel or color-drum, as
already been indicated [Pages (2) and (3), — in particular (2)]
an induction motor lends itself to constant speed service under
the conditions imposed. The above here goes to that as
listed under Item (b) under Page (3).

Let us suppose that as a primary condition, it is
required to drive a given color wheel or color drum
for the normal and usual design procedure, 10-25%
slip, and that therefore its operating speed at standard
supply voltage would lie somewhere between its full-load
and its no-load speed. This condition would be in

but in which the synchronous motor works as part of a tandem arrangement with an induction motor, with the synchronous motor supplying only a part of the start and run energy requirements;

and,

- F. a system as per (A), (B), (C), or (D) as regards the generating of an A.C. feed to a synchronous motor and as per (E) as regards a tandem arrangement with an induction motor but in which the two motors are built into a common frame.

Each of the systems listed above have the following in common:-

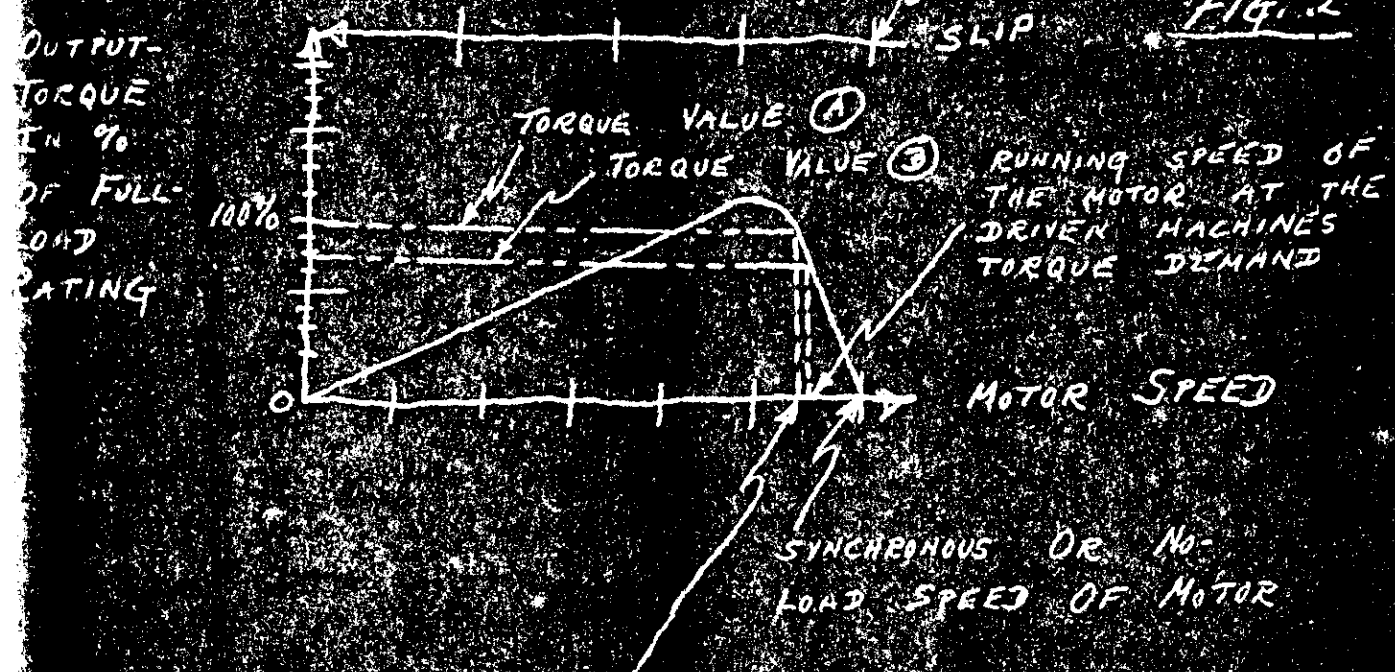
- (a) They propose a "lock" to a powerful and ^{highly} accurate signal [the 174 cycle vertical pulse in (A), (B) and (C), and the 48-cycle color pulse in (D)] and, in fact, a signal which gates the picture-projection of the set; and, (b) they lodge the phase detection or discrimination functions of the CBS servo-mechanism in the functional properties of a synchronous motor.

THE NOW-PROJECTED IDEA -

The now-projected idea goes back to the use of an induction type motor as the driver for a color wheel or color drum. It has already been indicated [Page (2) and (3), — in particular (3)] that an induction motor lends itself to constant speed service if either of two conditions are imposed. The choice here goes to that alternative listed under Item (b) ~~under~~ on Page (3).

It is supposed that as a primary condition, the motor that is selected to drive a given color wheel or color drum is, as per the normal and usual design procedure, 10-25% "over-size", and that therefore its operating speed at standard supply voltage would lie somewhere between the full-load speed and its no-load speed. This condition would be indicated by

Fig 2:-



when the running speed of the motor and the machine would lie between the full-load speed of the motor and the motor's no-load or synchronous speed. Let us suppose that the full-load speed of the motor is 1725 rpm and its no-load speed is 1800 rpm, and, finally, let us suppose that the torque-demand of the driven roller-wheel or roller-drum within the equilibrium speed range is such that a speed of 1750 is obtained from the motor. There a gear ratio between the motor shaft and the wheel or drum-shaft of 50:60, this would mean a running speed of approximately 1458 rpm for the wheel or drum. To bring the wheel or drum to a constant speed of 1440 rpm then the indicated gear set would demand a motor speed of approximately 1729 rpm. To accomplish this with the conditions stated above, to reduce the motor speed from 1750 rpm to 1729 rpm, would require, by Fig 2, that the torque-demand on the motor be lifted from Torque Value (B) to a value very close to Torque Value (A). The task, which amounts to supplementing the driven device's torque-

demand by an increment in torque that when added to Torque Value ⑤ would approximate Torque Value ④, the newly-projected idea proposes be accomplished with an Eddy Current Brake which is controlled by a servo-mechanism linkage.

Before continuing with a description of the newly-projected idea, let us examine, at least superficially, what is involved. If 1725 rpm is the full-load speed of the motor involved and its nominal horsepower rating were $\frac{1}{8}$ HP (0.125 HP), then the full load torque-output of the motor would be:

$$\frac{0.125(63025)}{1725} = 4.57 \text{ in-lbs.}$$

If the motor were as much as 25% overage and if its loaded speed without external influences were 1750 rpm as indicated above, then

$$\frac{(1-0.25)(0.125)(63025)}{1750} = 3.37 \text{ in-lbs.}$$

would be its output torque at the above-indicated condition of loading, and

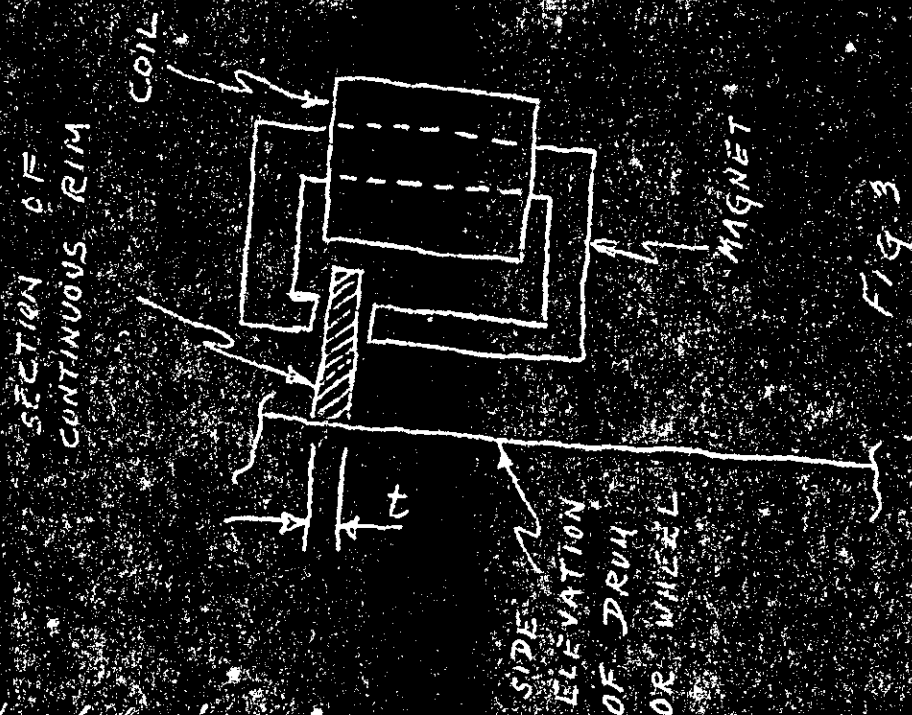
$$4.57 - 3.37 = 1.2 \text{ in-lbs.}$$

would have to be the torque increment borne by the Eddy Current Brake Assembly. Assuming that the braking action would occur at a radius of 12" from the axis of rotation, then

$$\frac{1.2}{12} = 0.1 \#$$

would have to be the force exerted by the Brake at the indicated radius.

Consider then an arrangement as per Fig. #3 in which a rim (of aluminum), attached to the rotor-wheel or rotor-drum, is made to pass thru a magnetic structure of the type indicated in Fig. #3:-



Let the pole face be square, and let the average path of the induced currents be assumed to be $4l$, where (l) is the length of any side of the pole face. The magnitude of the induced E.M.F. in a circuit in which a conductor of length (l) , cuts magnetic flux of density B at a velocity of (v) is given by:-

$$E = Blv \times 10^{-8} \quad (1)$$

where (E) is in volts, (l) is in cms., and (v) is in cms. per sec. If the resistance of the conductor is given by (R) , then

$$R = \frac{4\rho l}{t \times l} = \frac{4\rho}{t} \quad (2)$$

should define the resistance in ohms to the induced currents where (ρ) is in $\frac{\text{ohm-cms.}}{\text{sq. cms.}}$, $4l$ = the average current path, and the product of (t) - in cms. - and (l) , sq. cms., defines (A) , the area of the conductor. From (1) and (2), it follows that I , in mps., would be given by:-

$$I = \frac{E}{R} = \frac{Blv \times 10^{-8}}{\frac{4\rho}{t}} = \frac{Blv (10^{-8}) t}{4\rho} \quad (3)$$

The force acting on a conductor in a magnetic field for the above-indicated construction is given by:--

$$F = \frac{B I l}{10} \quad (4)$$

where:-- (F) , in dynes, is the mentioned force; (I) , in amps, is the current flow in the conductor; and, (l) , in cms., is the length of the conductor. Thus, by (3) and (4), we obtain

$$F = \frac{B l}{10} \cdot \frac{B l v (10^{-9}) t}{4 \rho} = \frac{B^2 l^2 v (10^{-9}) t}{4 \rho} \quad (5)$$

Converting (F) , which in (5) is yielded in dynes, to units of gms., and

$$980 \text{ dynes} = 1 \text{ gm.}$$

then

$$(F) = \frac{B^2 l^2 v (10^{-9}) t}{4 \rho (980)} = \frac{B^2 l^2 v (10^{-11}) t}{39.2 \rho} \quad (6)$$

For a speed of 1410 rpm (24 rps) and a radius of 12", (v) would have a value of

$$v = 2\pi (24)(12)(2.54) = 4530 \text{ cms./sec.}$$

and, hence (6) may be written

$$F = \frac{45.3 B^2 l^2 t (10^{-9})}{39.2 \rho} = \frac{1.153 B^2 l^2 t (10^{-9})}{\rho}$$

Taking

$$B = 750 \text{ gauss}$$

$$l = 1 \text{ cm.}$$

$$t = 0.2 \text{ sec.}$$

$$\rho = 3.21 (10^{-9}) \text{ ohm-cm.}$$

Substituting

$$F = \frac{1.153 (10^9) (1) (0.2) (10^{-9})}{3.21 (10^{-9})} = 40.3 \text{ gms.}$$

$$\frac{40.3}{454} = 0.0886 \text{ #}$$

If we were to use two such magnetic structures as have been indicated above, thus giving the arrangement a wide latitude of operation about the required 0.1 # force calculated on Page 7; then a braking force of

would be available. $2(0.0886) = 0.1772 \#$
By definition

$$\Phi = BA \quad (7)$$

and since $A = l^2 = 1 \text{ cm}^2$, then $B = \Phi$. The required magnetomotive force is given by:-

$$\Phi = \frac{\text{mmf}}{R} \quad (8)$$

where R = the reluctance of the magnetic path, and is, in turn, given by

$$R = \frac{l}{\mu A} \quad (9)$$

where:- l = the length of the magnetic path; μ = the permeability of the path; and, A = the area of the flux path. Setting $l = 0.3 \text{ cm}$, $\mu = 1$ and since $A = 1 \text{ cm}^2$,

$$R = \frac{0.3}{(1)(1)} = 0.3 \text{ reluctance units}$$

By (8) then, since

$$\text{mmf} = \frac{4\pi NI}{10} \quad (10)$$

then

$$750 = \frac{4\pi NI}{0.3}$$

$$NI = \frac{750(0.3)}{0.4\pi} = 179 \text{ amp-turns}$$

If (I) is to be not more than 0.005 amps as an average condition,

$$\frac{179}{0.005} = 35,800 \text{ turns/coil}$$

would be required.

Assume the use of 36 gauge wire. Then, since 36 gauge wire = 0.005 in.

$35,500(25) = 895,000 \text{ cir. mils} \div 0.895 \text{ in.}^2$
 would have to be the x-sectional area of the winding on any one side of the square pole section. For $x'' = \frac{1}{2}$, then



FIG. 4

$$l_2 = \frac{0.895}{\frac{1}{2}} = 1.790''$$

Since any side of the pole is 1 cm. = 0.394'', then the minimum length of any winding-turn would be 1.8'', which 5.6'' per turn would be the maximum length

This would mean an average length of 5.6'' per turn; or a wire length of

$$\frac{35,500(5.6)}{12} = 10,720 \text{ ft. per coil}$$

Since the resistance of 36 gauge wire is approximately 450 ohms/1000 ft., then

$$\frac{10,720}{1000} \times 450 = 4830 \text{ ohms}$$

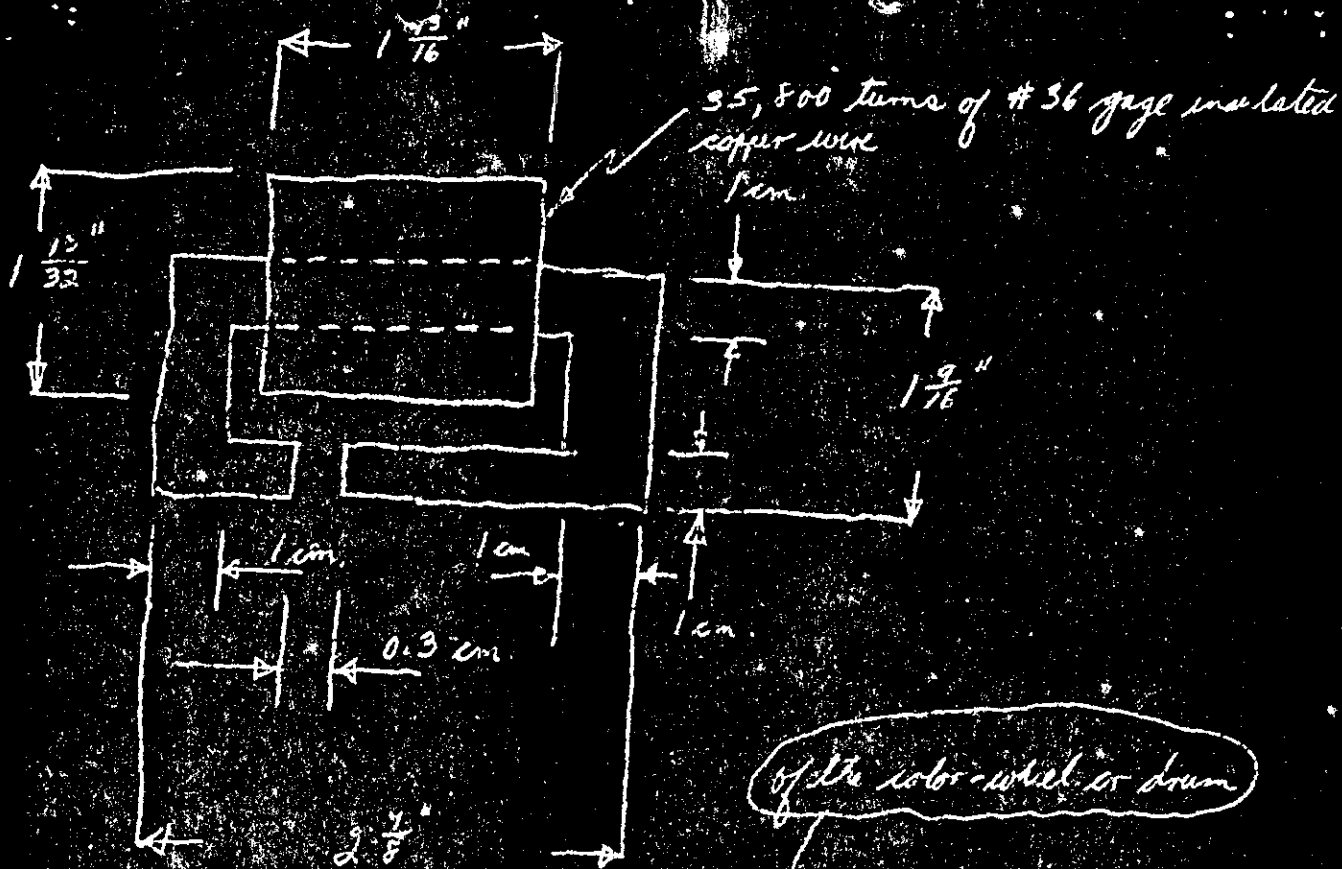
would be the resistance per coil. Two coils in series, as stated above would mean a total resistance of

$$2(4830) = 9660 \text{ ohms}$$

The feeding of 5 milliamperes against a resistance of roughly 10,000 ohms is a test which lies comfortably within the range of a 6SN7 vacuum tube.

By the above approximations, it will be seen that:-

a two-coil magnetic structure as per the sketch given below:-



placed opposite another (to establish balance around the axis of rotation) opposite fed by a tube of the class indicated above

and

- b. a servo-mechanism based on a phase detector or discrimination section comparing the pulse frequency from a slug-actuator and pulse magnet arrangement with the vertical r-p pulse of the act, in which the out of balance or error voltage from the phase detector circuit is used to bias the operation of the tube feeding the brake magnets

would provide a system, when properly stabilized by anti-hunt provisions, that, in conjunction with an aluminum rim of c. & c. electrodes attached to the wheel or drum, would yield accurate control over an induction motor towards obtaining constant (and controlled) speed service from the motor.

Thus a novel servo-mechanism for the control of an induction motor (single-phase, - or even 2-phase) has been outlined. It now remains to suggest the merits of one system

with respect to another.

CRITIQUE OF THE DESCRIBED SYSTEM

For obvious reasons, it would be best to treat with each system on their individual merits, and then to treat with their comparative positions.

The CBS synchronizing method has as its strongest advantage the fact that it employs a type of motor, an induction motor, which permits of a wide latitude in translation as the screen is built up upward. As the industry moves towards larger screen color viewing sets, CBS will be able to use its system, almost intact, except for increasing the motor sizes involved. The larger motors which will become involved will call for a comparative moderate increase in the cost of the synchronization systems they employ. As a rule, induction motors are less expensive, more rugged, and smaller than corresponding speed synchronous motors. There are important factors from many points of view. There can be no doubt that the "tightness" of CBS system's arrangement would be something less than one could obtain from the best kind of a design in a synchronous motor power; but a stable and accurate servo solution ^{using an induction motor} is possible at a lower production cost.

The systems described heretofore under the heading of "SOME POSSIBLE NON-SERVO MECHANISMS" require some end comment, after their common properties are discussed. In each of systems from (A) thru (F) respect the use of one of the best powerful and accurate operating signals as a comparison standard to gauge the performance of an externally powered motor, but rather than systems use such signals as point in to guide the performance of a motor power generating section of the system, and underlying principle is regularly addressed to in (A) thru (E), and, possibly, less regularly in the case of (F).

(79)

The principle of employing adding a motor-power-generating section to the set and controlling the characteristics of the generated power by "locking" the motor-power-generating section to one of the set's powerful and accurate signals commutes one to the class of synchronous type motors, for these are the only type of motor that can exploit the aforementioned "lock". There can be no doubting of the control which the "lock" exerts over the performance of the motor-power-generating section of the set; but every reason exists for believing that only a fairly special type of synchronous motor can avoid attributing a certain "looseness" to the system as a whole. Ordinary construction synchronous motors do "hunt" and oscillate about their nominal "absolutely" constant speeds. For most synchronous motor services, the mentioned "hunting" or oscillation is a negligible item, for the service tolerances are sufficiently wide to take this into account. In the "NON-SERVO MECHANISMS" which these motors serve, they, as noted above, incorporate within themselves the phase detection and anti-hunt functions which are otherwise taken care of in the CBS synchronization system. Hence, the synchronous motors which must be used here must be of a construction that limits the "hunting" and oscillating tendencies to a negligible limit. Given such a specially constructed synchronous motor (which means that, if one were to run a motor which approximates the stability which the "locked" motor-power-generating section would have), there could be no questioning of the stability which such an arrangement would have.

Finally, we are brought to the system projected under the heading of the "THE NEW-PROJECTED IDEA". It has already been indicated that the "NEW-PROJECTED IDEA" amounts to a complete reversing of the fundamental concept behind the CBS servo. Whereas CBS achieves constant speed servo there a control exerted over the input conditions to the motor. The "NEW-PROJECTED IDEA", which will hereafter be referred to as the Eddy Current Brake

Principle, select to achieve stable constant speed service by the motor's work-output. The fact that the Eddy Current Principle uses an induction motor means that every Eddy-Current motor that was previously attributed to the CBS servo-system and it employs an induction type motor, must also be attributed now-proposed system. The other advantages which the new-proposed system makes available will come out in the comparisons and treatments listed below:-

For quite clear reasons, the comparisons noted below will be referred to the now-proposed idea as a reference standard:-

Control over the input-conditions to the motor, which in CBS is achieved, through a saturable reactor as a means of controlling the applied voltage. Saturable reactors are expensive equipment, and in the best of production conditions will remain so, for the iron of this must answer to the very highest of standards for magnetic iron. It is the writer's belief that a saturable reactor of the type used cost in the order of \$20 each; and, further, it is estimated that little hope can be held for this to be produced at a selling price than \$5 each. By comparison, the two magnets of the new-proposed idea would cost substantially less than \$5.00 for both, a reasonable estimate being about \$1.00 for the two magnets. An important factor needs in a comparison between the costs of a 65H7GT (which is used to "power" the magnets) and the cost of the 6AN6 (which is used to operate the saturable reactor). A difference in the work is involved here. A more important factor is the "time factor" of a saturable reactor versus that of the magnetic structures which have been proposed here. A saturable reactor has a "time factor" of 70 $\frac{1}{20}$ sec., which is large in comparison to the phenomenon to which

* The optimum gain properties of a saturable reactor are critically dependent on the quality of the iron used.

accomodation must be made, and is certainly very much larger than one would obtain from the brake magnets.

Now, turning to a comparison between the "NON-SERVO MECHANISMS" and the now projected idea, the cost of a synchronous motor versus that of an induction motor bears out the most obvious item of comparison. The cost of a 4-pole synchronous motor is substantially higher than that of a 4-pole induction motor. The cost of a 12-pole synchronous motor as is proposed in Item (B) Franklin 5045 POSSIBLE NON-SERVO MECHANISMS would be even larger, being into the question of the motor power-generating sections, with cost of the proposals from (A) that (C) involve, it is clear that for us there large item of additional expense which must be compared with the high cost of a synchronous motor of fairly special design. The role that the motor power-generating section would play in the design of the overall cost of the wheel we have shown would be a factor equally pronounced in the case of drive motor systems (and I would happen like the industry move toward larger synchronous). In the connection, it should be recalled that the capability of the C-35 synchro generator system to be handled without external synchronous motor larger systems was considered above to be one of its outstanding advantages. The question which arises from the principle of type motor of an induction motor is characterized by an accuracy of operation, a accurate and precise signal and which makes a motor of very great value in many types of control systems, as factors to achieve the item (D), but is substantially more than the item (E) and (F). In looking at the item (G) it is clear that the bulk of the cost and the main part of the expense is shifted to the induction motor system, which is a factor as urgent as it is possible to achieve. The cost of the power-generating section is larger than that of the motor.

[illegible]

Without further belaboring the point, it is then clear that in schemes (A) thru (F), the translation of the basic motion to larger size drives would be costly because of the higher cost of synchronous motors as compared with induction motors, and because the necessary power-generating sections would have to increase with the size of drive involved (even when schemes (E) and (F) are used).

Before leaving the topic of the "NON-SERVO MECHANISM", it should be observed that as larger size screens are supplied for color-viewing, and as ~~larger~~ especially as this begins to involve the use of drum rather than disc assemblies, the question of the size (the physical spatial dimensions) of the motor frame will become increasingly important. As previously pointed out, synchronous motors are larger than induction motors of the same horsepower rating, and hence this factor would be aggravated by the use of synchronous motors. * And, lastly, it should be remembered that when schemes (A) thru (F) involve multi-vibrator or counting circuits as component parts of the vertical pulse-to-generated A.C. motor-driving power assemblies, there are an additional cost item.

Returning to the question of the comparative merits of schemes (A) thru (F) versus those of the now-proposed idea, it will be recalled that it was said of the "NON-SERVO MECHANISMS" that there would be no doubling of the "tightness" of the "lock" that would be attained via the "NON-SERVO MECHANISMS". This puts it up - any servo-mechanism, whether it be the CBS servo or the fly current brake principle servo, to match the stability which

When going into the question of motor size, it should be noted in connection with scheme (B) the frame size of a 12-pole motor would be larger than that of a corresponding horsepower 4-pole motor.

the fact that the magnetic structure
of the motor is such as to require for
the purpose of the present mechanism itself could rep-
resent a point which the design would be guided by the de-
sign of the full scale machine. Determining the ratio
of the motor to the generator, the proper provisions, the
proper a stability which would give a convergent
character to the obtained results (A) then (F). The possible
arrangements which may be incorporated into the drive-linkage are the
principles of the principle of the drive-linkage, developing a feed-back
with the feed-back with the discriminator or pho-
tometer, in operating the drive feeding the brake magnet
which is of the general principle could give the drive-linkage
which would indeed include the drive of what could be
used (A) then (F). One of the ways of achieving the regu-
lation of the drive would be to have the Main Drive shaft drive
the discriminator of the type made by Ellinger; while a
smaller shaft would be to receive a portion of the power or
output of the discriminator, full-wave rectify the said output
and the output of a turn-off filter, and then employ it
for the purpose suggested above. Finally, towards the goal
of achieving a high degree of the stability, which scheme (A) then
would offer, it is possible to alter the slope of the speed
characteristic of an induction motor towards a less steep
slope (and hence a less critical sensitivity) by introducing
an increased resistance into the motor rotor. There are an
infinite number of conventional ways of accomplishing this, and
that experiment would suggest.

For in summary, the now-projected idea offers the following advantages over the CBS synchronization system:-

(a) a great advantage is that the now-projected idea employs the expensive tube-to-power the operated mechanism, in that the now-projected employs a far less expensive operated mechanism (an Eddy Current Brake) than the CBS system (with its returnable reactor).

(b) a great advantage is that the Eddy Current Brake operated by the now-projected idea involves a smaller returnable reactor than does the returnable reactor of the CBS system. The lower "time-factor" characteristic of the Eddy Current Brake permits of the addition of a number of effects such as have been mentioned in the CBS system without interfering with the accuracy of the CBS synchronization system.

(c) the now-projected idea offers the following advantages over the CBS system:-

(i) a great advantage is that the now-projected idea employs a motor-driven mechanism in that the now-projected does not involve rewinding or a returnable reactor. Translation between a set pulse and the signal generated from such a translation is made from that the now-projected idea does not involve a motor-driven rewinding action as part of the CBS system.

(ii) a great advantage is that the induction motor used in the now-projected idea is smaller for any given horsepower than is a synchronous motor.

(iii) the now-projected idea of a returnable reactor for more costly does not require a 3 cycle returnable reactor would that be used to provide the returnable reactor as in the CBS system.

BULKY EXHIBIT

Date received 8/20/57

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained John D. Walker

Address Federal Detention Headquarters, NYC

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 147. Photostatic copy of Drawing #6 Revised.
- 148. Photostatic copy of Drawing #7 Revised.
- 149. Photostatic copy of Drawing #8 Revised.
- 150. Photostatic copy of Drawing #9 Revised.
- 151. Photostatic copy of Notes on Drawing #9.
- 152. Photostatic copy of Paper entitled "Errata, Addenda, and Comments".

81
100-95068-1B
S.M.

Dr. G. H. FERRIS

1954

1. "x" 1" x 8" bright strip glued to plywood base (2)
2. plywood base 1" x 1" x 8" forms to give a full line of contact
of (2) with the Outer Drum L.H. Lubricating along the Ring's
periphery.
3. mild steel drawing for bronze bushing (2). To be formed from 1/2" D.
K. 1/2" x 1/2" x 1/2" 1120 stainless steel tubing 1/2" by 1/2" and welded
to end of the lever bar (6).
4. form to 1/2" x 1/2" x 1/2" of lead-bronze bearing bushing (bronze
bar Waco).
5. do (2).
6. 1/2" x 1/2" wide slot in which the actuator pin (2) rides.
To be drilled and (steel), hardened, and press-fitted into the
hole (2). The actuator pin to be 1/2" by
1/2" wide x 1/2" thick x 1 1/2" by mild steel bar, to be fixed in
according to convenience into the indicated end of the
actuator's plunger.
7. Pin-actuator type (2) into the mounting screw-pitcher's
plunger.
8. Actuating extended & plunger.
9. Allen Bradley size #6 small mounting model, 210 v, 20 cycle,
A.C. Solenoid (Bulletin 860)
10. Cap screws & bolts anchoring the actuator's solenoid to bedplate
11. 1/8" x mild steel flange running from the actuator's bedplate to
the brake's baseplate.

15. Identical with (3) except that this gusset is also welded to the gusset (17)
16. Tops of the solenoid's coil
17. $\frac{1}{2}$ " mild steel gusset plate running between one leg of the angle (16) and the baseplate (5)
18. $\frac{3}{4}$ " x $\frac{3}{4}$ " x $\frac{1}{4}$ " structural steel angle
19. #5 wood screws
20. Knot at one end of the solenoid's plunger
21. Retainer for the Recoil Spring (22). Dimensions to conform with (20) to be tied into the "knot" portion (20) of the solenoid's plunger by any means that insures squariness of the Retainer with the plunger's principal axis
22. Recoil Spring (Specifications soon)
23. Vertical strips for Recoil Spring Mount of mild steel plate. Thickness along its entire material. Dimensions of all named Retainer to conform where they are not defined by Proj. # 6
24. $\frac{1}{2}$ " x $\frac{1}{2}$ " x $\frac{1}{4}$ " spacer & nut tying the Retainer (21) to the horizontal strips of the Recoil Spring Mount
25. Retainer for the other end of the Recoil Spring Mount. Identical with (21) except for method of mounting, and the fact that (21) goes with the "knot" (20) while (25) is fixed.
26. $\frac{1}{2}$ " mild steel gusset running between the angle (16) and the plate (23). Height of the gusset plate same as (17)
27. $\frac{1}{2}$ " x $\frac{1}{2}$ " plate for the mounting of the plate assembly
28. Recoil Spring (22) in Plan Perspective

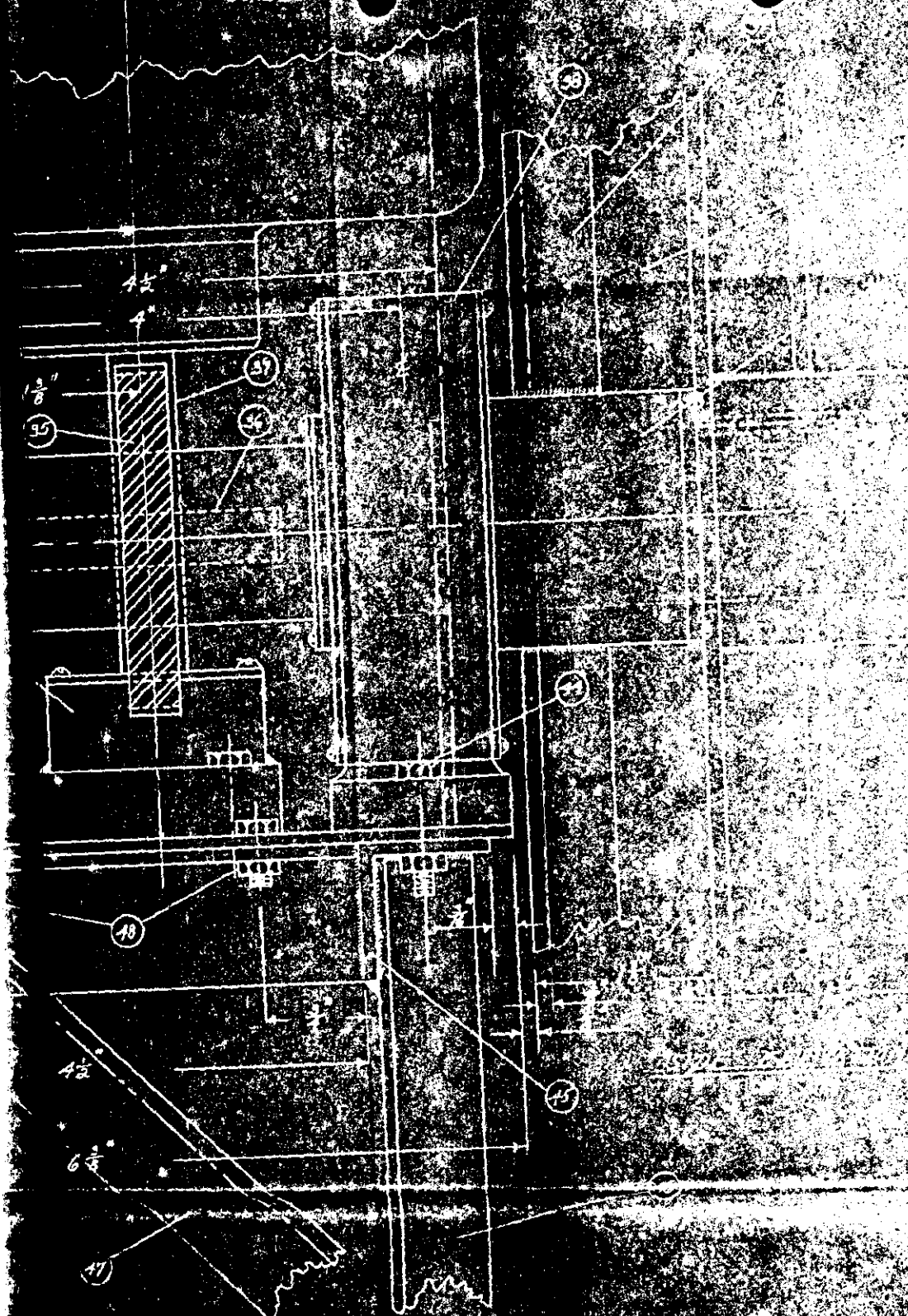
29. Top end of the solenoid's plunger as seen in Plan Perspective
30. Babbal Gear Works $\frac{1}{4}$ " I.D. x $\frac{3}{8}$ " O.D. x $\frac{3}{16}$ " Thk. Best-Bronze
Hub Ring
31. $\frac{1}{16}$ " x mild steel rod, welded as indicated into one leg
of the angle (E)
32. Induction Type Drive Motor (further specifications soon)
33. $\frac{1}{8}$ " x mild steel baseplate for the Drive Motor (see End
Elevation View)
34. $\frac{1}{4}$ " shaft size ball bearing pulley block
35. Babbal Gear Works 3" P.D., 50 tooth, L.H., 45° helix
 $\frac{3}{4}$ " face helical gear *
36. Babbal Gear Works 2.5" P.D., 50 tooth, L.H., 45° helix
 $\frac{3}{4}$ " face helical gear *
37. Drive Motor's output shaft
38. $1\frac{1}{4}$ " shaft size ball bearing pulley block
39. $\frac{3}{16}$ " x $\frac{1}{4}$ " x $\frac{1}{8}$ " aluminum angle spokes of Outer Drum L.H. End-
Ring
40. Outer Drum L.H. End-Ring
41. Hub of Outer Drum L.H. End-Ring
42. Hub of Inner Drum L.H. End-Ring
43. $\frac{3}{4}$ " x $\frac{3}{4}$ " x $\frac{1}{8}$ " aluminum angle spokes of Inner Drum L.H. End-
Ring

Oil Bath in which gears run is not shown here. See drawing #8

44. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " ^{nut} ~~nut~~ tying (53) to the members (45) & (51)
45. $1\frac{1}{2}$ " \times $1\frac{1}{2}$ " \times $\frac{1}{2}$ " structural steel angle top member of L.H. A-frame
46. $3\frac{1}{2}$ " \times $3\frac{1}{2}$ " \times $\frac{1}{2}$ " structural steel plate of the L.H. A-frame
47. $3\frac{1}{2}$ " \times $3\frac{1}{2}$ " \times $\frac{1}{2}$ " " " & joint member of the
Inverted combination (47) and (56)
48. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " ~~nut~~ nut tying (51) to (56) on the
far side of (51) rather than the side seen here
49. Outboard flange for the motor shaft
50. End plate flange (49), and on which (49) is mounted
51. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " mild steel baseplate for the Drive Assembly
52. The Drive Assembly Assembly
53. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " ~~nut~~ nut tying (31) to the End plate (50)
54. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " mild steel gusset plate. One at each end of
the End plate (50)
55. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " structural steel & welded to the End plate
(50) One at each end to stiffen (53)
56. $1\frac{1}{2}$ " \times $1\frac{1}{2}$ " \times $\frac{1}{2}$ " structural steel & welded horizontal member of the
Inverted combination (46) and (47)
57. $\frac{1}{2}$ " \times $\frac{1}{2}$ " \times $\frac{1}{2}$ " mild steel baseplate for Drive Assembly

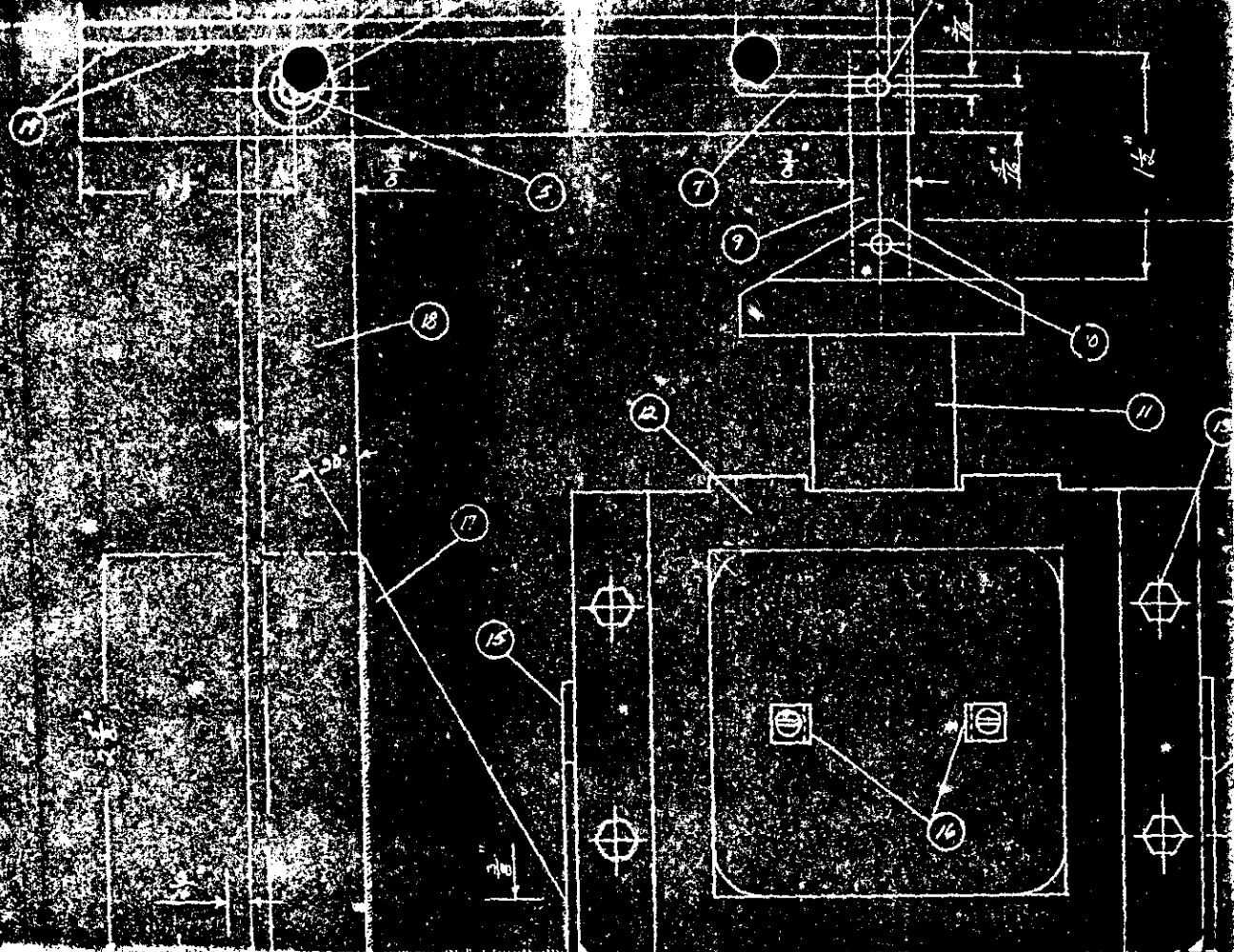
L.H. END OF ASSEMBLY

SCALE



END ELEVATION

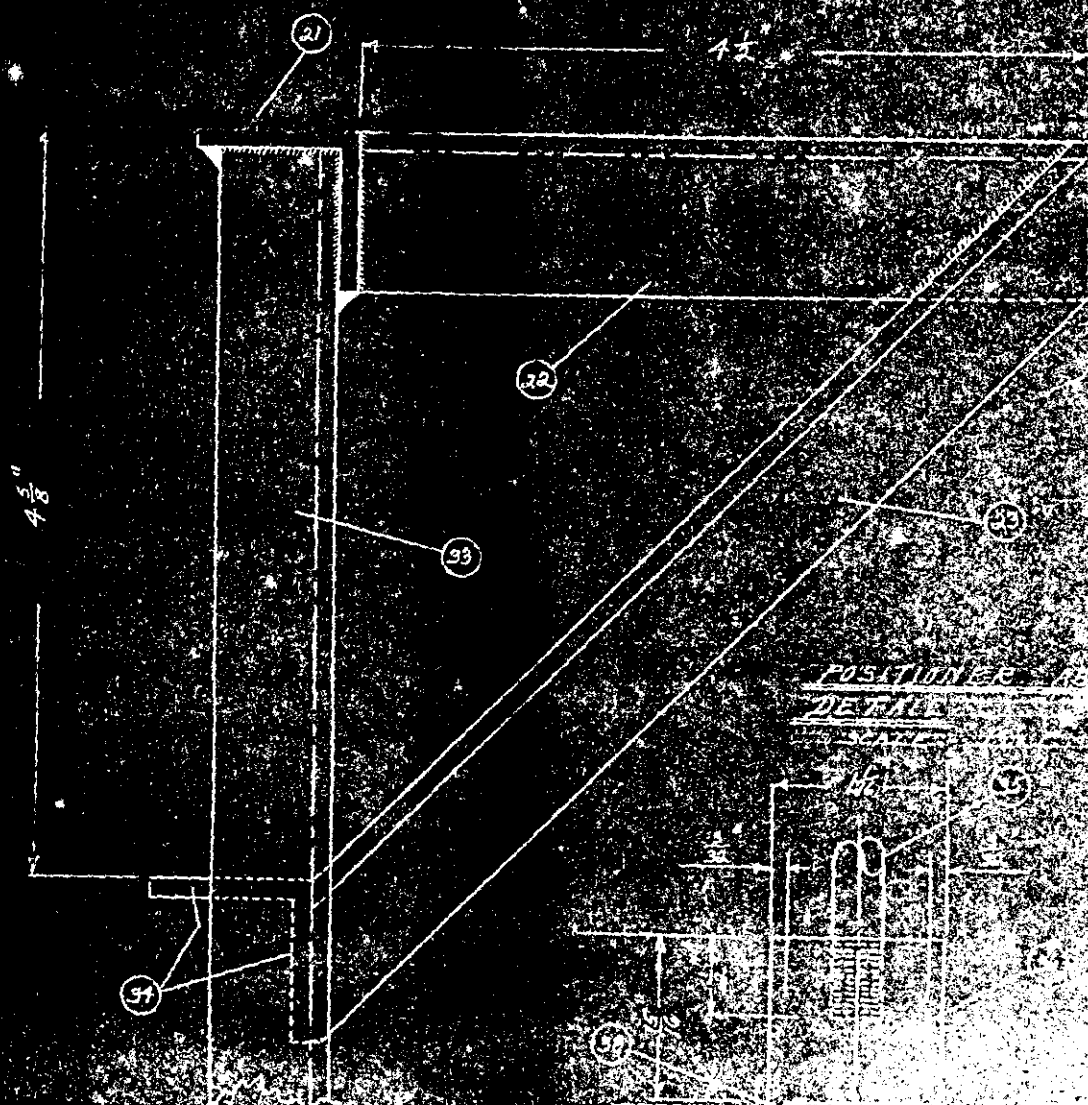




1. Mild Steel Cover-plate
2. $\frac{7}{16}$ " R. H. machine - 6 reg. on $1\frac{1}{2}$ " D.S.C.
3. S.A.E. 1020 steel housing, to be fabricated from $1\frac{5}{8}$ " o.d. $1\frac{1}{2}$ " I.D. Tube Stock
4. $\frac{1}{2}$ " shaft size Nace 1600 series, permanently lubed and sealed, ball bearing
5. Pad plate of $\frac{1}{4}$ " mild steel R
6. $\frac{1}{4}$ " & 1/8" holes for mounting of pad plate
7. Outboard bearing member of the Pad-plate
8. See Det. ②
9. Drill & tap for $\frac{1}{4}$ " cap screw to mount $1\frac{1}{2}$ " shaft size ball bearing yellow block
10. Horizontal principal centerline of $1\frac{1}{2}$ " shaft size ball bearing yellow block
1. Drill and tap for $\frac{1}{4}$ " Allen Rubber Det screw
- Shoulder against inner race of $1\frac{1}{2}$ " shaft size ball bearing
- to make keyway for $\frac{5}{16}$ " x $\frac{5}{16}$ " set screw connecting the driver against the Main Drive Shaft
- Keyway for $\frac{1}{2}$ " x $\frac{1}{2}$ " key connecting the sub member of the Outer Drive L.H. End-Ring to the Main Drive Shaft
- Shaft of $1\frac{1}{4}$ " o.d. x $\frac{3}{8}$ " I.D. Standard SAE 1020 Steel Tube Stock
1. Direction of Rotation of the Drive Assembly
1. L.H. End-Ring of the Outer Drive
10. Position "3"

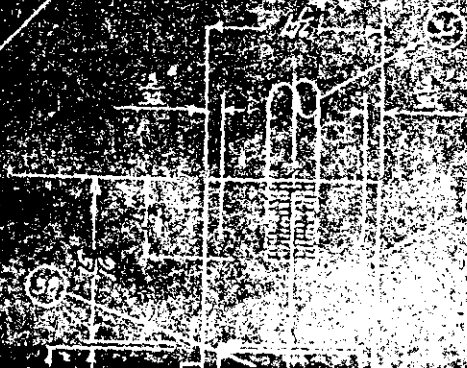
38. "Knob" portion of solenoid's plunger
39. Allen-Bradley, size #5, Wall Mounting Type, 110 v., 60 cycle, A.C. Bulletin 560 Solenoid
40. $\frac{1}{8}$ " ϕ mild steel gusset plate between ③ and vertical portion of frame
41. Cap screws and nuts tying mounting channel of solenoid to the bedplate member of the frame
42. Horizontal plate member of frame, $2\frac{1}{16}$ " \times $4\frac{1}{8}$ " \times $\frac{1}{8}$ "
43. Slot in ③ for plunger ④. Must be wide enough to accommodate "stop" portion of the plunger
44. Plunger (armature and thereof) of solenoid
45. Pole Faces of Electromagnet, against which ④ goes "home"
46. Mounting Wings on "stop" end of plunger
47. $\frac{1}{8}$ " ϕ shaft, press-fitted into drill holes in the Mounting Wings ④
48. $\frac{1}{4}$ " O.D. \times $\frac{1}{8}$ " I.D. steel tube spacers on both sides of spring member to prevent sideways motion of spring
49. Recoil spring (specifications soon)
50. $\frac{1}{4}$ " ϕ cap screw and nut anchoring the bottom end of the Recoil Spring ④
51. $\frac{5}{8}$ " O.D. \times $\frac{1}{4}$ " \pm I.D. ^{steel} tube stock welded to bedplate of frame
52. Nut member of ⑤

ITEM "FC"
SCALE: 1" = 1"



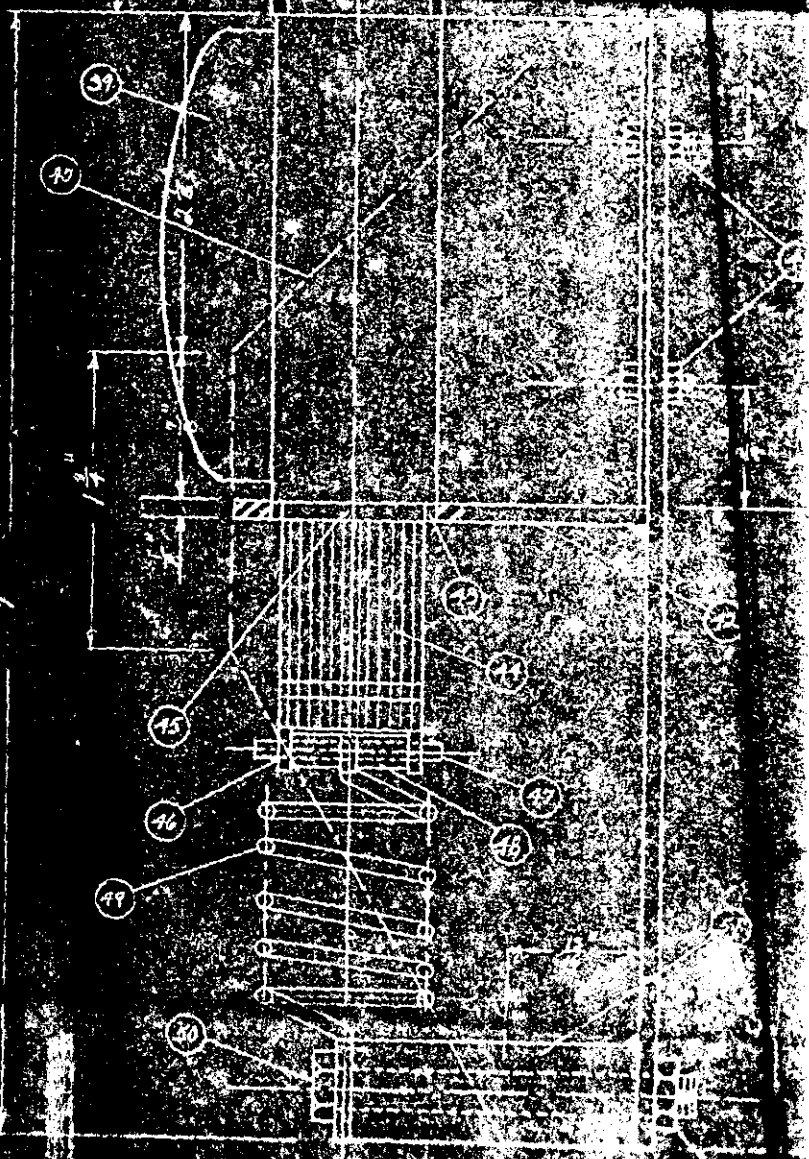
POSITIONER ASSEMBLY
DETAIL

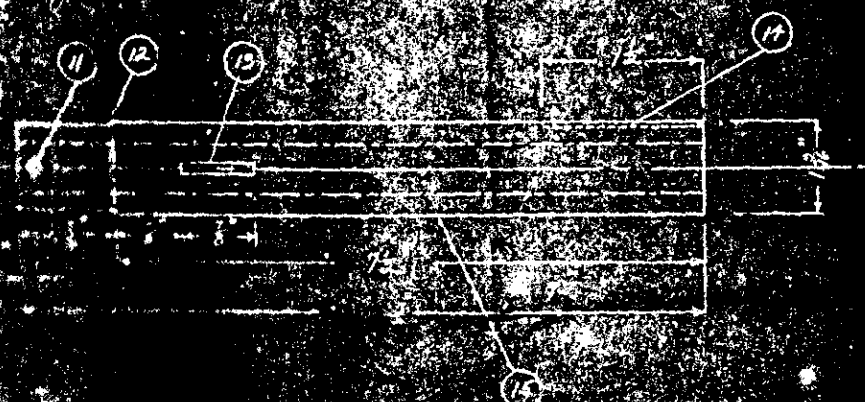
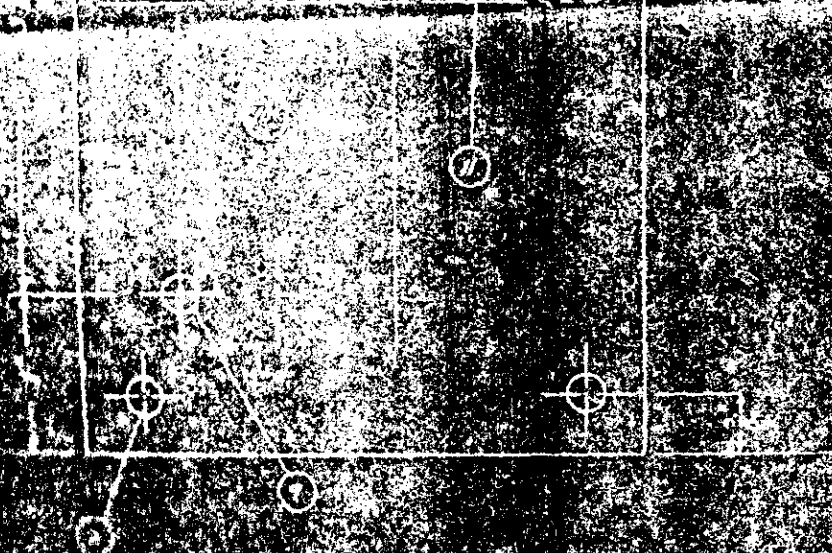
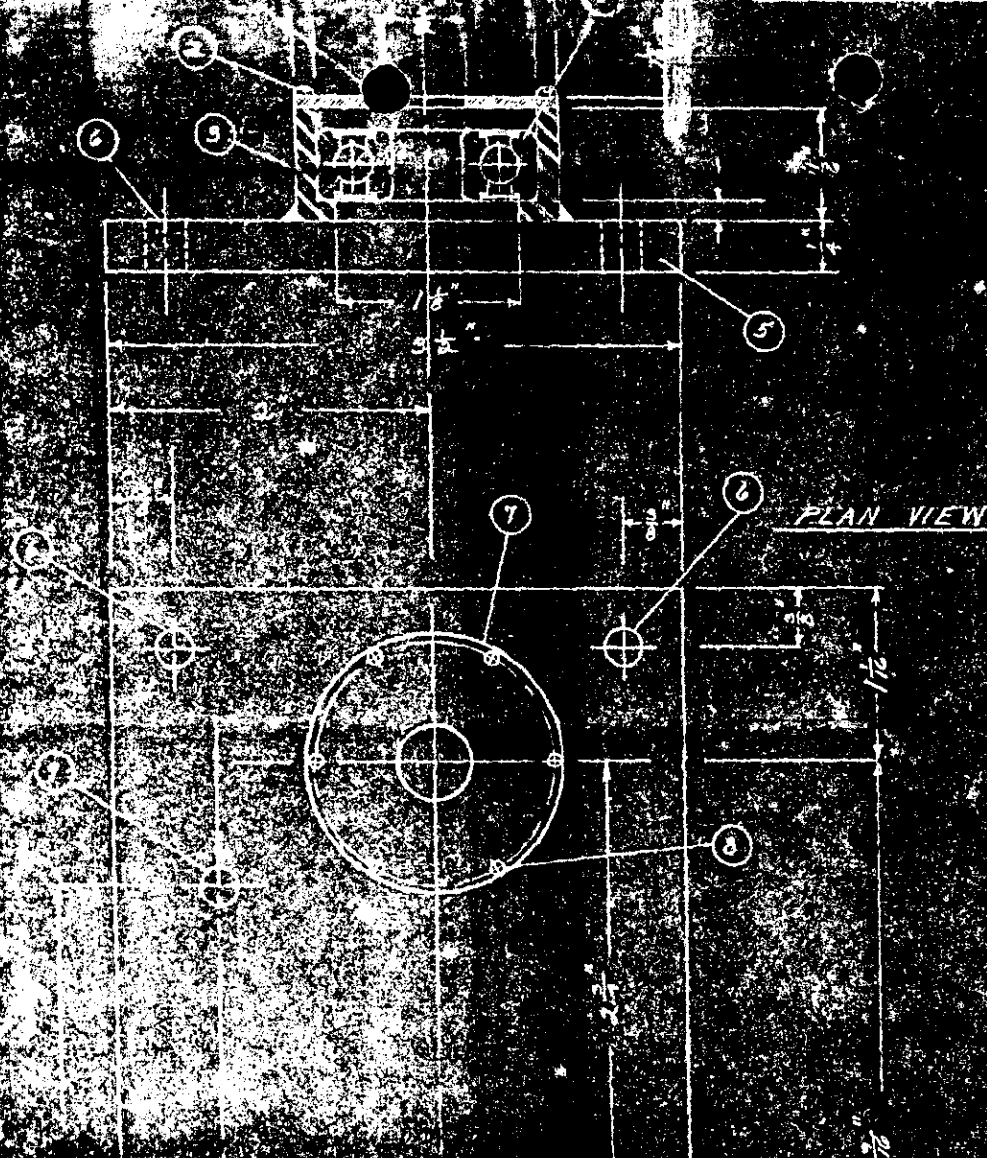
SCALE: 1" = 1"



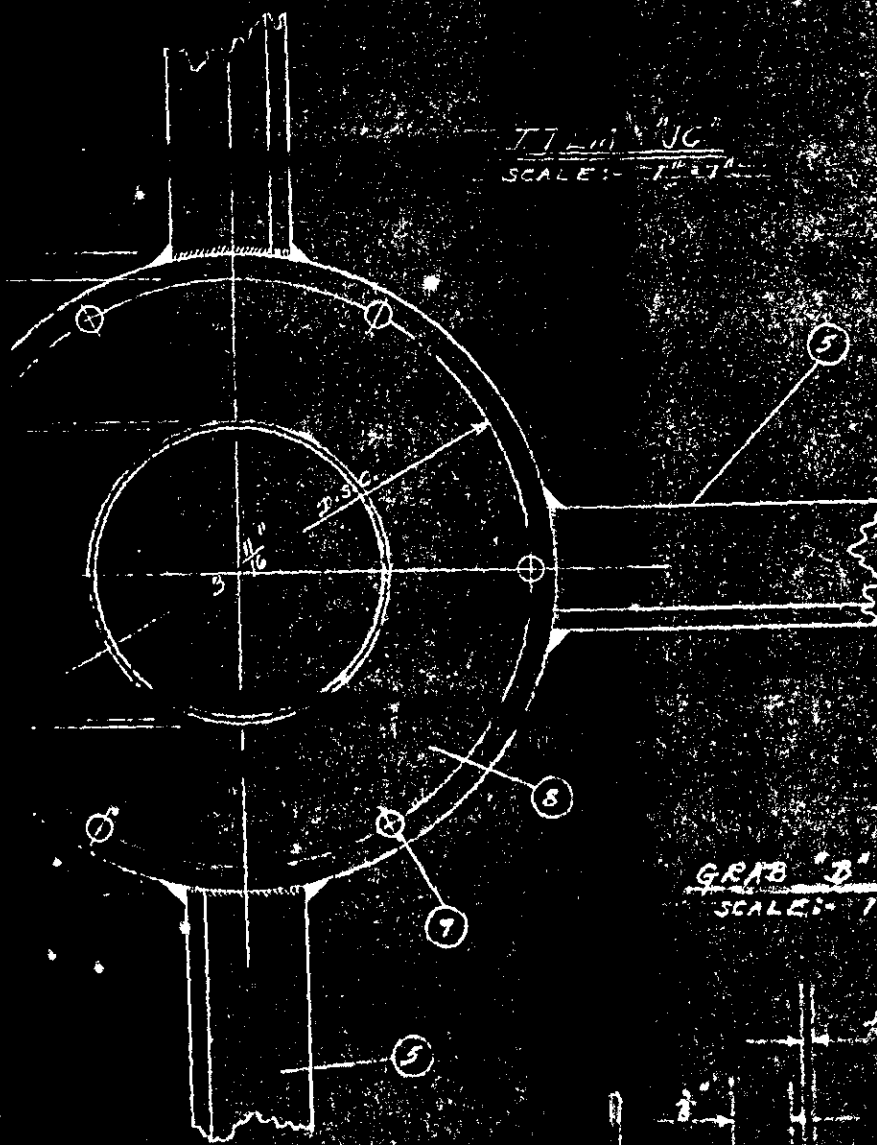
THE

THE MIRIASCOPE — FOR A
RECTANGULAR C.R. TUBE
V.D.S. 4.7 REVISED

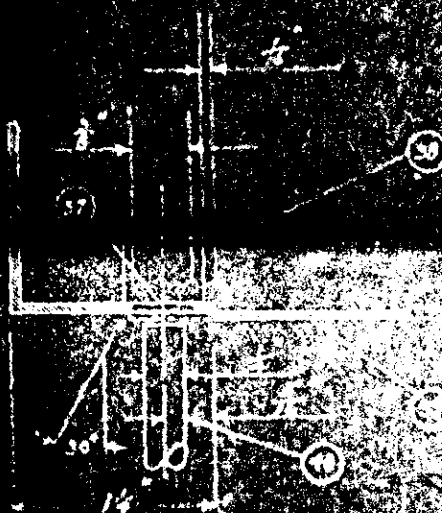




SCALE:- 1"=1'



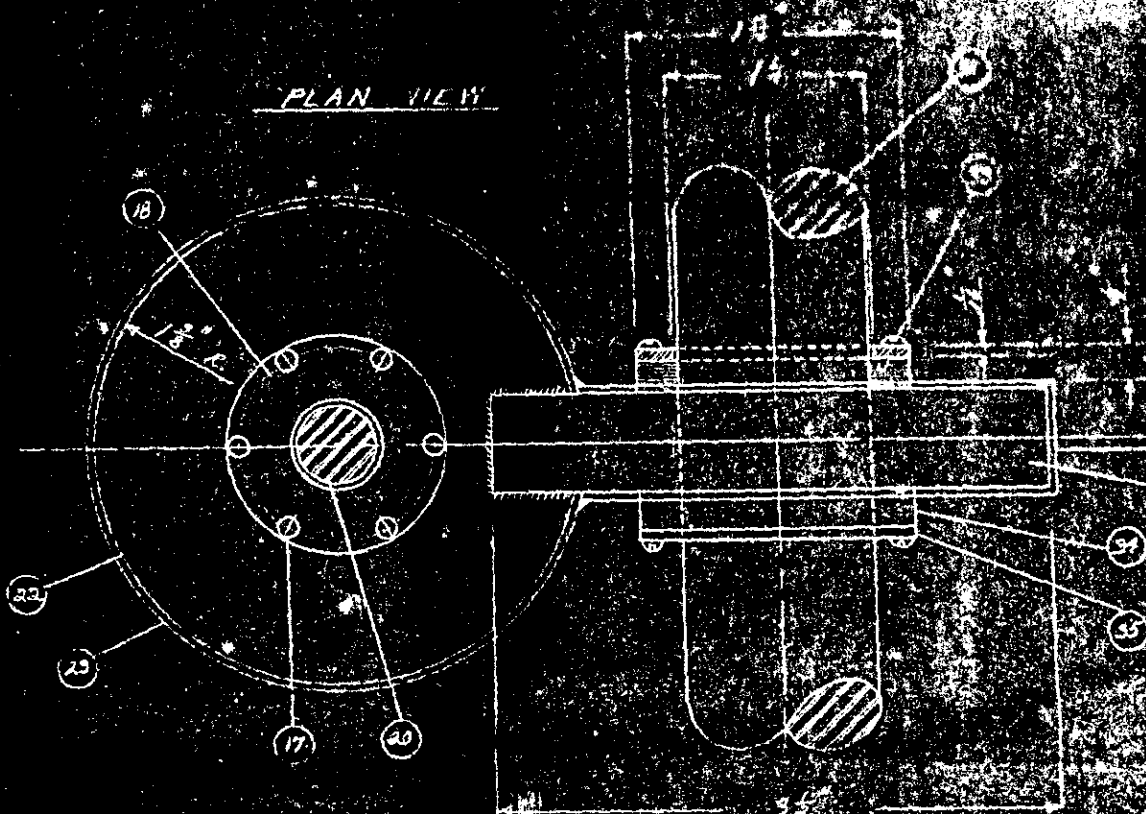
SCALE: 1" = 1'

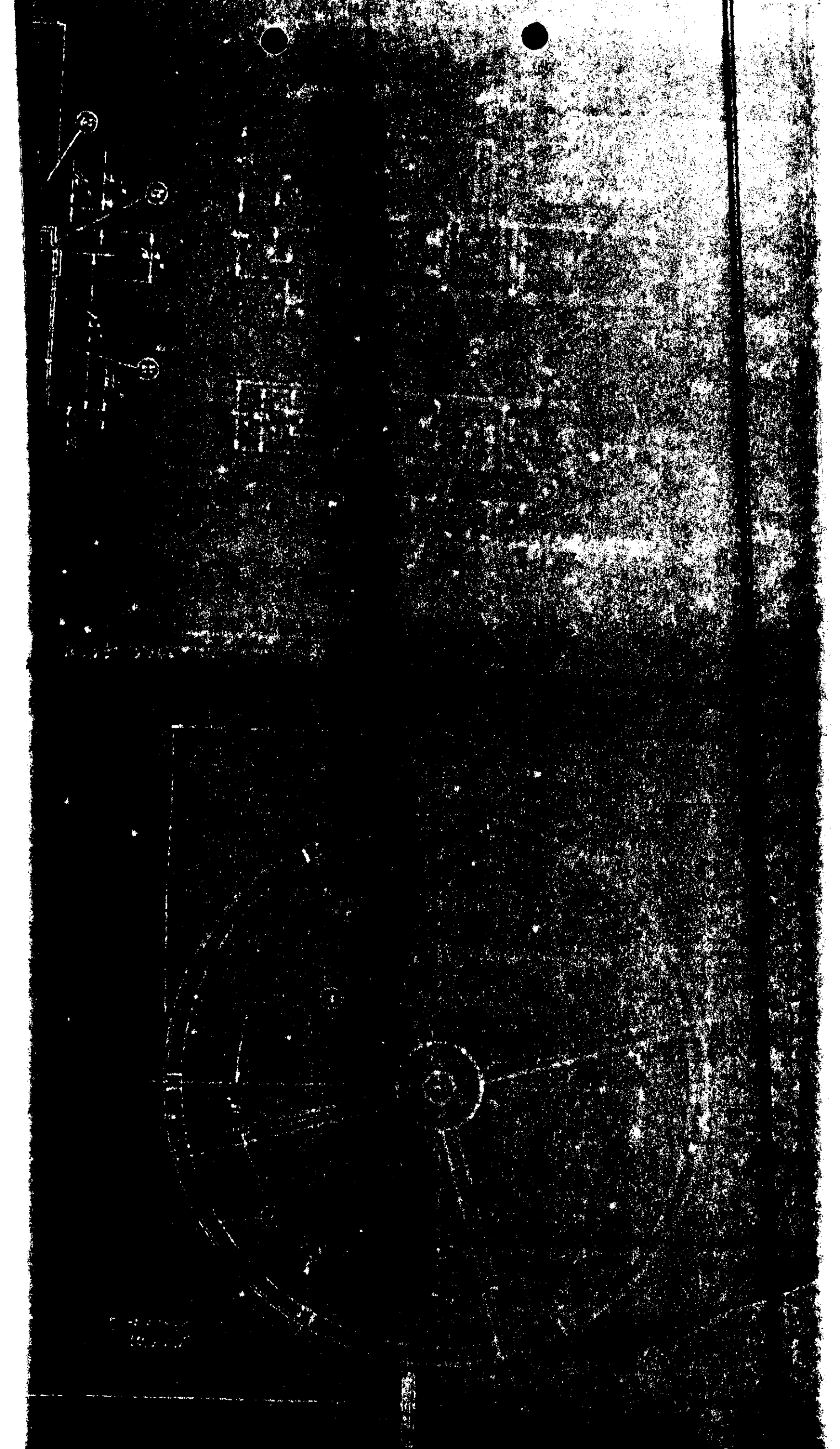


REVISED

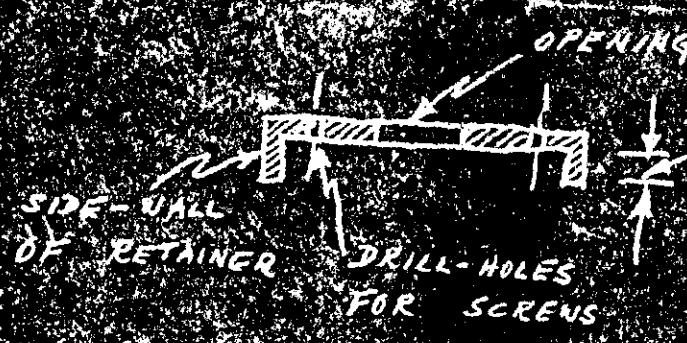
DE AIL

PLAN VIEW





1. Rem of $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$ aluminum angle
2. Hub inside of Inner Drum "End-Ring" (R.H.) see Item "18" & "19"
3. Flat plate to which the axle member of each "support member" is anchored. see Item "19" - 6 req. square-faced
4. Detail of the spoke-to-rim joint, see Item "13"
5. $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$ aluminum angle spoke
6. Aluminum Hub - Housing. Fabricate from 4" aluminum round stock, or 4" O.D. x 1 1/2" I.D. tube stock - if available
7. Two rollers 1000 x 1 1/2" shaft size permanently sealed and permanently-lubed ball bearing
8. Aluminum steel cover-plate
9. $\frac{1}{4} \times \frac{3}{4}$ by 1/2" hd. mech. screws - 6 req. on 3 1/8" disc
10. $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$ aluminum angle rim, see fig 1
11. ditto (5)
12. $\frac{1}{4} \times \frac{3}{4}$ by 1/2" by cap screw to nut - 2 req. per "support member"
13. Axle portion of "support member assembly" to be fabricated from mild steel bar stock (13) in particular, refers to the roller-bearing portion of the axle
14. Anchored portion of the axle member, see (13)
15. side-plate of $\frac{1}{8} \times \frac{1}{4} \times \frac{1}{8}$ plates welded to both legs of the rim angle as indicated
16. $\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$ aluminum angle rim
17. $\frac{1}{4} \times \frac{3}{4}$ by 1/2" hd. mech. screws - 6 req. threading into properly drilled holes in the top of (25)
18. Retainer Ring, of mild steel &c. A retainer with a side-wall to restrain the outward "creep" of the felt rings as they are compressed around, of course, the preferable steel a Retainer would be as shown below:

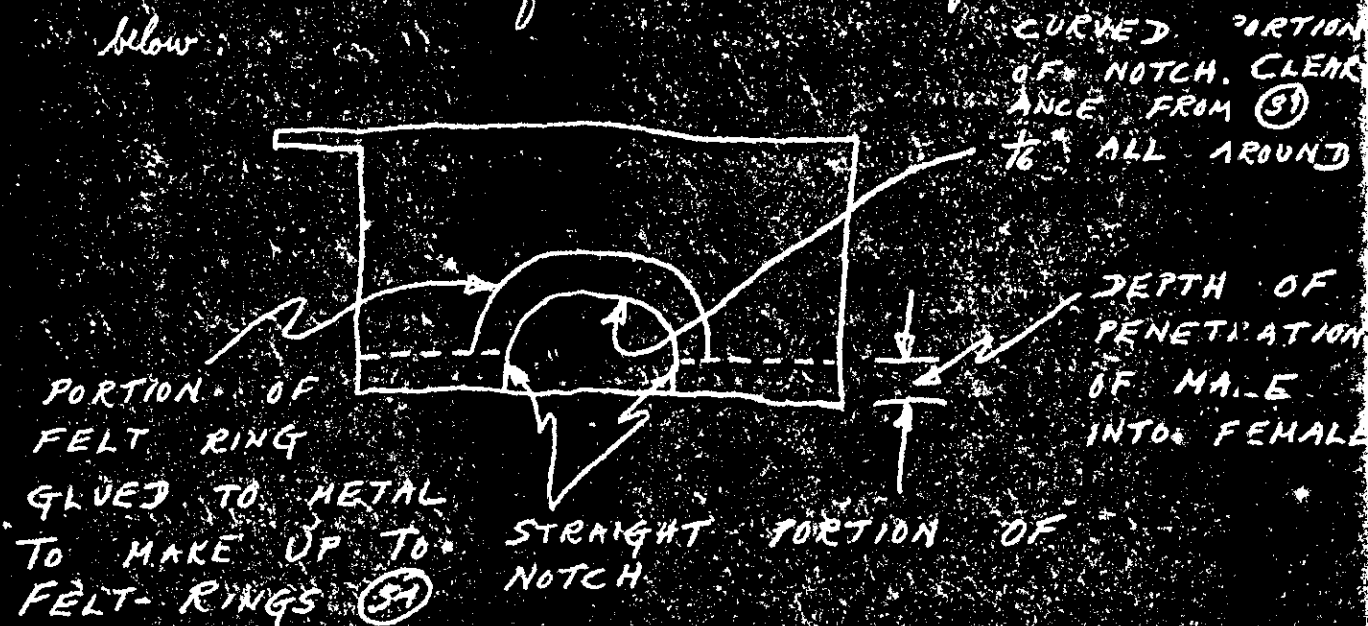


THIS HEIGHT SUFFICIENT
TO CONTAIN A ^{APPROX.} 50% OF
THE UNCOMPRESSED
FELT-RINGS HEIGHT
PERMITTING AN ^{ULTIMATE} COMPRES-
SION OF THE FELT RING
TO APPROX. 50% OF
THEIR STARTING HEIGHT

19. $\frac{1}{8}$ " thick, medium soft felt ring. 2 may be used to allow for a greater "area-of-contact" with the shaft.
20. Output shaft of the Drive Motor
21. Keyway for $\frac{1}{8}$ " x $\frac{3}{16}$ " key between driving gear and the output shaft of the Drive Motor
22. 21 gage sheet steel, galvanized, metal. Member (22), which is formed as an approximately 360° surface-of-revolution of a line about the ϕ of the Motor-shaft, together with (30) forms the top half of the bath. The bottom edge of the 'top half' of the bath forms the male member of the joint between the 'top' and 'bottom' halves of the bath.
23. 21 gage sheet steel, galvanized. Member (23), which is of the same shape as (22) for the most part, together with member (32) form the 'bottom half' of the bath. The top edge of (23) and (32) is flared to form the 'female member' of the joint between the 'top' and 'bottom' halves.
4. 50-Tooth, $\frac{5}{8}$ " face, 45° helix angle, 2.5" P.D., L.H., helical gear, steel
5. Housing for Harlock Kluge. To be formed from $1\frac{3}{8}$ " O.D. x $\frac{7}{16}$ " I.D. seamless S.A.E. 1020 steel tube-stock, and braced

or welded to member ②⑤.

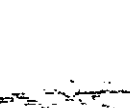
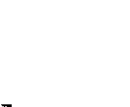
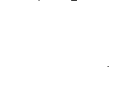
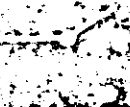
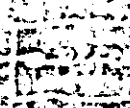
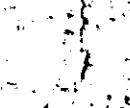
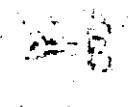
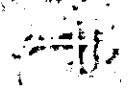
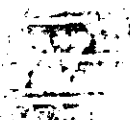
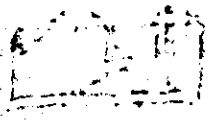
26. $\frac{1}{16}$ " \times $\frac{3}{16}$ " lg. rd. hd. mach. screws - 6 req. on $1\frac{3}{4}$ " D.S.C.
27. Garlock $\frac{1}{4}$ " \times $\frac{1}{4}$ " double- lip Klegum heater or felt seal
28. The end of shaft enters the Outboard Bearing on the Pad-plate
29. Key between driven gear and the Main Drive Shaft. Key: $\frac{3}{16}$ " \times $\frac{3}{16}$ "
30. Member ③① is notched for the Main Drive Shaft as indicated below:



31. Main Drive Shaft. See DWG. # 7 REVISED. Though shown here as a solid shaft, the Main Drive Shaft is hollow in fact.
32. Member ③② is correspondingly notched for the Main Drive Shaft as in member 30, and a portion of a felt ring is similarly glued beneath the flange to make-up to the felt-rings ③④.
33. $\frac{1}{16}$ " \times $\frac{3}{8}$ " lg. rd. head machine screws to draw-up on Kevlar Rings ③⑤.
34. Medium soft felt rings, each $\frac{1}{8}$ " thk. or one $\frac{1}{4}$ " thk, making-up to glued portions of rings above noted in ③① and beneath the flanged portion of noted in ③②.

35. Retainer Ring of sheet steel — 2 req., 1 each side of (30)
36. $1\frac{1}{4}'' \times 1\frac{1}{4}'' \times \frac{1}{16}''$ Alk. aluminum angle riv of Out. Drum End-Ring (L.H.).
37. ~~Drum~~ Slide member of Grab "B"
38. Departure block of Grab "B"
39. Plastic Drum (NOTE:— In the immediate vicinity of the hole (37), in the longitudinal as well as girth sections, a general clearance for the hole is used. The dotted extension of (39) indicates the normal overlap of (39) over (36).
40. The plunger member of Positioner "B" which consists simply of a square-finished drill-rod instead of the ball-point assembly used in Positioner "A"

NOTE:— The normal oil level in the Oil Bath is indicated by the horizontal discontinuous line across the bottom of (32).



1951

1951

1951

1951

1951

1951

1951

1951

1951

1951

1951

1951

1951

1951

NOTES ON DWG.

9

Since Pages 112-117 and Pages 201-210 were written, the following changes have been made in Page #9:- a) C16 has been equipped with 2 N.C. contacts instead of one N.C. set; b) has been installed in the circuit; and (c), C18 has been installed in the circuit.

The inter-act of N.C. load contacts on C16 provides for the disengagement of C17 immediately after C16 engages. Thus, soon after C17 fails to introduce a Time-Delay between the achievement of black-and-white alignment between the two Prisms and the disengagement of Positioner the engagement of C16 leads not only to the disengagement of C18, but to the disengagement of C17's operating coil as well. The no member of the black-and-white alignment section of the mechanism functioning during black-and-white viewing.

The purposes served by C17 are commented on on Page 215 of the enclosed. [NOTE:- On Page 205, C17 is given as C18. Note the change in legend]. Also please read Page 204 in the connection.

The purposes served by C18 are commented on on Page 115 of the enclosed. The method of guarding against the hazard raised Note on Page 115 is inadequate and incorrect. The action performed by C18 is positive, and the setting of the Drive Motor into regular color-viewing service definitely avoids the tripping of C18 by the plunger member of Positioner 'H', and thus guarantees that the plunger pin is withdrawn from Limit 'B' when the Drive Motor is set into regular color-viewing service.

(in continuation)

onto the departure block of Grab "B"; (b) a gliding of the latch-pawl down the slope of the departure block; and, (c), in consequence of (c), a return of CS's indicator to its normal position.

With the return of CS's actuator to its normal position, a signal would be caused to course from phase supply across the normally-closed set of contacts of CS, and then across a normally-open set of contacts in the still-engaged relay C9, to one of the normally-open sets of contacts of C14. X

C14, it will be recalled like C13, remains engaged as long as C2 is in its "color" position and C15 is not engaged. Therefore, the signal originating at the normally-closed set of CS's contacts is relayed across the indicated normally-open set of contacts in the now-engaged C14 to pass across a normally-open set of load contacts in the now-engaged C11 and appear finally at the upstream-side of the normally-closed set of auxiliary contacts of C11. Here, the signal results in the engagement of C11.

The engagement of C11, by the closing of its normally-open ~~load~~ load contacts, opens a path for a succeeding signal from the normally-open set of contacts in CS to be applied to the normally-open set of auxiliary contacts in C12. Thus, when I run #2, during the completion of its hook which is initiated when C12 engages, causes the latch-pawl to mount the approach block of Grab "A". The actuator of CS is tripped and a signal is caused to course from the downstream side of the normally-open contact of CS across the normally-open set of load contacts in the still-engaged C9, and then across a normally-open set of load contacts in the still-engaged C9, to the upstream side of one of the normally-open sets of contacts of the conventional relay, C14. Since C14 is still engaged, this signal is then relayed across a normally-open set of load contacts in C11 to wind up ultimately at the upstream-side of the normally-open set of auxiliary contacts of C12. In application of the signal to the mentioned set of auxiliary contacts causes an energizing of the disengaging section of the operating coil of C12, a resultant disengagement of C12. Accordingly, the power signal to the drive-motor is interrupted, and, in net effect, the motor is disengaged just as the latch-pawl mounts the ~~off~~ slope of the approach block of Grab "A". The engagement of the latch-pawl in Grab "A" a grab shot is

then accomplished on the basis of the residual momentum of Drum #2

SENDING THE COLOR-VIEWING-ALIGNED DRUMS INTO ACTION:-

Once the latch-pawl drops into Grab "A"'s slot, the actuator member of C5 returns to its normal position, and, with C12 in its now-disengaged position and C11 in its ^{still-}engaged position, a path is opened for a signal from the downstream side of the normally-closed set of contacts of C5 to the operating coil normally-closed set of auxiliary contacts of the mechanically-held relay C15. The application of the mentioned signal to the normally-closed set of auxiliary contacts of C15 leads to the engagement of C15. The signal which accomplishes this task proceeds from the downstream side of the normally-closed contacts of C5 across a set of normally-open contacts in the still-engaged relay C9 to the upstream side of a normally-open set of contacts in the conventional relay C14. From this point, it travels across the mentioned set of contacts in the ^{now}still-engaged C14 to a normally-closed ^{closed} set of contacts in the ^{now}disengaged mechanically-held relay C12, from which point it is relayed to a normally-open set of load contacts in the still-engaged C11. The still-engaged C11 permits the mentioned normally-open set of load contacts to convey the thus-relayed signal to the upstream side of the normally-open set of auxiliary contacts of the mechanically-held relay C15. As indicated above, the eventual travel of the signal to ^{the} normally-closed set of auxiliary contacts of C15 leads to the energizing of the engaging section of the operating coil of C15, and hence to the engagement of C15.

For its part, the thus-accomplished engagement of the mechanically-held relay C15 leads to:-

- a) the application of a maintained and continuous energizing signal to the Drive Motor
- b) the discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14
- c) the sending out of a "disconnect signal" to C9 and C7

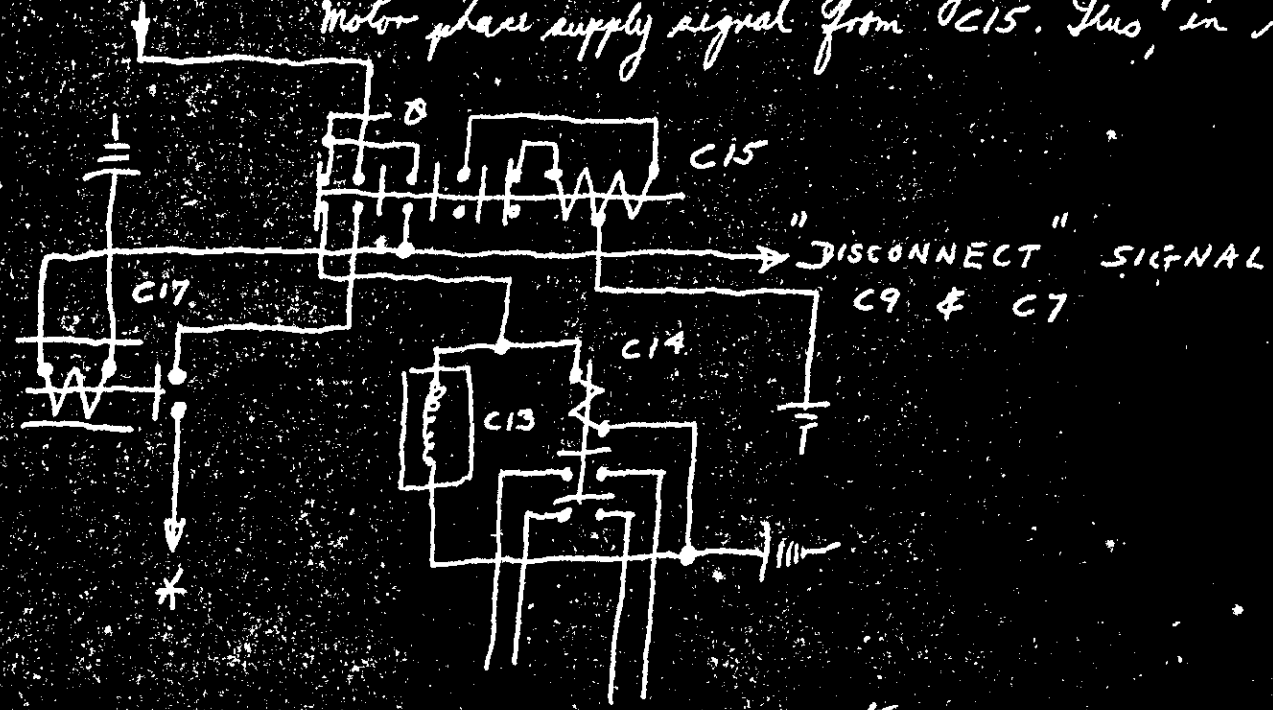
The discontinuation of phase supply to the solenoid of Positioner "B" and the conventional relay C14 according to (b) above takes place via the opening of the normally-closed set of load contacts in C15 when C15 is engaged. The discontinuation of phase supply to C13, the solenoid member of Positioner "B", means the retraction of the plunger-member of Positioner "B" from the drill-hole member of Grab "B". This retraction of the plunger-member (see Diag. #9) takes place under the action of the recoil spring member of the Positioner assembly. The retraction of the plunger-member of Positioner "B" from the drill-hole member of Grab "B" clears the impediment to the Drum Assembly's going into action which the energized Positioner constitutes. The simultaneous discontinuation of phase supply to ~~Positioner "B"~~ the conventional relay C14 means the de-energizing of C14, and the breaking of the paths whereby the 'activating' signals for C11 and C12 are transmitted.

The application of a maintained and continuous energizing signal to the Drive Motor according to Item (a) above is accomplished by the 'making', or closing, of a normally-open set of load contacts in C15 when C15 engages. As noted above, since the plunger-member of Positioner "B" is withdrawn from the drill-hole member of Grab "B" simultaneously with the application of the energizing signal to the Drive Motor, both conditions for the sending of the Drum Assembly into action are accomplished with the engagement of C15:-

1. the plunger-member of Positioner "B" as a holding agency against rotation of the Drum Assembly is removed
- and
2. the ^{continuous} power supply for the Drive Motor which is required for its operation in color-viewing is supplied.

NOTE:

The simultaneity of action which C15 establishes between retraction of the plunger of C13 and the energizing of the Drive Motor raises the question as to whether slowness of the recoil action of plunger assembly could result in a jamming of the plunger in the drill of Grab "B" and a possible consequent stalling of motor. To forestall such an eventuality, it may be desirable to place a time-delay relay in the path of motor phase supply signal from C15. Thus, in the



shown below, the on-delay timing relay C17 would delay the application of the energizing signal to the Drive Motor for a sufficient period of time to guarantee the retraction of Positioner "B"'s plunger from the drill-hole of Grab

thereby eliminating of questions of jamming of the plungers or stalling of the motor.

Now, let us return Item (C) above, namely the 'disconnect' signal to C7 and C9. [NOTE:- Observe that in ^{the} sketch given above a 'tap' off the signal to C7 and C9 is used to activate the on-delay timing relay C17]. By its very nature, the 'disconnect' signal to C7 and C9 is a 'clear-the-board' signal which readies the "black-and-white alignment" section of the control circuit for its next call to action. This 'disconnect' or 'clear-the-board' signal is accomplished via the closing of a normally-open set of load contacts in C15 when C15 is energized.

In connection with the 'clear-the-board' signal from C15 to C7 and C9, it might be well to point out a 'clear-the-board' signal for the case of the mechanically-held relay C16 is provided via a 'tap' from the color-position contact of the 2-position selector switch C2. Thus when the 2-position selector switch C2 is turned to its color-position, C16 is 'cleared' for its next service in the functioning of the "black-and-white alignment" section of the control circuit. No activation of any portion of the "black-and-white alignment" section of the control circuit follows from this since the turning of the selector switch C2 to its color-position perforce removes phase supply from the "black-and-white alignment" section of the circuit.

Finally, it should be observed that the 'clear-the-board' signal for the "color-alignment" section of the circuit (in particular for the C15 and C11 components thereof) is obtained by a 'tap' from the black-and-white position of the 2-position selector switch C2. Thus, simultaneously with the next calling of the 'black-and-white' alignment section of the circuit into action.

The rotor-alignment section of the control circuit is readied for its next call to duty.

ERRATA, ADDENDA, & COMMENTS

IN RE: PAGE 1-27, THE MIRIASCOPE
PRINCIPAL DIFFERENCES BETWEEN THE
ORIGINALLY SUBMITTED DESIGN & THE
DESIGN SET FORTH ON PAGES DWGS #1-

9

The original outlines of the Miriascope were set forth in a series of Preliminary Sketches numbering 19, sketches of which the last was devoted to a proposed Control Circuit. The balance was devoted to detail aspects of the design. The original design, its objectives, its fundamental principles, and its detail aspects were discussed in a 27-page document beginning with an untitled communication dated 8/6/51. Later, a series of 9 formal drawings were submitted which in many aspects differed from the originally-submitted drawings (Sketchs 1 thru 19). The differences are for the most part in detail aspects of the design rather than ^{in fundamental} principles.

NOTE:

In the series of drawings numbered #1-9, it will be found that successive drawings in dealing with any ^{one} detail may differ. Such differences when they occur between succeeding drawings are intentional, and are meant to convey revisions of the design as given on previous drawings. Therefore, any and all conflicts between successive drawings are to be construed in favor of the drawing bearing the most recent series number.

IMPORTANT:

Positioner "A" via a normally-closed set of load contacts in the mechanically-held relay C16; while, on Ltr. #19, the same signal is passed directly from the mentioned set of load contacts in C3 to C8 and C6 without any interposed relay effects;

- b) on Dwg. #9, C15 is indicated as a mechanically-held relay; while on Ltr. #19 it appears as a conventional relay;
- c) on Dwg. #7, the mechanically-held relay C9 appears as a 3 N.O. - 1 N.C. unit, the mechanically-held relay C10 as a 2 N.O. - 1 N.C. unit, and the mechanically-held relay C7 as a 2 N.O. - 1 N.C. unit. On Ltr. Ltr 19, C9 appeared as a 2 N.O. - 2 N.C. unit, C10 as a 2 N.O. unit, and C7 as 1 N.O. - 1 N.C. unit;

and,

- d) in correspondence to the above-mentioned equipment changes, certain details of the functional patterns have been altered.

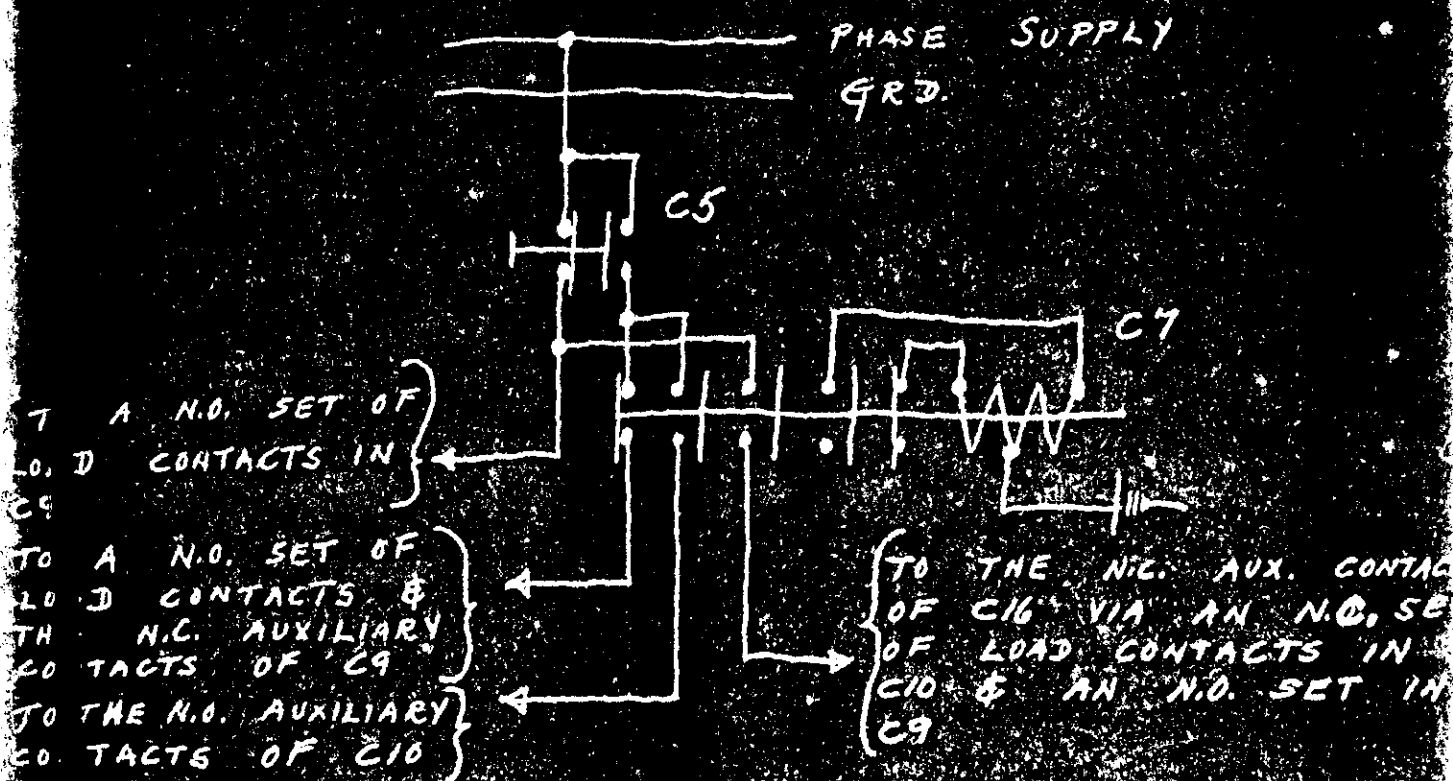
The addition of C16 to the circuit as per (a) has been for the purpose of providing for the disengagement of C6 and C8 after the re-alignment of the Oruma for "black-and-white" viewing has been achieved. By so doing, any A.C. chatter associated with the continued engagement of C6 [the solenoid member of Positioner "A"] and C8 [the on-delay timing relay] is eliminated; and, further, any disturbing effects due to ~~the~~ a continued feeding of these equipment items is eliminated.

Associated with the addition of C16 to the "black-and-white" alignment section of the control circuit are the above-noted changes in the specifications for C10 and C7 and, in part, the changes in the specifications for C9. From a reading of pages 101-111, it will be observed that:-

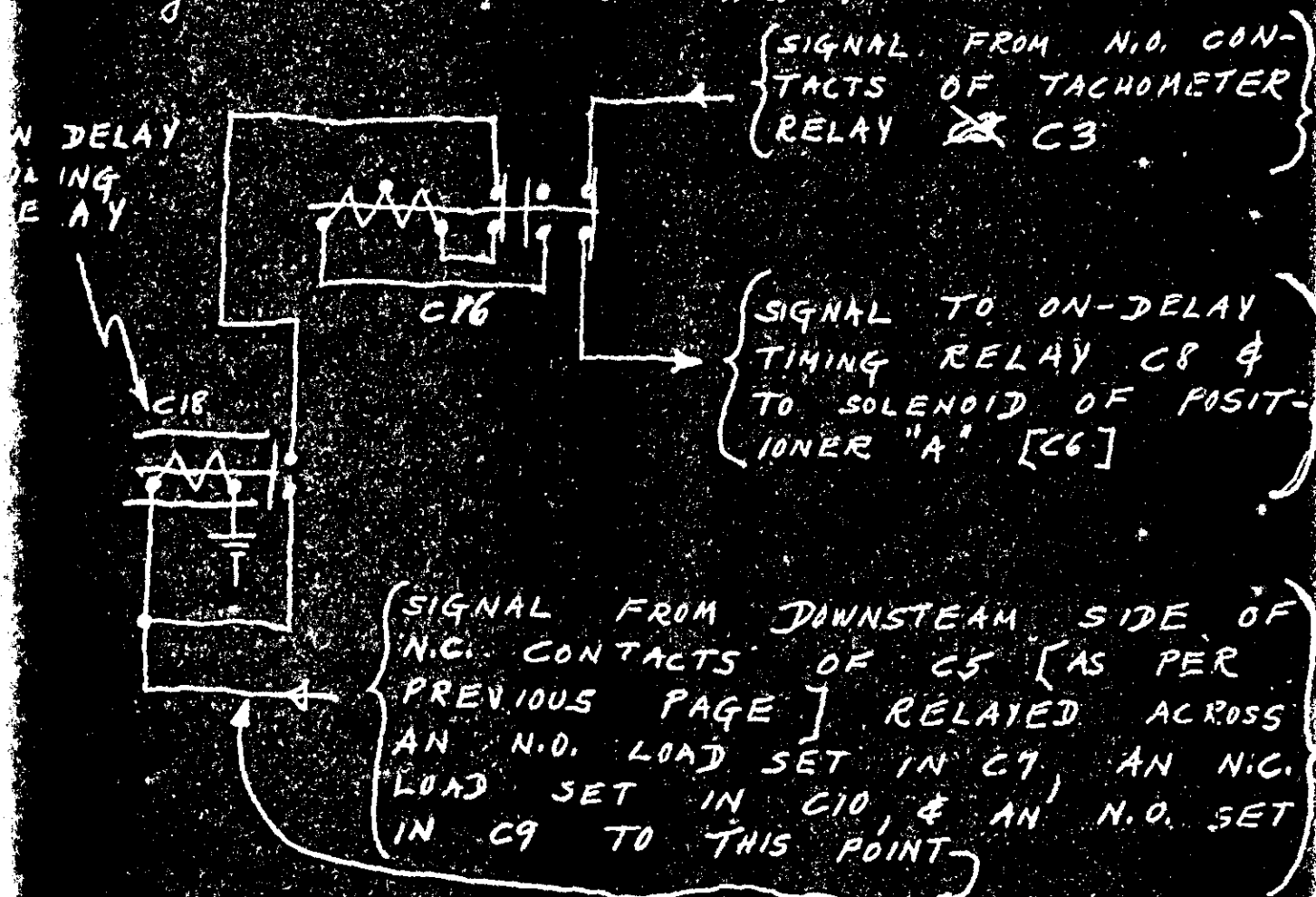
- A. when the arresting of the Drum Assembly and the disengagement of the latch - pawl from Knob "A" is accomplished as the first step in the re-alignment of the two drums for black-and-white viewing, C9 is ~~then~~ engaged;
- B. after C9 is engaged following the events mentioned in (A), C10 is engaged;
- and,
- C. after C10 is engaged as a consequence of the engagement of C9 and after the ensuing motivation of Drum #2 alone results in the return of the latch - pawl to a position where it no longer trips the actuator of the Permit Limit Switch, C7 is engaged.

Studying the Microscope Control Circuit as given on Dwg. #9, it will be seen that when C7 and C9 are engaged, and C10 is disengaged, a path is opened for a signal starting from p'ase supply, and, after transmission ~~to~~ over an appropriate set of contacts in each of the mentioned relays, terminating at the normally-closed set of auxiliary contacts of the mechanically-held relay C16. The necessary conditions for the opened path, namely that C7 and C9 be engaged while C10 be disengaged, are fulfilled as a sequel to them (C) above. From pages 101-111, it will be found that after C7 is engaged as per (C) above, C10's disengagement is made responsive to a signal starting from the normally-open set of contacts in the limit switch C5. This signal which is transmitted across a normally-open set of load contacts in C9 to the normally-open set of auxiliary contacts in C10 occurs when the latch pawl of Drum #2 has already mounted the approach block of Knob "B" during the Drum's travel towards the black-and-white viewing, required position. It will also be found in the "Description", page 101-111, that the mounting of the approach block of Knob "B" by the latch-pawl member of Drum #2 is followed shortly thereafter by a blocking of the latch-pawl

in the grab-slot of Knob "B", signifying the arrival of Drum #2 at a position which is consistent with a proper alignment of the clear slot of Drum #2 with a clear slot in Drum #1 for the purpose of black-and-white viewing. Thus, since the signal which which engages C16 (and consequently disengages C6 [the solenoid of Positioner "A"]) occurs when the locking action between the two Drums is impending rather than completed, it may be argued that a possibility exists that the ultimate absorbing of the flywheel energy of Drum #2 and the rotor of the Drive Motor could act to rotate the Drum Assembly's position past the 'window' in the cabinet. To obviate this possibility, it would be possible practical to draw the prime signal for the disengagement of C16 from the downstream side of the normally-closed set of contacts of C5 instead of from phase supply as now indicated on Dwg. #9. This scheme is illustrated below:-



By the scheme illustrated above, the signal engaging C16, and consequently disengaging the Drum Assembly-rotating action of the plunger of Positioner "A", would await the completion of the locking-action between the Drums. This means as well that the newly-aligned Drums would be prevented from slipping past the 'window' in the cabinet. Any further assurance that the newly-aligned Drums should not slip past the 'window' would be obtained from introducing a time-delay factor between the completion of the afore-mentioned locking-action and the retraction of the Plunger of Positioner "A" from the drill-hole of Grab "A". If this were done, then a way of doing it would be as indicated below:-



Of the matter raised on page 202, only one has thus far not been discussed, and this is Item (b) dealing with relay C15. On Skt. #19, as is recalled in Item (b), C15 was indicated as a conventional relay; while on Diag. #9, it appears as a mechanically-held relay. Two reasons underlie the change, of which the first is the more important:-

1. Skt. #19 indicates that the prime signal for the engaging of C15 originates at the N.C. contacts of C5, is transmitted across an N.O. load set in C9 to an N.O. set in C14, is then transmitted across an N.O. set in C14 to an N.C. load set in C12 to an N.O. set in C11, and, finally, is then applied to the phase side of the operating coil of the conventional relay C15. This would demand that C9 be in its engaged position, ^{that} C14 be engaged, that C12 be disengaged, and that C11 be engaged for C15 to be continuously engaged during color-viewing. However, since ~~the~~ the engagement of C14 is dependent on C15 being disengaged, it follows that the engagement of C15 would lead to the disengagement of C14, which would in turn lead to the secondary disengagement of C15 — and ultimately to a chattering relationship between C14 and C15. This is the prime reason for the change shown on Diag. #9;
2. The second reason lies in the inadvisability of C15, or any other relay, being continuously energized during the operation of the TV circuit, since A.C. chatter and electrical disturbances to the operation of the TV circuit are possible. By making C15, a mechanically-held relay the permanent engagement of C15 prior to

(29)

the disengagement of C14 is secured; and, once, the engagement of C15 is reestablished, it holds that engagement without any further feed of power. The latter fact satisfies the above-mentioned conditions that no member of the switching circuit be capable of "chattering" or demand a continued feed of power during any viewing cycle, other than — possibly — the Tachometer Relay.

As C15 is now specified, its engagement follows the completion of the drum re-alignment action, for the engagement signal is transmitted along the following path:—

- a) the signal originates at the downstream side of the N.C. contacts of C5, which means that the latch-pawl of Drum #2 must be in its "low" position;
- b) the signal as of (a) is relayed across a normally-open load set in C9, which means that C9 must be engaged — and this condition is satisfied since C9's position is reversed only after C15 is engaged;
- c) the signal as of (b) is applied from the downstream side of the N.O. load set in C9 to the upstream side of an N.O. set in C14, which means that C14 must be engaged for the further relaying of the signal — and this is satisfied since C14 is engaged as long as C2 is in its rotor position and C15 is disengaged;
- d) the signal as of (c) is applied from the downstream side of the N.O. set in C14 to the upstream side of an N.C. set in C12, which means that C12 must be disengaged for the further relaying of the signal.

— and this condition is satisfied by the fact that C12 is restored to its disengaged position once the latch-pawl of Drum #2 is brought to a given state of 'left' by the approach block of Crab "A"

and,

- e) the signal as of (d) is relayed from the downstream side of the N.C. load set in C12 to an N.O. load set in C11, which means that C11 must be in its engaged position for further relaying of the signal — and this condition is satisfied by the fact that C11 is sent into its engaged position by the 'drift' of Drum #2 past the departure block of Crab "B" during the travel of Drum #2 towards its color-aligned position with Drum #1, and further C11 maintains its engaged position until the next black-and-white relieving alignment is signalled.

The signal as of (e) is then applied to C13. Here the 'left' of the latch-pawl by the approach block of Crab "A" eminently precedes the locking of Drum #2 into its color-alignment position with Drum #1, it follows that C13 is engaged only as color-alignment of the two drums is achieved or is imminently about to be achieved. By the refinement of the control circuit given on Page 115, it would follow that C13 would ~~then~~ engage to release Position "B", disengage C14, and restore C9 and C7 to their disengaged positions, only after ^{the} color-alignment of the two drums has been achieved. This item (b) on Page 202 is explained.

THE TENTH CONSIDERATIONS

The important considerations underlying the projected design of the Control System are:-

- a) the type of mechanically-held relay used
 - b) the means whereby the release of Position "A" block-and-white alignment has been achieved
- It has been repeatedly set forth above that one of the functions served by the use of mechanically-held relays was to eliminate letter and electrical disturbances to the operation of the TV circuit with the functional demands on any given relay at its continued engagement. This set of qualifications more or less defines the type of relay which is required. Explicitly, it would be required that:-

1. The holding of the relay in engaged position be accomplished either by a mechanical or a magnetic latch

2. A second operating coil which overcomes the mechanical or magnetic latching action be a part of the relay.

Mechanical latches for the holding of relays in their engaged position are extremely common, and, in fact, the name — mechanically-held relays — is derived from the original use of such latches. More recently it has been common to replace mechanical latches by permanent magnets which hold the relay-plunger the plunger is drawn against the permanent magnet pole-face. This type of construction, which has been referred to as a magnetic latch, is preferred here, since strictly mechanical latches are subject to imperfect operation when the baseboards to which they are attached are jammed.

Finally as regards the mechanically-held relays used

should be observed that to ensure the best operation of such a relay, the two operating coils of the relay — the one which acts to engage the relay, and the other which acts to disengage, or de-latch the relay — should be signalled thru auxiliary contacts which are operated in common with the load contacts. The contacts which are auxiliary to the engaging action — the N.C. auxiliary contacts — should have a 'dragging effect' incorporated in them to ensure the completion of the engaging stroke against a spurious or chattering 'making' action.

If the construction schedule for the models permits, I will design a set of relays suited in size and other characteristics to the demand of the Control Circuit.

On the subject of the decision to disengage Positioner 'A' after black-and-white alignment of the Drum has been achieved, it has been held here that the inertia of the Drum Assembly and the Drive Motor rotor, plus the friction forces between the gears constituting the power transmission, would be sufficient to hold any previously established position once the desired Drum Assembly alignment and positioning in front of the cabinet window has been achieved. The further argument that a continued energizing of the Positioner solenoid might lead to 'chattering' and also to electrical disturbances to the T.V. circuit's normal operation led to one of two solutions:-

- * A. either construct the Positioner potentiels along mechanically-held lines;
 - or,
 - B. hold any given Drum Assembly position on the basis of the inertia and friction forces named above.
- The latter was chosen for the reason of the costs involved in the former alternative.

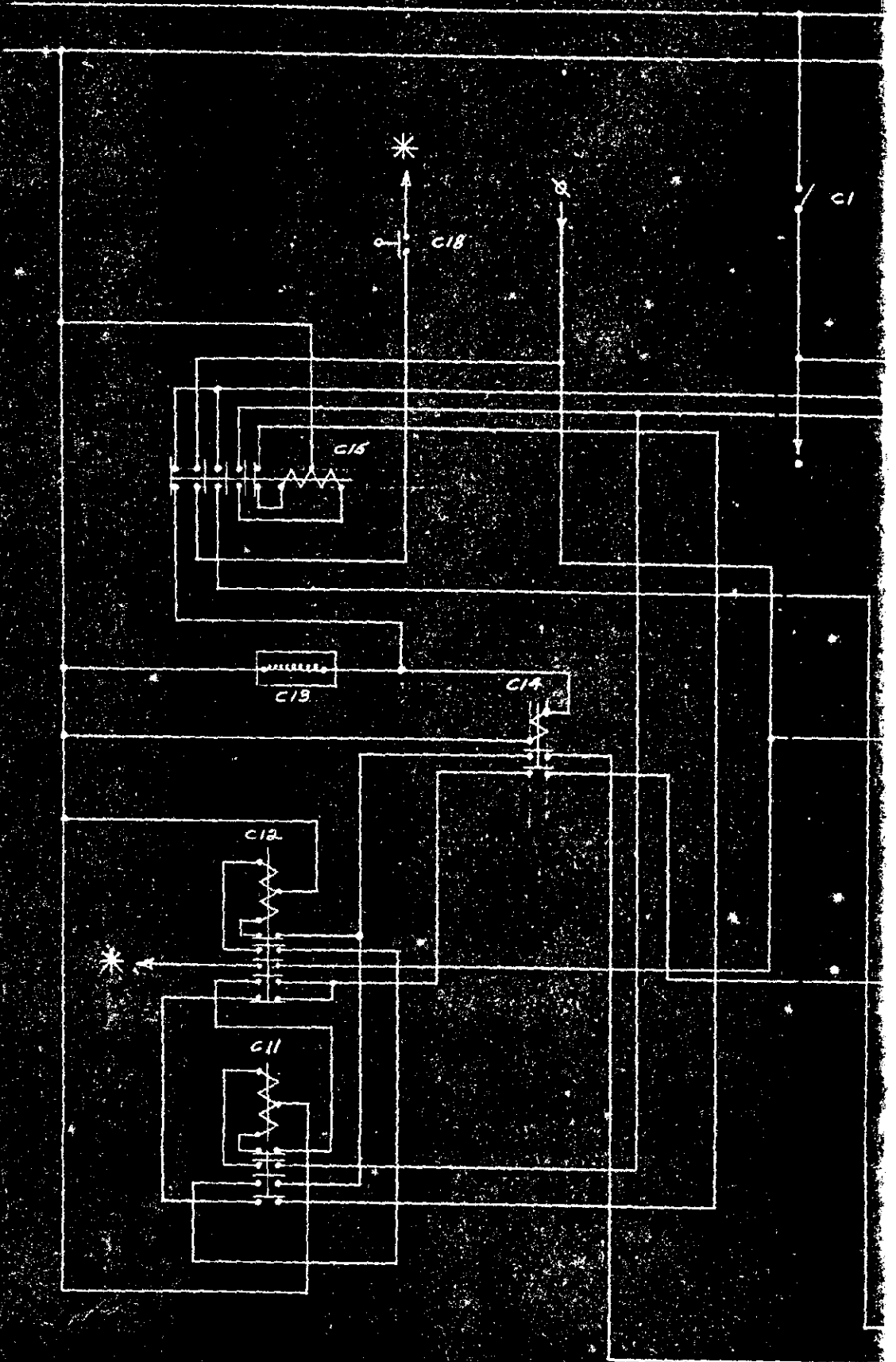
* NOTE:- WLT m 7 17

and 205

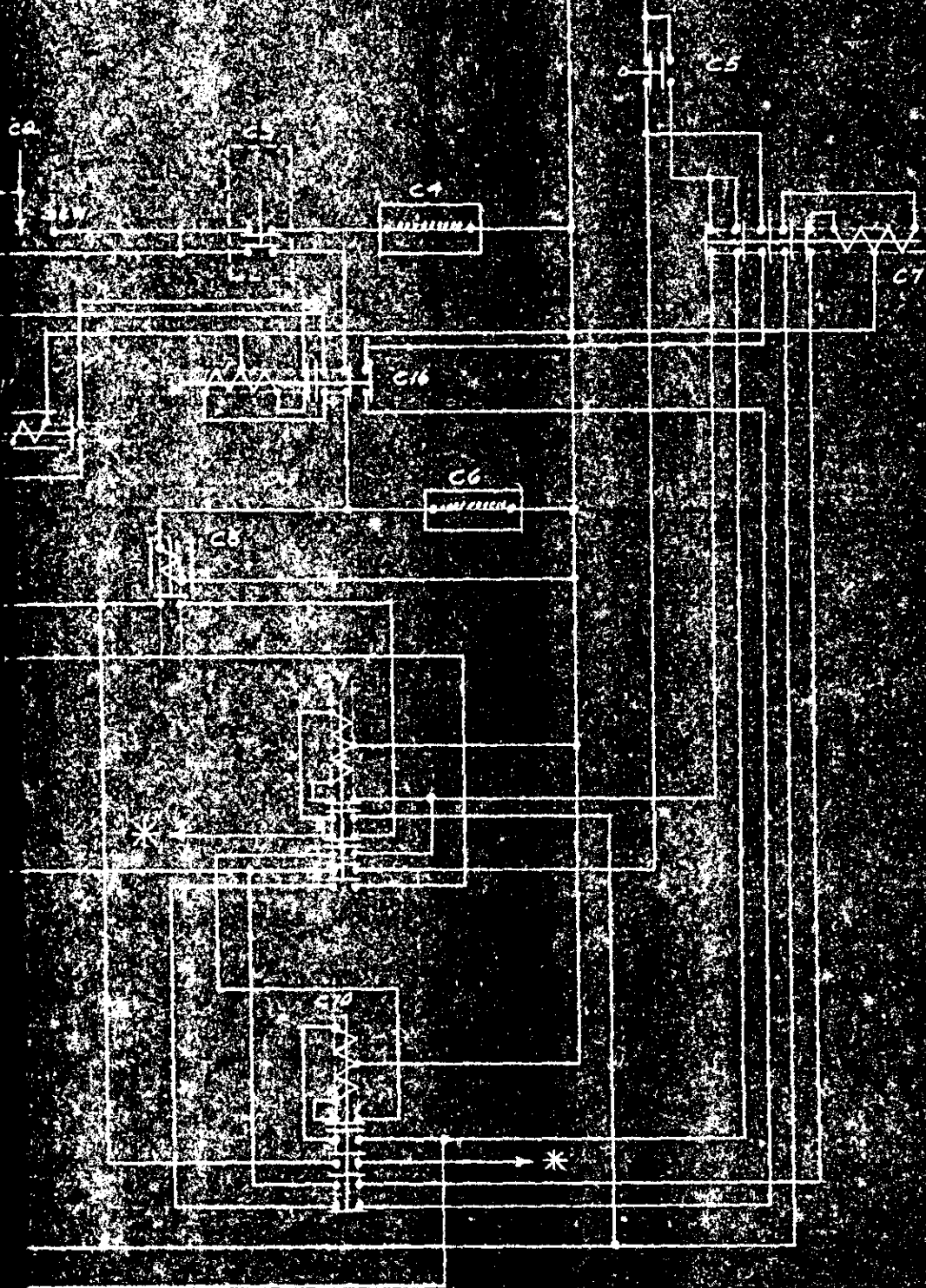
June 11

THE MIRIASCOPE CONTROL CIR

DW



7
2



1. The first part of the document is a list of names and dates, which appears to be a record of some kind. The names are written in a cursive script, and the dates are in a more formal, printed style. The list is organized into columns, with names in the first column and dates in the second column.

2. The second part of the document is a series of lines of text, which appear to be a continuation of the record or a separate entry. The text is written in a cursive script, and the lines are separated by horizontal lines. The text is somewhat difficult to read due to the cursive script and the quality of the image.

3. The third part of the document is a series of lines of text, which appear to be a continuation of the record or a separate entry. The text is written in a cursive script, and the lines are separated by horizontal lines. The text is somewhat difficult to read due to the cursive script and the quality of the image.

4. The fourth part of the document is a series of lines of text, which appear to be a continuation of the record or a separate entry. The text is written in a cursive script, and the lines are separated by horizontal lines. The text is somewhat difficult to read due to the cursive script and the quality of the image.

5. The fifth part of the document is a series of lines of text, which appear to be a continuation of the record or a separate entry. The text is written in a cursive script, and the lines are separated by horizontal lines. The text is somewhat difficult to read due to the cursive script and the quality of the image.

[illegible]

1. The first part of the paper is a list of the names of the persons who have been elected to the office of the President of the United States, from the year 1789 to the present time. The names are arranged in chronological order, and each name is followed by the year in which he was elected.

The principal ^{design} provisions set forth by Sup. # 1-9, as referred to Sheets # 1-19, are the following:-

- A. THE DECISION TO GIVE INNER DRUM END-RING (R.H.) A DOUBLE SUPPORT:- Sup. # 1 in its DETAILS "J" indicates that the Inner Drum End-Ring (R.H.) is to be a spoked ring, with its spokes attached at one end to a central hub and at their other end to an angle rim. DETAILS "J" further indicates that the rim bears "support members" which ride on the inner side of the Outer Drum End-Ring (R.H.). The "double support" for the Inner Drum End (R.H.) in this case can then be said to consist of:-
- a) the spoked construction which supports the ring from the stationary shaft (Detail "D"); and, (b) the "support members" construction which supports the ring from the Outer Drum End-Ring (R.H.).

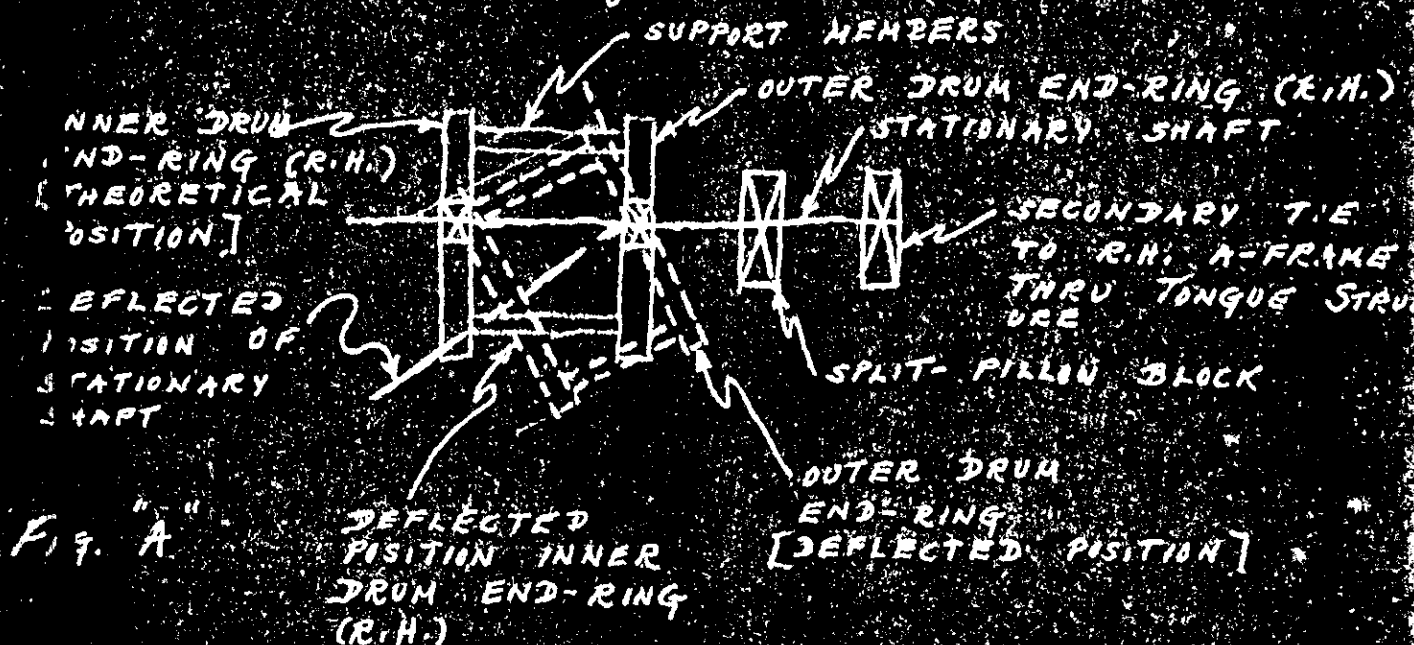


Fig. "A" sets forth the operative principle of the assembly which is obtained via the "double support" arrangement. It will

apparently be seen that the "support members" (the Drums #1 & 2) are a means of assuring "squareness" between both rings and the stationary shaft about which they rotate, in that they (the "support members") establish a parallel alignment between both rings (as they are related to one another). Thus, if either of the rings were to depart from its theoretically "square" geometrical relationship to the principal axis of the shaft, the "support members" would force the other ring into a parallel alignment to the first, and, thru the spoke support structure of the second, the second ring would communicate the slope of the deflected shaft at the first ring to the point at which the second ring is "anchored."

THEORETICAL AXIS OF INERTIA

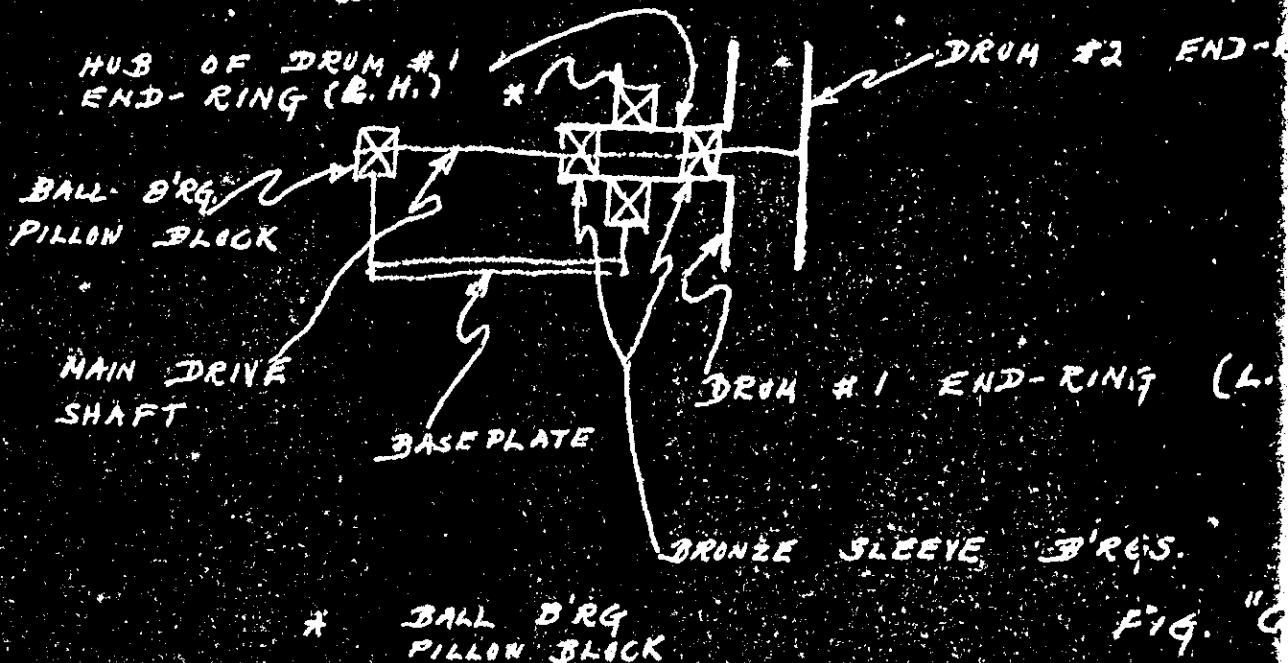


FIG. "B"

THE POSITION ELASTIC DEFLECTION CURVE OF DRUM #1 END-RING WHEN ROTARY SHAFT IS DEFLECTED

Fig. B illustrates the thought expressed above, and indicates that, if the stationary shaft is a sufficiently stiff member, the R.R. End-Rings as an assembly would be a stable one. Having arrived at this conclusion, it was then possible to consider the R.R. End-Rings as an independent assembly. Finally, this is illustrated in the diagram.

used on the L.H. side; -



Observing Fig. "C", it is clear that the Bronze Sleeve are a means of preserving a parallel alignment between two indicated End-Rings. Once this is clear, it is that if the thus-aligned rings are now adequately secured as an assembly the stable independence of the L.H. Assembly is an established fact. The two ball-bearing block units provide the support for the assembly as a whole.

Thus, it will be seen that both the R.H. and the L.H. Rings - Assemblies form individually stable, independent devices. Each draws its fundamental stability from its A-frame on which it is mounted. And so, if connections between the two A-frames are made in a manner that the two A-frames are integrated as a stable and stiff composite structure, it will be that little if any of the responsibility for the operation

by the Microscope as a whole would be imposed on the plate comprising the Drum Assemblies. In fact, the load imposed on the Drums would be transmission of the accelerating and the braking torques to the R.H. Ring-Assembly. The narrowing of the structural and dynamic functions of the Drums to the ones which have just been cited makes it feasible to adopt the following lines of assembly and maintenance: -

i. in assembling the Microscope, it is possible to establish a sequence in which the two A-frames and their inter-connecting members are first put together to form the prime structure. Next, each of End-Assemblies of the device should be assembled onto each of the A-frames. This should then be followed by a mounting of the C.R. tube and its auxiliaries on the Mounting Plate (See Diag. # 4) and a connecting of these members to the appropriate leads in the cable coming from the Hollow Shaft Member of the Mounting Assembly. With the foregoing having been accomplished, the plate for the Inner Drum, and later the plate for the Outer Drum, should then be fastened onto the appropriate End-Rings to yield a fully-assembled unit which is then placed in the cabinet.

and, ii. in the replacement of the C.R. tube or in checking the leads to the tube and its auxiliaries, this will be done by removing one or more adjacent plate in both Drums to get at the Tube Mounting Plate. The plate which may be removed for such purposes might best be clearly indicated by some special marking on the non-viewed ends of the plate.

It will already be surmised from what has already been said on the assembly and the maintenance topics that the "welded longitudinal frame which between plates, wheel Pairs #1 sets forth" and which were similarly set forth in the earlier sheets #1-19, are to be abandoned in favor of an individual fastening of each plate to the appropriate End-Rings, with each plate remaining an individually constituted member not otherwise connected to its adjacent plates, then by the "ring effect" of the End-Rings. As to the fit of each plate to its next adjacent plate, more will be said in the comments which are to follow on the fabrication of the plate themselves. It therefore just remains to say that as a result of the "double support" principle which has been built into the R. H. End-Rings, and because of the mutual parallel alignment feature which has been built into both End-Rings - assemblies, no reliance is now made on the Droms themselves towards the stiffness of the assembly as a whole; and the comments in this regard which appear on Pages 7 & 8 of the communication of 7/6/51 are therefore to be disregarded.

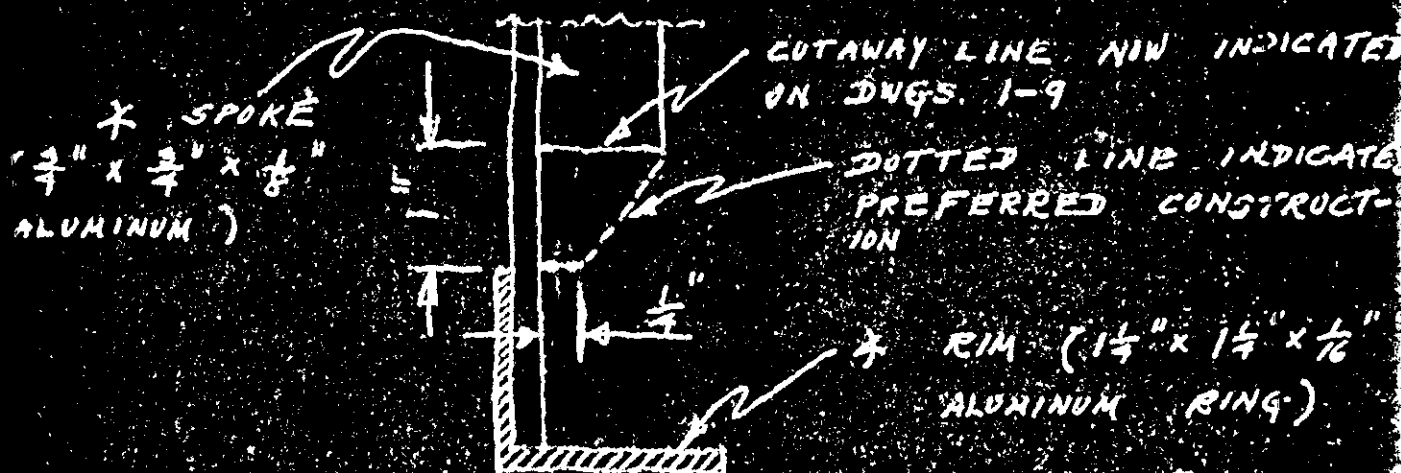
B. THE SPECIFIC DESIGN OF EACH OF THE END-RINGS:- In Sheets 1-9, the rim members of the End-Rings have been specified to be of angle members, rather than the types of rims specified in Sheets #1-19. In the case of both Outer Drom End-Rings, the spoke formation has also been altered over that previously given. Concerning the End-Rings rim members, the choice now of an angle section over the simple rectangular section previously indicated on Sheets #1-19 was dictated by the desire to give all of the rims a greater stiffness to with-stand roundness distortion influences. Moreover, the use of an angle shape in the case of both Outer Drom End-Rings contributes towards the ability to employ spoke formation which would otherwise not be possible.

^{independence of the}
The shifting of the structural (i.e. static) and dynamic boundaries of the wrist as a whole from its previous base in the 'complete cylinder effect' of the Drums to its later base in the metal parts of the assembly was the principal motivating factor in going to an angle section for the rim. But the fact that the angle shape is a stronger form and the necessity (from the standpoint of ease of assembly and maintenance) for shifting from a dependence on the Drums for a weighty contribution to the strength and roundness properties of the assembly need no further discussion. Let us turn therefore to the way in which the angle rims have contributed to other aspects of the construction.

The 'other leg' of the angle rims employed, it will be seen, has served as:- a) a means of securing of firm joint between the rims and the spokes; and; (b) a means of anchoring such gadgetry as the support plate for the recoil spring and the limit switch components of the latch-pawl device (on the L.H. Inner Drum End-Ring) and the side-plate to which the support ends of the "support members" are attached (in the case of the Inner Drum R.H. End-Ring). Specifically, on the questions of both Outer Drum End-Rings, the inner surfaces of the rims must be 'clear' for the movement of gadgetry associated with the Inner Drum. This necessitates, in both instances, that one leg of the angle spokes be cut away to provide the necessary freedom of movement. The fact the Outer Drum End-Rings are formed of an angle section make it possible to provide the necessary cut-away without risking a wobbling of the rings due to a weakening of the spoke, since the stiffness of the rim can be held to be transmitted in part to the one remaining leg (of the cutaway spoke), by which the rim is fixed to the drum members of each ring. Here, the fact that the remaining leg is welded along all of its lines-of-contact to the side leg of the rim, and the strength properties of the

residual span of the cutaway length of the spoke, combine $\frac{1}{2}$ to draw on the angle rim for a stiffness which would not otherwise be expected for the cutaway length.

A preferred construction in regard to the spoke-to-rim joint for both Outer Drive End-Rings would have been that shown below over that indicated in Dwg. 1-9:-



In any case, the use of angle spokes in the ^{interior} of both Outer Drive End-Rings in the place of the constructions indicated in Dts. 1-19 which call for the use of channels tied into relatively complicated joints with each rim, is a move in the direction of space-saving and a more rigid construction for the overall rings. The use of an angle section for the End-Ring rims and the use of angle spokes tied into angle butt-joints with the rims and hubs of the Ring-Assemblies is in fact a part of the general conclusion that the plastic Drive per se should not be depended on for any substantial contribution to the stiffness of the overall assembly.

II. THE CHANGES IN THE SPECIFICATIONS FOR THE BEARINGS:- Inspecting Dwg. 1-4, it will be

stated that anti-friction bearings have been used wherever the members-in-motion are involved in roller-viewing (that is, wherever the members-in-relative motion experience duty for substantial periods of time); and, where the members-in-relative motion experience duty only during Drum-realignment, these bearings have been specified to be skirt-type bearings of the "proper" construction type. Thus, the bearing between the stationary shaft and the Outer Drum End-Ring has been changed from the construction shown in Sheet #1-19 to an anti-friction bearing as shown in Sheet #1-9. With regard to the stationary shaft-to-Outer Drum End-Ring bearing, it is well to point out that the "presence of squeal" with the stationary shaft, which the construction shown on Sheet #12 would have contributed to, is accomplished in the case of the presently-indicated construction by the Baffle-Support Effect between the two R.H. End-Rings, as was noted above. The reasoning behind the preference for anti-friction bearings when prolonged bearing duty is involved is of course obvious.

B. THE DESIGN OF THE "SUPPORT MEMBERS" :-

On Sheet #11 of the originally-submitted Sketch Sheets, "bearing arms" of phenyl-methacrylate were proposed. These were to be attached to a at-that-time proposed plastic end-ring of the same material for the R.H. side of Drum #2. These "bearing arms" were to ride on the inner surface of the R.H. Outer Drum End-Ring, and to play a part not different from that now proposed for the "support members" on Drums #1 of the series Drums #1-9.

The presently-proposed "support members", which involve a roller action on an axle attached to the Inner Drum R.H. End-Ring, were substituted for the originally-proposed "bearing arms" because they are capable of taking a larger load, and also because over a long period of time the presently-proposed "support members" would require less

maintained and would be more noise-free.

E. THE LATCH-PAWL MECHANISM ALTERATION:

I
M
P
O
R
T
A
N
T

P
L
E
A
S
E

N
O
T
E

Before discussing the alteration in the design of the latch-pawl, it would do well to point out a revision which should be made in the design now projected on Diag. #1 of Sheets #1-9. As presently indicated on Diag. #1, it would appear as if the 'relaxed' position of the latch-pawl would involve its Hub member resting on the floor of the inner Outer Drum L.H. End-Ring. This should be altered so that the relaxed position of the spring (S) on Diag. #1, controlling the pawl's position, keeps the pawl about 1/8" off the mentioned floor. This would mean that there would be no scraping action by pawl's hub on the floor of the given End-Ring when Drum-realignment occurs; and, yet, the engagement of the End-slot of either Knot would not be ill-affected as to the positiveness of engagement between the two Drums. With the slight modification of the design shown on Diag. #1, it is clear that the only contact between the Drum latch-pawl and L.H. End-Ring of the Outer Drum would occur when:-- (a) the two Drums are engaged; and, (b), when the latch-pawl mounts the slope of either Knot's approach-block. For the case where action (b) occurs, the roller-covered roller on the shank of the pawl would give a noiseless rolling action whereas the design originally submitted on Sketch Sheets #1-19 would involve a scraping action between the latch-pawl and each approach block.

and,

F. THE SPECIFICATIONS FOR AND THE FABRICATION OF THE SLATS:-

The originally-submitted bill-of-materials and the document of 7/6/51 called for the use of 1/8" milled plate sheet of steel, saturated blue, patented green, and saturated red colors.

At the time, these specifications were laid down it was ^{the} understanding of the writer that polymethacrylate sheet of the correct optical filter properties is available. This is apparently not true. It now appears that true colors depend on the use of filters of tight optical specifications. Against this latest information, it would appear that the optimum construction for the filter-slats would consist of Wratten Blue #1, Wratten Green #58, and Wratten Red #26 filter sheets sandwiched ^{in an optical grade} unwrinkled and uncreased form between two $\frac{1}{16}$ " thick ^{poly-} methacrylate sheets preformed to the specified curvatures. [NOTE: - At a later date, some experimentation in the deposition of filter gelatin on one of the two methacrylate sheets forming each composite slat would be in good order, and instructions in this regard will be furnished.]

As to the composite slat as defined above, the adjacent longitudinal edges should be so finished off that tight, square fits between the slats are possible. In the case of clear slats, two slats of $\frac{1}{16}$ " thick polymethacrylate sheet should be employed encasing a "balancing" sheet of clear cellophane should be used. [* Balancing here means balancing the filter Wratten color filter sheets used in the color filter slats.]. No bonding, as previously indicated, between the longitudinal slat joints will be necessary. Each slat made up as above outlined is to be independently attached to the appropriate End-Rings.

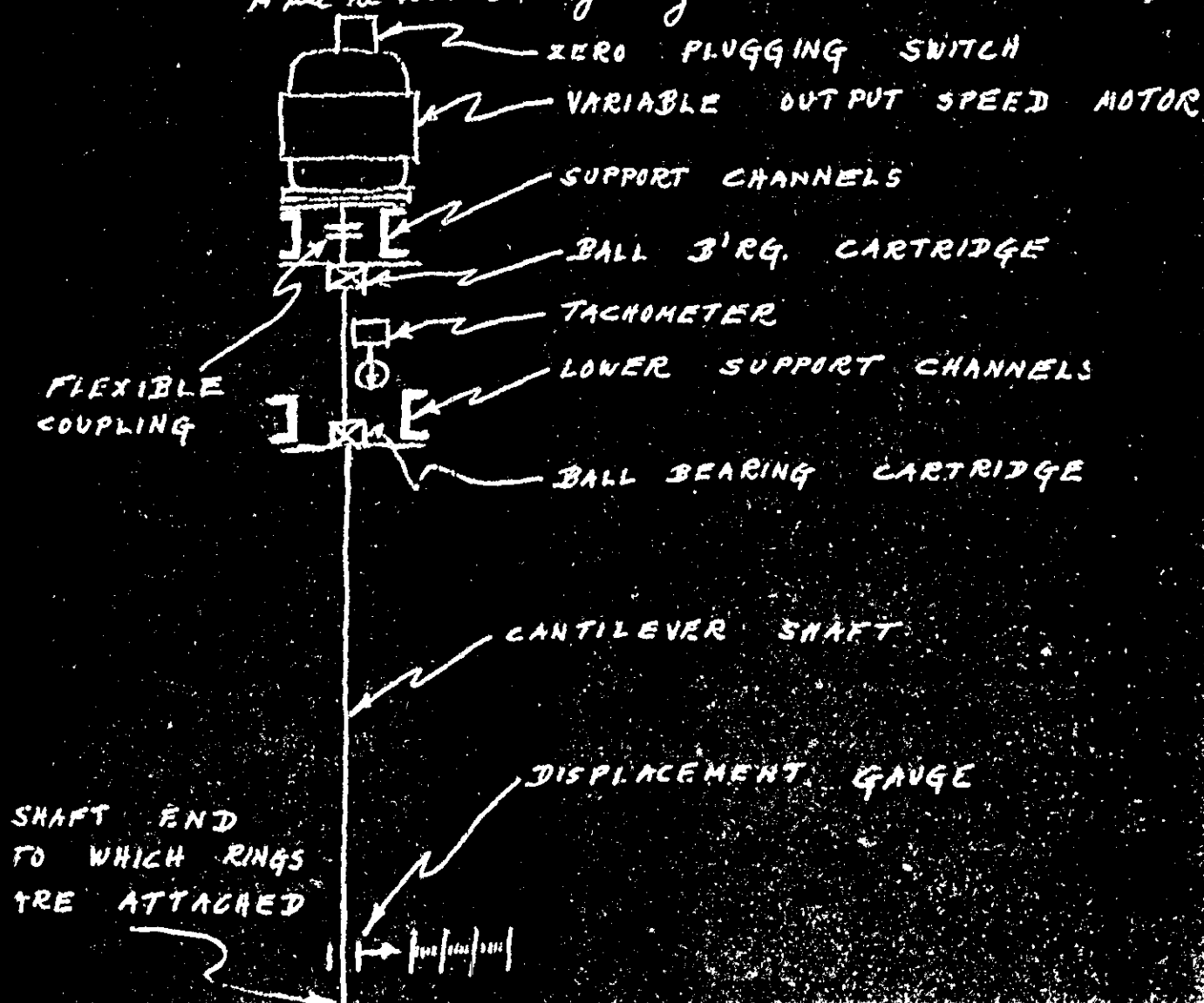
THE PRINCIPAL ASSEMBLY PROBLEMS:-

The proper operation of the microscope as it is now projected depends on the following critical factors:-

I. THE PROPER BALANCING OF EACH OF THE END-RING UNITS:-

Quite obviously, at least two of the End-Rings [The L.H. End-Rings of the

Inner and Outer Drums] are not balanced as shown on Dumps 1-9. It goes without saying that a substantial order of dynamic balance is demanded of all of the End-Rings. As a first step, each of the Rings shall be brought to 'static balance' individually. Conventional procedure for the accomplishment of 'static balance' will suffice. After each Ring has been brought to 'static balance', a satisfactory method of testing for 'dynamic balance' and adjusting according to measurements determined thereby would be to use a device as generally outlined below:-



The apparatus sketchedly indicated above would operate on the relationship between (E) - the eccentricity of the attached rotor, (ω_N) - the natural frequency of the loaded Ring & loaded cantilever shaft assembly, (ω) - the angular velocity of the rotating assembly, and (y) - the linear displacement of the shaft due to the influence of (E) . Of the above variables, (y) would be determined by the displacement gauge and (ω) by the tachometer. Since (ω_N) is an analytically-computable property of any system in which the weight of the Ring, the length, diameter, and weight of the shaft, and modulus of elasticity of the shaft are known, it follows that an alignment chart of proper make-up would yield a value for E , the arm at which the rotor mass acts to induce the displacement of the shaft. The determination at any identical shaft velocity of the displacement following from the clamping of a known weight to any randomly-chosen but accurately determined point on the rim of any Ring would then permit the determination from a second alignment chart of the radial direction of the centrifugal force due to the rotor's mass acting at the previously determined eccentricity. The same second alignment chart could be set up to yield the point at which a balancing weight should be placed to yield a given order of balance at the test shaft velocity. A series of three, at most, such combined measurements, each followed by the appropriate attachment of balancing weights, — with one test being performed at a low velocity, one test at an intermediate velocity, and the third at the full operating velocity of the Ring, would suffice to yield a properly balanced ring for incorporation in the Waviascope.

Yet the balancing of each of the Rings to a high tolerance would not necessarily mean the obtaining of a suitably balanced overall assembly

even if the method of attaching the slats and the distribution of mass amongst the slats were perfect, which admittedly is not a theoretically obtainable condition. Before the driving gear is located in its designated position, it would be necessary to test the unit for static balance. Once assured of, or corrected to, an adequate condition of static balance, the device in its assembled form would have to be mounted on a ~~spring supported~~ test table ^{or frame}, preferably a light frame (which is to say, a frame composed of light members). Using a vibrometer to measure the amplitude of the vibrations induced in the floor frame where the A-frames are tied in, it is possible to correct any assembly unbalance condition according to which of three classes of unbalance is determined to exist. These three conditions of unbalance can always be resolved to the operation of two centrifugal forces acting from the same side of the axis of rotation and in the same axial plane; or, two forces — producing a rotation couple — acting in the same axial plane but from equidistant opposed arms as referred to the axis of rotation; or, two forces — capable of being resolved into a couple and one additional force — when the two forces act in different axial planes. The addition of compensating weights to produce opposing the Outer Drum End-Rings to produce opposing couples and/or forces then corrects the dynamic balance of the assembly. The balancing of the Microscope should be accomplished in two stages: — the first at Drum speed roughly $\frac{1}{2}$ of the operating speed; and, the second at the full operating speed of the assembly.

II. THE FITS BETWEEN CRITICAL MEMBERS OF THE ASSEMBLY :- To assist in this matter, a schedule of the required fits between various assembled members is given below :-

BULKY EXHIBIT

Date received 9/5/51

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent John M. Collins

Source from which obtained E.E. Thompson

Address Warden, Federal Detention Headquarters

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

153. Miscellaneous papers found in Brothman's cell after his removal to Atlanta.

100-95068-1B

8/12

BETWEEN

&

CLASS OF FIT

Plastic Commutator
Ring Holder

Inner Core of
Main Drive Shaft

Friction Fit

Outer Race of $1\frac{1}{8}$ "
shaft size bearing

Core of the Pillow
Block Housing

Loose Fit

Core of the Inner
Race of the $1\frac{1}{8}$ "
shaft size bearing

Main Drive
Shaft

Tight Fit

Output Shaft of
the Motor Drive

Core of the Inner
Race of the Outboard
Bearing

Loose Fit

Hub of the Outer
Drum L.H. End-
Ring

Core of the Inner
Race of the $1\frac{3}{4}$ "
shaft size bearing

Tight Fit

Outer Race of the
 $1\frac{3}{4}$ " shaft size
ball bearing

Core of $1\frac{3}{4}$ " pillow
Block Housing

Loose Fit

Main Drive Shaft

Core of the Bearing
Housing in the Hub
of the Inner Drum
End Ring

Medium Fit

Main Drive Shaft

Core of the Inner
Race of the $1\frac{3}{4}$ "
shaft size bearing

Wringing Fit

Stationary Shaft

Core of the Inner
Race of the $1\frac{1}{16}$ " shaft
size ball bearing

Loose Fit (Medium)

Outer Race of the
 $1\frac{15}{16}$ " ball bearing
in the Hub of the
Inner Drum R.H.
End-Ring

Core of the Hub of
the Inner Drum
R.H. End-Ring

Tight Fit

<u>BETWEEN</u>	<u>&</u>	<u>CLASS OF F</u>
Stationary Shaft	Core of the inner Race of the $1\frac{13}{16}$ " shaft size ball bearing in the hub of the Outer Drum R. H. End Ring	Medium Force Fit
Outer Race of the $1\frac{3}{16}$ " shaft size b. b. in the hub of the Outer Drum R. H. End Ring	Core of the Hub of the Outer Drum R. H. End Ring	Tight Fit
Member (43) Dwg. #1	Member (45) Dwg. #1	Medium Fit
Member (46) Dwg. #1	Member (45) Dwg. #1	Free Fit
Member (66) Dwg. #1	Outer Portion of Member (62) Dwg. #1	Medium Fit
Member (53) Dwg. #1	Shaft member of Disintegrator Assembly - Dwg. #1	Loose Fit

- ① Where the superscript ① appears, attention is called to the fact that the fit should approach a "wringing" or "turning" fit.
 - ② Where the superscript ② appears, the specified " snug fit " should be a typical "snug fit".
 - ③ Where the superscript ③ appears, the specified "tight fit" should approach a "wringing" or "turning" fit.
 - ④ Where the superscript ④ appears, the specified "medium force fit" should approach a "tight fit".
- * The ball bearing referred to here is in the hub of the Inner Drum R. H. End Ring.

BETWEEN&CLASS OF FIT

Bearing Bushings

Bore of the Outer
Drum L.H. End -
Ring

Wringing Fit

Bearing Bushings

Bore of the Stationary
Shaft

Wringing Fit

Hollow Shaft Member
of the Tube Support
PlateBore of the Bearing
Bushings in the
Stationary Shaft

Snug Fit (2)

Hollow Shaft Member
of the Tube Support
AssemblyBore of the Hub of
the Tube Support
Bracket

Wringing Fit

Stationary Shaft

Hub of the "second
support" anchor

Snug Fit (2)

Bore of the Driven
Gear

Main Drive Shaft

Snug Fit (2)

Output Shaft of
the Motor Drive

Driving Gear

Snug Fit (2)

Finally, as regards the Support Member of the Inner End-Ring (R.H.) and the Outer Drum End-Ring R.H., care should be taken that each roller member is in solid contact with the whole rotation of these roller members with the inner surface of the rim of the Outer Drum End-Ring R.H. And, regarding the Stationary Shaft in the Split Pillow Block, the latter should be drawn up rigidly tight against the Stationary Shaft, the capscrews fixing the two halves of the Split Pillow Block be provided with lock-washers to prevent a loosening of the Stationary Shaft.

III. A variety of assembly and operational factors will be discussed in the final section of this document under the collective heading of a "Syllabus of Pearl Rugs, And Their Correction."

* * * * *

RE-CALCULATIONS CONCERNING THE
SALIENT FEATURES OF THE
DESIGN

THE SLATS



The larger diameter set of slats would have a radius of $24 \frac{1}{16}$ ". The approximate area of each slat is

$$\frac{2\pi(13)(60)(24 \frac{1}{16})}{360} = 338 \text{ in}^2$$

and if each slat were $\frac{1}{16}$ " thick the volume of each slat would be -

$$\frac{338 \text{ in}^2}{16 \text{ in}} = 21.1 \text{ in}^3$$

and assuming the specific gravity of polymethylacrylate sheet is 1.1 and assuming the slats would have a weight of

$$\frac{21.1 \text{ in}^3}{1.1} = 19.18 \text{ in}^3$$

$$(19.18 \text{ in}^3)(0.075 \text{ lb/in}^3) = 1.438 \text{ lb}$$

being at an angle of 60 degrees

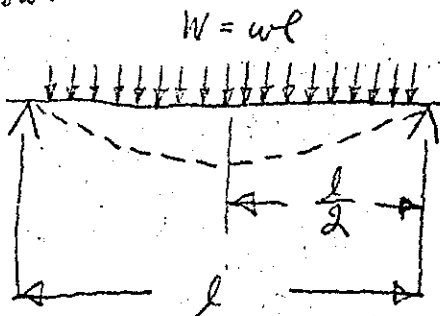
$$24 \text{ rpm} \left(\frac{2\pi \text{ rad}}{1 \text{ rev}} \right) = 150.8 \text{ rad/sec}$$

The centrifugal force acting on each slat would amount to

$$F_c = \frac{0.1902 \text{ #}}{32 \frac{\text{ft.}}{\text{sec.}^2}} \cdot (150.8)^2 \frac{\text{rad.}^2}{\text{sec.}^2} \left(\frac{13 \text{ ins.}}{12 \frac{\text{ins.}}{\text{ft.}}} \right)$$

$$= 694 \text{ #}$$

The force would be distributed as a uniform load over the entire l of the loaded beam to give a condition as schematically indicated below.



$$W = wl$$

$$EI \frac{d^2 y}{dx^2} = \frac{wx}{2} (l-x)$$

$$\frac{dy}{dx} = \frac{w}{2EI} \left(\frac{lx^2}{2} - \frac{x^3}{3} \right)$$

$$\text{Since } \frac{dy}{dx} = 0, \text{ when } x = \frac{l}{2},$$

$$0 = \frac{w}{2EI} \left(\frac{l^3}{8} - \frac{l^3}{24} \right) + C_1$$

$$C_1 = -\frac{w}{2EI} \left(\frac{l^3}{12} \right) = -\frac{wl^3}{24EI}$$

whence :-

$$\frac{dy}{dx} = \frac{w}{2EI} \left[\frac{lx^2}{2} - \frac{x^3}{3} - \frac{l^3}{12EI} \right]$$

$$y = \frac{w}{2EI} \left[\frac{lx^3}{6} - \frac{x^4}{12} - \frac{l^3 x}{12} \right] + C_2$$

Since $y = 0$, when $x = 0$, then $C_2 = 0$; and,

$$y = y_{\max}$$

where $\frac{l}{2} = x$, so that

$$y_{\max} = \frac{w}{2EI} \left[\frac{l^4}{48} - \frac{l^4}{192} - \frac{l^4}{24} \right]$$

$$= -\frac{w}{2EI} \left[\frac{5l^4}{192} \right] = -\frac{5wl^4}{384EI} = -\frac{5Wl^3}{384EI}$$

Referring back to the diagram on Page 318, the dot on the y- indicates the center of gravity of the slat. The distance (\bar{y}) of the dot from the axis of rotation would be given by :-

$$\bar{y} = \frac{r \sin 30^\circ}{\cos 30^\circ} = \frac{13(0.5)}{\frac{\pi}{6}} = \frac{13(3)}{3.14} = 12.42$$

The x-sectional area of the slat is approximately

$$\frac{2\pi r 60^\circ}{360^\circ} \cdot t = \frac{2\pi(13)1}{6(16)} = \frac{26\pi}{96} = 0.852$$

and its approximate (I_0) about its center-of-gravity is given by :-

$$0.852(13.00)^2 = I_0 + 0.852(12.42)^2$$

where $13''$ is taken to be the radius of gyration of the slat about its x-axis thru the axis of rotation. By the equation derived on Page 31 then

$$y_{\max} = \frac{5(694)(24 \frac{1}{16})^3}{384(26)(10^6)(12.78)} = \frac{5(694)(15)(10^3)}{384(26)(10^6)(12.78)} = 0.000408 \text{ in.}$$

This is indeed a negligible deflection, but it ~~establishes~~ is based on the proper value for (E) — the (E) for steel — which is in all likelihood large; but even if it were $\frac{1}{30}$ of the indicated value, then

$$0.000408(30) = 0.01224''$$

would be the approximate magnitude of (y_{\max}). Even such a value could be tolerated; and would evidently involve a very low stressing of the slat. If, as per Page 311, two sandwichee slats of methacrylate were to be used, then

$$\frac{360}{60}(694)(2) = 8328\#$$

would be the total load imposed on the Outer Drum End — the by the slat when the Drum is rotated.



The stress induced in the End-ring, would be a tensile stress. In fact, a $1\frac{1}{4} \times \frac{1}{2} \times \frac{1}{8}$ aluminum alloy is employed. The x-section of the angle offers an I_x of 0.3 in.⁴. This would mean that, since the load is between two Rings,

$$\frac{8328 \#}{2(0.3) \text{ in.}^4} = 13,880 \#/\text{in.}^2$$

would be the tensile stress induced. This stress lies actively beneath the elastic limit of such aluminum 515, and hence is acceptable.

CONCLUSIONS UP TO THIS POINT:-

- A. The 60° slats, which are the weakest of the slats in the Outer Drum, will not suffer in undue flexion due to centrifugal loading during the running of the Drum Assembly. If this is true of slats in the Outer Drum, it certainly means that slats in the Inner Drum are equally "safe".
- B. The Outer Drum Rings, which were originally specified at $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{16}$ 4s, but which in practice were brought to $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$ 4s, are certainly safe. For the Inner Drum End-Rings which are $1\frac{1}{4} \times \frac{3}{4} \times \frac{1}{8}$ 4s, and which have a cross-sectional area of 0.13 in.²

$$\frac{8,328}{2(0.13)} = 31,600 \#/\text{in.}^2$$

would be the induced stress, which is still beneath elastic limit for a 515 aluminum. Consequently, the Inner Drum Rings are also "safe". If the modulus of elasticity of the 515 is taken at $3.7(10^6)$ lbs./in.²

$$E = \frac{S}{\epsilon} = \frac{31,600}{\epsilon} = 3.7(10^6)$$

$$\epsilon = \frac{31,600}{3.7(10^6)} = 0.00854$$

which is to say that

$$2\pi(13)(0.00854) = \text{peripheral stretch in the rim} = 0.696"$$

during rotation in the case of the Inner Drum E. If the increase in the circumference, (Δc) , is 0.696 then

$$\frac{0.696}{6.28} = 0.11"$$

would be the increment in the radius of the wheel. The moment we were to drop the restraining influence of the spokes from consideration. Continuing the check, clear that @ a hoop stress of 13,800 #/sq. in.

$$\frac{13,800}{31,600} (0.11) = 0.0481"$$

would be the radial stretch in the Outer Drum. Correcting the 0.696 circumferential stretch for the π of the Inner Drum Ring, which is $25\frac{1}{2}"$ instead of 2. find

$$\frac{25.5}{26} (0.696) = 0.684" = \Delta c$$

and

$$\frac{0.684}{2\pi} = \Delta r = 0.1088"$$

the Ring radius would go from 12.75"

$$12.75 + 0.1088 = 12.8588"$$

for the case of the Inner Rings, while the Outer Ring would go from 12.9375" to

$$12.9375 + 0.0481 = 12.9856"$$

the gap between the Rings of

$$12.9856 - 12.8588 = 0.1268"$$

the dynamic gap as opposed to the static gap. The calculations are enough to indicate the effect of the radial stretch in the inner drum.

Outer

The stress in the Rings due to their rotation is given by

$$T = \frac{W}{g} v^2 \quad (\#/ft.^3)$$

where:- w = the density of the ring-material; T = tensile stress, and, g = gravitational acceleration, $ft./sec.^2$. Where the sp. g. of is 2.7, then

$$\begin{aligned} T &= \frac{2.7(62.5)}{32} \cdot \left[(24 \text{ rps}) (2\pi \text{ rads/rev}) \left(\frac{13 \text{ ins}}{12 \frac{\text{ins}}{\text{ft}}} \right) \right]^2 \\ &= 140,000 \text{ \#/ft.}^2 \\ &= \frac{140,000 \frac{\text{\#}}{\text{ft.}^2}}{144 \frac{\text{ins.}^2}{\text{ft.}^2}} = 973 \frac{\text{\#}}{\text{in.}^2} \end{aligned}$$

The combined ^{tension} stress in the Outer Rings due to their rotation and due to the imposed load from the slats would be

$$13,880 + 973 = 14,853 \frac{\text{\#}}{\text{in.}^2}$$

which would mean a radial stretch of

$$\frac{14,853}{3.7(10^6)} \times 13 = 0.522 \text{ "}$$

which are approximately 12" in length, a unit elongation of

$$\frac{0.522}{12} = 0.0435$$

$$3.7(10^6)(5.96)(10^{-3}) = 16,080 \text{ \#/in.}^2$$

stretch of the spokes would take place. The force of this stretch, for the four spokes, would pull on the rim. Between

the uniform loading of a spoke, the force for the $1\frac{1}{4} \text{ " } \times 1\frac{1}{4} \text{ " } \times 0.5 \text{ in.}$ area is 0.5 in., a stress

a stress of 14,853 lbs./in.² means a load of

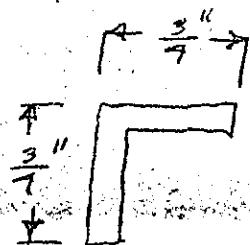
$$14,853(0.3) = 4455.9 \text{ \# / ring}$$

Per spoke, this would mean

$$\frac{4456}{4} = 1114 \text{ \#}$$

or a stress of

$$\frac{1114}{\frac{11}{64}} = 6500 \text{ psi}$$



$$\frac{5}{8} \times \frac{1}{8} = \frac{5}{64} \text{ in.}^2$$

$$\frac{6}{8} \times \frac{1}{8} = \frac{6}{64} \text{ in.}^2$$

$$\frac{11}{64} \text{ in.}^2$$

and, for a spoke length of approx. 12", the area to

$$\frac{6500}{3.7(10^6)} \cdot 12 = 0.0211 \text{ in.}^2 = \Delta L$$

For a uniformly-loaded beam with fixed ends, (y_{\max}) [not shown here] would be given by:-

$$y_{\max} = \frac{w l^3}{384 E I}$$

(l) may be taken to be $\frac{1}{4}$ x the circumference, whence

$$\frac{13(2\pi)}{4} = 20.4 \text{ in.} = l$$

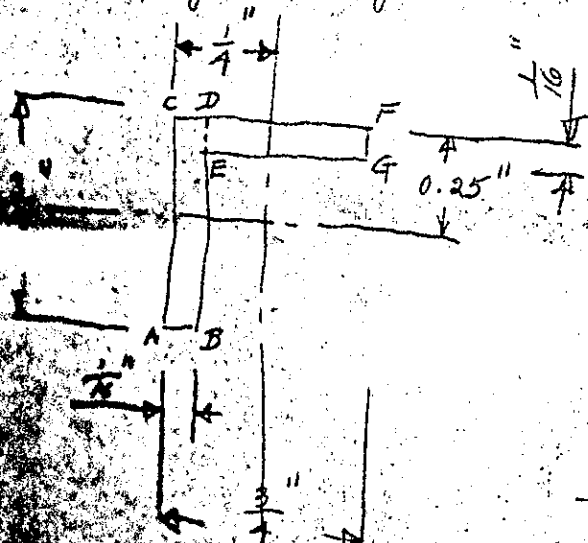
and, since I , for $1\frac{1}{4} \text{ in.} \times 1\frac{1}{4} \text{ in.} \times \frac{1}{8} \text{ in.}$ is 0.04 in.⁴, then

$$y_{\max} = \frac{1114(20.4)^3}{384(3.7)(10^6)(0.04)} = 0.2335 \text{ in.}$$

This indicates that a doubling of the number of spokes already specified would be required to hold the between-spokes deflection of the rim to tolerable limits. Such a doubling of the no. of spokes used would halve the load per span, and halve the span — the combined effect of which would be to cut the between-spokes deflection to $\frac{1}{16}$ of the value computed above.

$$\frac{0.2335}{16} = 0.0146 \text{ in.}$$

In the case of the inner kerge, only part of the solution to the problem of preventing a large between-spokes deflection lies in doubling no. of spokes, for the moment of inertia of the angle section is



The moment of inertia of ABCD about its own neutral fibre would be :-

$$\frac{1}{12} \cdot \frac{1}{4} \cdot \left(\frac{3}{4}\right)^3 = \frac{0.92}{19.2} = 0.00219$$

About the indicated X-axis the moment of inertia of this section is

$$I_x = 0.00219 + \frac{1}{16} \cdot \frac{3}{4} \cdot \frac{1}{8}^2$$

$$= 0.00219 + \frac{0.00073}{0.00586}$$

$$= 0.00292$$

$$= 0.00292 \text{ in.}^4$$

The moment of inertia of EFG about its neutral fibre would

$$\frac{1}{12} \cdot \frac{3}{4} \cdot \frac{1}{16}^3 = \frac{3}{48(4100)} = 0.00001523 \text{ in.}^4$$

About the indicated X-axis would be approximately

$$I_x = 0.0000153 + \frac{3}{4} \cdot \frac{1}{16} \cdot \frac{1}{4}^2$$

$$= 0.0000153 + 0.00293$$

$$= 0.00295 \text{ in.}^4$$

Total (I_x) of approximately 0.00587 in. ⁴

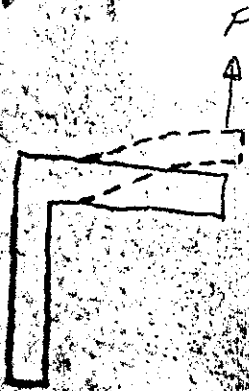
The moment of inertia of the angle section would increase by a factor of 7 in the flexure. Roughly it would amount to

$$0.00587 \cdot 7 = 0.04109$$

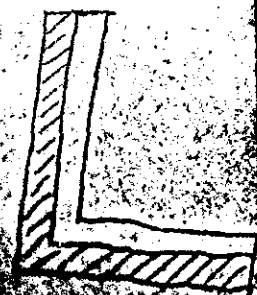
$$= 1.555 \text{ in.}^4$$

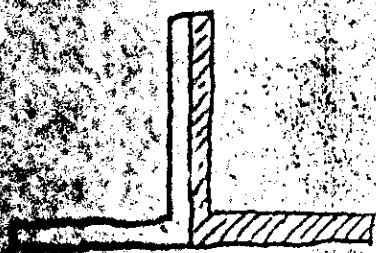
$$\frac{2.6555}{16} = 0.091"$$

for an 8-spoke wheel. Before passing the "8-spoke" to a conclusion, and before proposing a solution for the "between-spokes" flexure of the Inner Drum End-Rings, it pay to give attention to the problem which arises because of the loading of the centrifugal force acting on the plate to on the 4 rims. A situation such as is indicated below



In other words, a tendency would exist loaded leg to flare out due to a result of the loading. This would be most noticed the case of the Outer Drum L.H. End-Ring then, in the next instance, in the case of Outer Drum R.H. End-Ring. It would be applicable to the Inner Drum End-Rings, if the load involved is such that if it comes over any single portion of a $1\frac{1}{4}" \times 1\frac{1}{4}" \times \frac{1}{8}"$ will produce an excessive deformation of the concentrated-tension stresses are concerned, there is but one way and that is to increase the area of material. This is indicated some of the ways in which it is accomplished:-





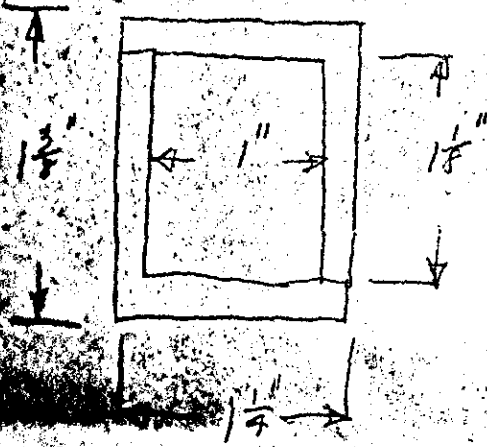
* * * * *

(In each case, the x-hatched member is the presently-specified 7-mm)

* * * * *

(D) From purely structural considerations, (A) and (D) provide the soundest means of "beefing up" the stressed section. From a cost standpoint, (B) and (C), and particularly (B), stand better. (B) and (C) involve the greatest re-design of the lateral members — in that for the given stroke of the "Positioners" plunger, any increase in the metal thickness of the leg through which the plunger goes means a decrease in the displacement to which the lateral pawl can be pushed. Though it would be hard to prove that this is true for (A) as well, certain accessories can be made with (A) which are not so easily made with (B) or (C).

In seeking towards a final solution of the problems involved, I have put my bets on (A), and for the moment I have decided to make the plate connecting of a sandwich type of construction. A section of 1/8" thick plate with a cross-sectional area of 0.6". The (I) for this sec.



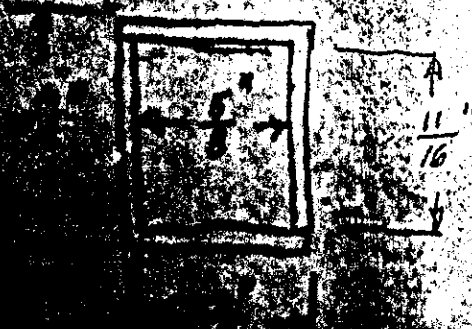
would be :-

$$I = \frac{1.25(1.375)^3 - 1(1)^3}{12} = \frac{3.25 - 1.42}{12} = 0.1525 \text{ in}^4$$

Accordingly, the deflection of 0.0146" on Page 324 would now assume a value of

$$\frac{0.0146(0.04)}{0.1525} = 0.00383 \text{ inches}$$

The (I) value for a similarly treated Inner Drum End Ring would be



$$I = \frac{\frac{3}{4}(\frac{13}{16})^3 - \frac{5}{8}(\frac{11}{16})^3}{12} = \frac{\frac{3}{4}(0.532) - \frac{5}{8}(0.323)}{12} = \frac{0.399 - 0.202}{12} = 0.0164 \text{ in}^4$$

and, similar to the case of the Outer Drum End Ring, the deflection of 0.091" given on Page 326 would be

$$\frac{0.091(0.006)}{0.0164} = 0.0333 \text{ inches}$$

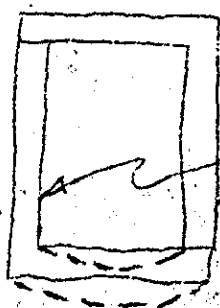
and ring is 4455.9 #/ring.

The following table shows the results of the calculations for the deflection of the rings under the given conditions.

$$y_{max} = \frac{59.5 \left(\frac{1}{8}\right)^3 (12)}{192 (3.7) (10^6) \left(\frac{1}{16}\right)^3} =$$

$$\frac{59.5 (0.293) (12)}{192 (3.7) (10^6) (2.43) (10^{-6})} = 0.000922"$$

be the probable order of the deflection of the loaded side of the box for the case of the box formed by the two $\frac{3}{4}" \times \frac{3}{4}" \times \frac{1}{16}"$ &s, the beam formed by the bottom is held to have an $(h) = \frac{1}{16}"$; and the so-formed beam is held to be one having its ends fixed. even the order of the flexure due to the slats in motion, or even if it several multiples of the indicated value, then the danger of a condition such as is indicated below:-



A SEVERE DEFLECTION OF
BOTTOM PANEL OF THE BOX
MEAN A DRAWING IN. OF
SIDE(S) TO WHICH THE ARR.
POINTS

developing until a collapsing of the beam occurs is indeed possible.

Thus, it is possible to sum up the major aspects of this section by stating that the structural stability of the Drum under dynamic conditions demands that:-

- 1) the $1\frac{1}{4}" \times 1\frac{1}{4}" \times \frac{1}{8}"$ & rims be converted from an angle section of the indicated dimensions to a box-section with an $h = 1\frac{3}{8}"$ and a $b = 1\frac{1}{4}"$ by properly joining two &s of the indicated specifications
- 2) the $\frac{3}{4}" \times \frac{3}{4}" \times \frac{1}{16}"$ & rims be converted from an angle section of the indicated dimensions to a box-section with an $h = \frac{13}{16}"$ and a $b = \frac{3}{4}"$ by properly joining two &s of the indicated specifications

and,

- 3) each End-Ring should be converted from a 4-spoke ring to an 8-spoke ring

Having thus assured ourselves of the structural correctness & stability of the Drum Assembly as such, we may now pass to a consideration of the associated mechanisms.

Firstly, let us obtain an approximation of the weights of the two Outer Drum End-Rings and the two Inner Drum End-Rings:-

A steel $4 \frac{1}{4}'' \times 1 \frac{1}{4}'' \times \frac{1}{8}''$ would weigh 1.01 #/ft. The of iron is 7.87, and that of aluminum 2.7. This means, on a basis of a 13" O.D. box-section, a weight of

$$\frac{2(1.01)2\pi(13)(2.7)}{7.87(12)} = \frac{566}{12} = 4.71 \#$$

for each of the Outer Drum End-Rings. The x-sectional area of a $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{16}''$ π is (Page 321) 0.13 in.² as compared a 0.3 in.² for a $1 \frac{1}{4}'' \times 1 \frac{1}{4}'' \times \frac{1}{8}''$ π . Thus, the box section formed as per above from the $\frac{3}{4}'' \times \frac{3}{4}'' \times \frac{1}{16}''$ π s would weigh approximately

$$\frac{0.13}{0.3} (4.71) = 2.04 \#$$

for each of the Inner Drum Rings. This would give a total of wt. of

$$2(4.71) + 2(2.04) = 9.42 + 4.08 = 13.5 \#$$

for the end-ring assemblies. To include the mechanisms which are hung onto the various End-Rings, it would be a fair estimate add on another 2.5 #, raising the total weight to 16 #.

Having ourselves on a sandwich formation for the slats 2 sheets of $\frac{1}{16}''$ thk. polyethylene sheet holding between them

the filter sheet), it is clear by Page 318 that if one 60° s. weighs 0.902# for one 1/16" thick sheet, then the weight of methacrylate on each Drum would be of the order of

$$\frac{0.902(360)(2)}{60} = 10.824 \#$$

giving a total of 21.648# for both Drums. Approximating the weight of the Rods and the plates to act from a 13" radius, then

$$\left[\frac{31.65 + 16}{32} \right] \left(\frac{13}{12} \right)^2 = \sum m r^2 = 1.382 \# \cdot \text{sec}^2$$

Consider all of the spokes to be 13" lg., and fabricated from 3/4" x 3/4" x 1/8" angle. There are 8 spokes per wheel, and 4 wheels to take into this means

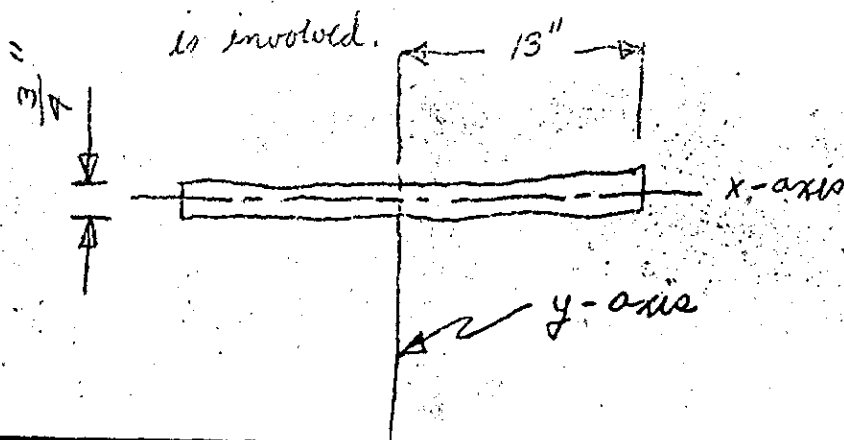
$$\frac{32(13)}{12} = 34.6'$$

of 3/4" x 3/4" x 1/8" angle is involved. If as per Page 321, a 3/4" x 3/4" angle has a x-sectional area of 0.13 in.², then a 3/4" x 3/4" angle would have approximately 0.26 in.² of x-sectional area which would mean

$$\frac{34.6(0.26)}{1.44} = 0.0625 \text{ ft.}^3 \text{ of aluminum}$$

is involved. This would mean a weight of

$$0.0625(62.5)(2.7) = 10.55 \#$$



Consider this 10.55# weight to be equivalent to a single bar 2' lg. and 3/4" wide, about the origin of indicated set of axes.

The ($m r^2$) about the x-axis would be

$$\frac{10.55}{32(12)} \left(\frac{26}{12} \right)^2 = \frac{10.55}{32(12)} \cdot 3.9(10^{-1}) =$$

$$1.08 \times 10^{-5} \text{ lbs. - ft. - sec.}^2$$

The ($m r^2$) about the y-axis would be :-

$$\frac{10.55}{32(12)} \cdot \left(\frac{26}{12} \right)^2 = \frac{10.55(4.7)}{32(12)} =$$

$$1.29(10^{-1}) \text{ lbs. - ft. - sec.}^2$$

Since

$$I_p = I_x + I_y$$

$$= 1.08 \times 10^{-5} + 1.29(10^{-1})$$

$$\approx 1.29(10^{-1}) \text{ lbs. - ft. - sec.}^2$$

Thus, the Drum Assembly would have a total inertia of

$$1.382 + 1.29(10^{-1}) = 1.511 \text{ lb. - ft. - sec.}^2$$

Then, the energy that must be assigned to the Drum in getting it up to a speed of 150.8 rads./sec. would be

$$\frac{1}{2} \cdot 1.511 (150.8)^2 = \frac{1.511(22700)}{2} = 17,200 \text{ ft. - lbs.}$$

which, if done in 60 secs., would amount to :-

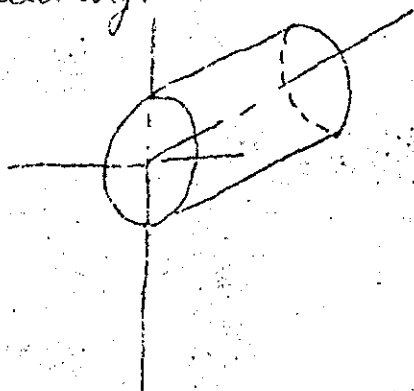
$$\frac{17,200}{60} = 284.4 \text{ ft. - lbs. / sec.}$$

Start-up in 60 secs. would then demand a

$$\frac{284.4}{550} = 0.518 \text{ HP motor driver}$$

This size of motor demanded here for start-up alone raises the question of a reconsideration of the sandwich formation of the plates to reduce the weight involved.

But before we consider a change in the design of the plate, we enter into the question of the power demand of the against the air fluid that fills the cabinet. The prime power load is due to the centrifugal fan action of the Drum assembly.



The fan action would occur prior at the ^{end} faces of the rotor, where cylindrical portion of the Drum a comparatively small contribution fan action. By a derivation indicated here, the fan torque of the end-faces would vary as the 5th power of the of the rotor, while the influence rotor length would be as the 6 of Drum length.

By the writer's understanding, a 22" diameter rotor, ¹⁶ called for a $\frac{1}{20}$ HP motor driver. Then,

$$0.05 \left[\frac{26}{22} \right]^5 \left(\frac{24}{16} \right)^{0.3} = 0.05 (2.3) (384) \\ = 0.05 (2.31) (5.95) = 0.688 \text{ HP}$$

would be the size of unit required to power the instant & if we assume that the $\frac{1}{20}$ HP motor was 75% loaded, then

$$0.75 (0.688) = 0.516 \text{ HP}$$

would be the actual power-demand here. It would then be a $\frac{3}{4}$ HP motor would be required.

Next, the question of braking the mechanism arises. If of the Drum assembly is 1.571 lb.-ft.-secs. and the D. to be brought to rest in about 60 secs, a negative deceleration

$$\frac{150.8(2)}{60} = 5 \text{ rads./sec.}^2$$

is needed, and this would require an applied torque of

$$1.511(5) = 7.555 \text{ ft-lbs.}$$

Based on the Eddy Current Brake already designed, the designed Brake at its feed of 25 milliamperes would exert a torque of

$$0.1772(25)(1) = 4.44 \text{ ft-lbs}$$

at the peak velocity of the Drum; and, at $(\frac{1}{25})$ of the starting running velocity of the Drum would exert

$$0.1772(1) = 0.1772 \text{ ft-lbs.}$$

Thus between an angular velocity of 150.8 rads./sec. and

$$\frac{150.8}{25} = 6.03 \text{ rads./sec.}$$

the designed Eddy Current Brake would exert an average torque of

$$\frac{4.44 + 0.1772}{2} = 2.31 \text{ ft-lb.}$$

which means that

$$\frac{2.31}{1.511} = 1.528 \text{ rads./sec.}^2 = \text{the yielded}$$

negative acceleration, and

$$\frac{150.8 - 6.03}{1.528} = 94.4 \text{ secs.}$$

of braking-time would be required to go from 150.8 rads./sec. to 6 radians/sec. Thus, a slight re-design of the Eddy Current Brake to provide for a higher permissible current feed-rate might bring the speed-control Brake at its over-excited condition into effective use as the Brake for slowing down the drum in switching to black-and-white viewing.

One important question in viewing the braking problem, toward attaining a speed suitable for Plunger "A" to "go home" is the question of how much energy the plunger-member of "Position 2A" can absorb.

$$y_{\max} = \frac{WL^3}{3EI}$$

defines y_{max} for a cantilever beam, which is what the plunger [Item # 45, DWG. A1] is:-

$$y_{max} = \frac{Wl^3}{3EI} = \frac{(Wl)l^2}{3EI} = \frac{Ml^2}{3EI} = \frac{5EI l^2}{3EI}$$

$$= \frac{5l^2}{3Ec} = y_{max} = \frac{25l^2}{3Ed}$$

since $l = 1.5$ ", if we specify a limiting stress of 20,000 psi,

$$y_{max} = \frac{2(20,000)(1.5)^2}{3(26)(10^6)(\frac{\pi}{16})}$$

$$= \frac{2(20,000)(2.25)(16)}{3(26)(10^6)5} = 0.0037$$

and now by

$$y_{max} = \frac{Wl^3}{3EI}$$

$$0.0037 = \frac{W(1.5)^3}{3(26)(10^6)\frac{\pi}{64}(\frac{5}{16})^4}$$

$$\frac{0.0037(3)(26)(10^6)(\pi)(0.0095)}{3.37} = W = 2560\#$$

which is to say that since the stored elastic energy would be given

$$E_e = W \frac{y}{2}$$

then

$$2560(0.0037) = 9.46 \text{ in-lbs.}$$

would be the energy which safely be stored in the plunger-me Positioner "A". Thus, the maximum speed from which the gun could act would be

$$\frac{9.46}{17} = \frac{1.511 W^2}{2}$$

$$\left[\frac{2(9.46)}{12(1.511)} \right]^{1/2} = W = 1.04 \text{ rad/sec}$$

Actually, the above calculation, despite its optimistic reflections on the problem, yields a deceptive result. The force between the drill-hol
 Host "A" and the plunger of Positioner "A" which would be involved is impractical. We will return to a consideration of this point.

If we measure the use of a $\frac{1}{4}$ HP motor and assume it is under ^{normal} operating conditions, it will give 25% on the average its full-load output torque, then

$$\frac{0.75(63025)}{1725} = 27.4 \text{ in.-lbs.}$$

or

$$\frac{27.4}{12} = 2.28 \text{ ft.-lbs.}$$

would be applied to the acceleration of the drum. Then

$$\frac{2.28}{1.511} = 1.508 \text{ rads./sec.}^2$$

would be the initial acceleration. To travel one full revolution then requires, starting from rest,

$$2\pi = \frac{1}{2}(1.508)t^2$$

$$\left[\frac{4\pi}{1.508} \right]^{1/2} = t = 2.88 \text{ secs.}$$

at which time the Drum Assembly would be moving with a

$$\text{velocity of } \frac{1}{2}(2.88)(1.508) = 2.17 \text{ rads./sec.}$$

At this velocity as indicated above that which Positioner "A" is to go home. At this rate, it will clearly be seen that when the Drum itself is driven by the Drive motor in its alignment, the load imposed on the latched-pawl in locking will be substantial. This calls for a re-evaluation of the design of the latched-pawl to be used operating Positioner "A" and in

Regarding:-

1. The synchronization system:- Conditions now make it look as if I will have to leave the detailing of the scheme outlined in "Drive Motor Arrangements" to you. I believe that the ideas were outlined with a sufficient clarity to enable a competent servo-engineer to proceed with this. The calculations in "Drive Motor Arrangements" in view of the comments on motor size below hold on as an outline. All indications are that the same magnetic structures that operate the mechanism can be temporarily over-excited when braking for the black-and-white realignment of the Drums. This would eliminate the brute solution which the solenoid-operated brake provides. The calculations on Page 316 thru 336 indicate that a "shorting out" of the tube which normally feeds the magnetic structures in synchronization control, and a substitution of a source capable of feeding possibly 50 millionamps would provide braking in a reasonable time (estimated 1 minute).

torque control.

2. The Drive Motor:- The calculations on Pages 316 thru 336 indicate that the motor size was sharply underestimated in the original calculations, and that a motor of $\frac{3}{4}$ HP size is required. The loading factor here is the "fan load" on the motor rather than start-up energy. In computing the "fan load" the basic relationships I have used are correct (except as the influence of rotor diameter and cylinder length on the power required), but the estimate that a $\frac{1}{2}$ HP motor is 75% loaded with a 22" disc of $\frac{1}{16}$ " thickness is just an estimate. Therefore the

2x Page (EE)
Action marked
IMPORTANT

Therefore the size of the Drive Motor should be checked against the more precise information you must have. Little possibility a substantially smaller motor would suffice.

The gearing:— The recent change in the gearing that drove the Main Drive shaft was in accommodation to the newly-conceived synchronization method. This will be seen from Page 6 of "Drive Motor Arrangements" and based on a 1725 rpm full-load motor speed. It is assumed that constant speed service for the motor would be established around the 1725 rpm full-load speed. All here in this matter are left up to you. One thing you must be lived up to here in connection with the gear and that is the use of an Oil Reservoir or Oil Bath. Right-angle transmission helical gearing is to be used. General, in all right angle gear transmissions, a great deal of rubbing action between the gear teeth is involved, and the proposed partially-filled Oil Bath (with one gear wheel thru the oil layer) provides for the long-life of the gears involved.

The functioning of Positioner "A" and realignment operation. The calculations on Pages 318 thru 336 indicate that during Positioner "A" entry action at speeds more than just a few rpm would be to impose such loads on the pin or plunger portion of the Positioner as would press into the pin and the rim of the drill hole of the Positioner, leading to a considerable friction between them. Moreover, it would seem that the size of the Positioner pin and plunger driving the Inner Drive shaft would be subject up to speeds in realignment operation to such shock loads on the latter as to be involved. Therefore, my suggestion

(C)

would be to: - a) bring the Drum Assembly to rest by positioning the Drum Assembly as a whole thru Positioner and, (b) in starting the Drum Assembly again preparatory to operating Positioner "A", to start the motor thru a High resistance that would reduce the applied voltage to the motor to a very low level - a level such that the motor would or weakly move the Drum. The same practice as regards the application of less than full voltage to the motor would apply to all realignment operations in which the Inner Drum is moved by itself. Some changes in the Control Circuit would be necessary by this scheme, and taking these in combination with those of using a temporarily over-excited Eddy Current brake, the braking unit in black-and-white going to black-and-white alignment from color operation, would produce the following suggestion: -

the operating coil of

Positioner "A" should be activated as per the recent Control Circuit using the same signal that energizes the operating coil of C8.

As a whole, the functional pattern of the Control Circuit changes only in that Positioner "A" is actuated after the Drum Assembly has been brought to rest.

2.) Using a schematic version of the Ellinger D.C. Motor, it would be possible to get a "rest signal" from the Drum Assembly, the signal being in the form of the absence of a blocking signal to tube operating a plate circuit relay. Such a relay would constitute the Lockman Relay C3. The energizing of the plate circuit relay could relay signal from the black-and-white position of the selector switch C2 to the timing relay now used in the application of the motor phase signal to the motor via C9, and, by another set of contacts, to the plate circuit relay power supply from the black-and-white position of C2 to a conventional relay now used to protect out of the tube normally feeding the motor and use of the auxiliary power source for over-current. The relay could be terminated. Thus the starting of the motor Drive from "rest" to the positioner, Positioner "A" would begin immediately after the Drum Assembly has been brought to rest and the Brake has been energized.

3.) The feeding of the power signal to the motor from the indicated contacts in C9, C10, and C12 should in each of these coils pass thru the same resistance limit to control the applied voltage and restrict torque from the Drive Motor, while in the case of C10, the power supply for the regular motor running operation of the motor would be applied directly to the motor to give a full voltage energizing of the motor.

4.) The information of the plate; - Page 310 comments on the information fabrication of the plate, and suggests a sandwich construction of two sheets of polystyrene with an aluminum layer separating a filter film. The filter film can be obtained from a single sheet of aluminum foil which can be applied, the sheet being the standard of many considerations of the

IMPORTANT

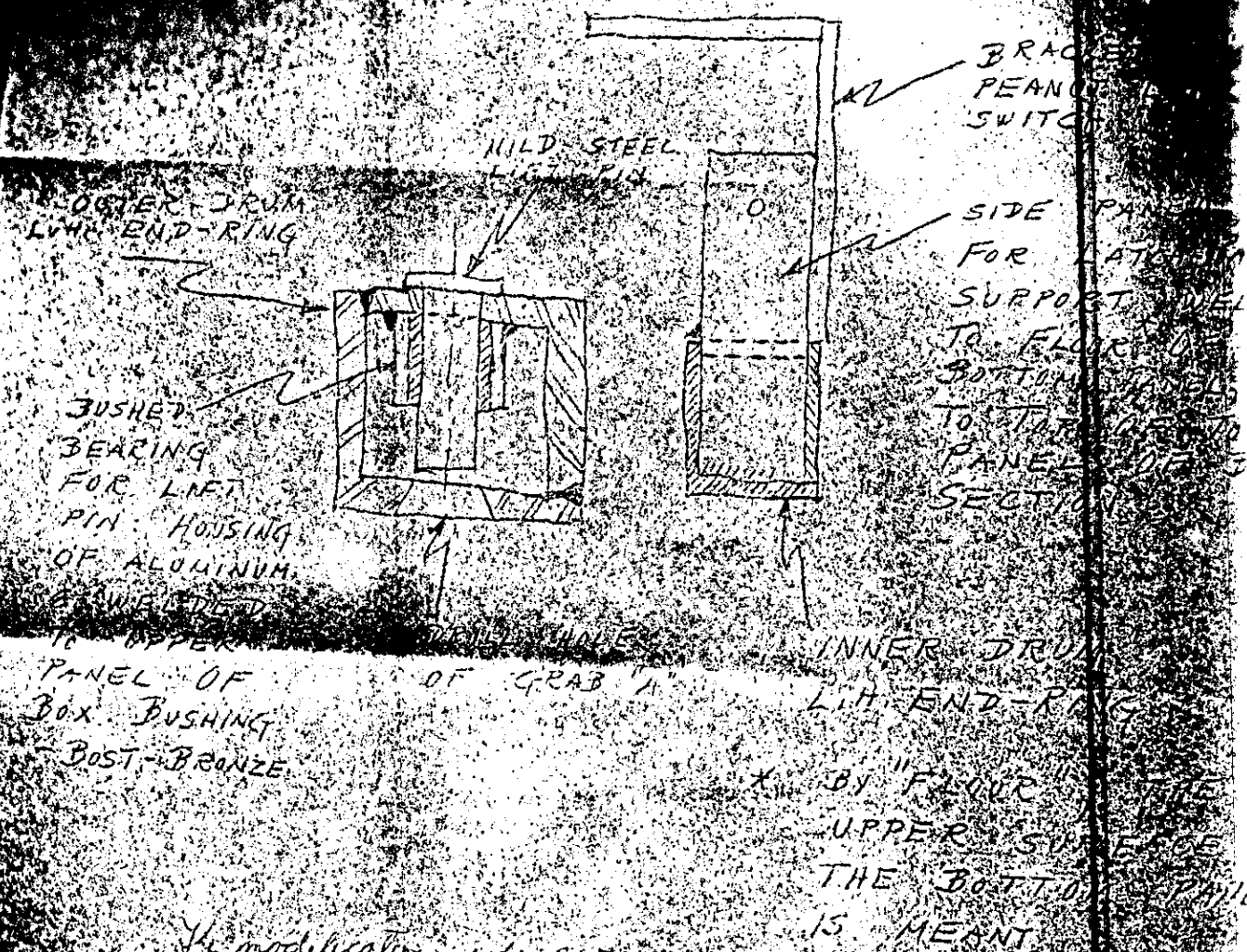
any method of obtaining adequate filter action by the use of a single methacrylate sheet for each slot should be used. But regardless of the slot formation method used,

1. The polymethacrylate sheet dimensions should be kept as now indicated.

2. The number of filter areas within each slot should be doubled to give what fundamentally amounts to a 12-color (4 sets of three) filter rather than a 6-color (2 sets of three) which would halve the drum speed. I am sure you will agree that the use of clear methacrylate sheet as the base of the slot structure makes such a move possible. Since the filter sections are merely applied mechanically to a clear sheet, the drum speed required by the drum would be as the cube of the drum speed, a reduction of the drum requirement to one-eighth of the present computed drum would be made possible as regards the minimum power requirements of the drum assembly. The start-up energy requirements for the same starting time would be reduced one-fourth of the present requirement. Since it would be possible to use a $\frac{1}{4}$ HP Drive Motor.

6. The End Rings - In conclusion of the calculations, Page 315 to 316 is that the outer drum end rings should be modified with a complementary $\frac{1}{4}$ of the same dimensions as the present specified to form a box-section ring with a base of $1\frac{1}{4}$ " and a height of $1\frac{1}{8}$ ". With the present design, the end rings should be similarly modified to a base of $\frac{1}{4}$ " and height $\frac{1}{8}$ ". In conclusion, that all dimensions from this point & apply.

for construction



The modifications which the box construction involves in the mounting of the lateral jaw, grab, and support member mechanisms are typified above. A lift per construction between the pin or plunger member of the positioner and the lateral jaw member of the positioner is made to the lateral jaw. The same lift per construction appears in connection with the grab. The grab is now mounted on the top panel of the positioner instead of the inner surface of the X now. The panel which supports the lateral jaw are extended through the positioner and are welded to the outer side of the positioner. The side of the positioner is now the side of the positioner.

... and B ...
... of the ...
... energy ... the recoil spring ...
... and (b) the ...
... and "B" return to their
... position. The distribution of the lift-force ...
... that 50% of the lift force acts to compress
... the lateral recoil springs, and 10% acts to ...
... while 10% ...
... would be adequate in the case of the ...
... of position ...
... the ball being against the scolded end of the ...
... 75% of the solenoid's lift-force, this spring should yield
... just enough for the ball to move clear of the ...
... the pen ... and roll in its ...
... the ball up.

8. The framework - ...
... the unit is ...
... into a plate and ...
... not been ...
... you ...
... can be ...
... become $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$...
... become $1\frac{1}{4} \times 1\frac{1}{4} \times \frac{1}{8}$...
... the horizontal ...
... will ...
... certain amount of rigidity from the

of the box section. The essential geometric relationships in each case, kept unaltered from those shown on page 1. Naturally, the support members will now ride on the top of the Outer Drive & 4 End-Ring. In constructing Ward End Ring, the spoke-to-ring flange ^{or flange} to be maintained, is now indicated on Page 1-8. In instances where the maintaining of the box section is taken down of a portion of one leg of a spoke &, the Ward End. The basic construction as per Page 1-8 are to be set up, and the appropriate support panels for the support members, lateral panel, etc. set in place on the originally shown &, and the other complementary & (suitably notched for the support panels) are be welded on to complete the intended box sections. The welds between the two & to form another to form the box angle need not necessarily be in the form of continuous welds except as they would contribute towards easier balancing of the final rings. Through the box section modification was completed at the higher velocity of 7500 rpm and is in for the critical modification at 7500 rpm, would do well to maintain it at the lower drive speed. The 8-spoke construction is mandatory at both speeds. To emphasize it is repeated that all mechanisms previously mounted on the top sides of the formerly specified & now are now to be mounted on or ^{or above} with the top panels of the now specified box sections. The same ^{force} geometric relationships ^{between} the mechanisms ^{and} are to be maintained.

the springs - springs now appear as long as
the "A" and "B" and all later
specimens of the series of
the Drake elevation is a
the Drake Assembly on Aug 4

BULKY EXHIBIT

Date received 2/20/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 768

Address _____

Purpose for which acquired Investigation

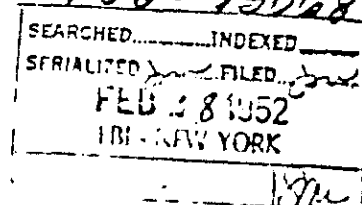
Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retained

List of contents:

154. Photostatic copy of the letter written by Brothman to the Reverend B.B. Nielsen, 4th Avenue, and 46th Street, Brooklyn, N.Y. whom Brothman classified as a friend.



NUMBER 71644
NAME ABRAHAM BROTHMAN
If written for one inmate by another enter name
and number of the actual writer in space below:
WRITTEN BY _____
NUMBER _____
Inmate's name and number must be signed at the
bottom of this letter and correspond with that on
this coupon.
NOTE: Do not write on reverse side of this coupon.

Letter sent to Following Address:
NAME Rev. J. E. Nielsen
Street and Number 7 Ave. 4
City Brooklyn State N.Y.
Relationship Friend
DO NOT WRITE BELOW THIS LINE
Last Letter to Same Address _____
Total Number to Same Address _____
FPI-LK-11-2-50-1,100M-7605

From ABRAHAM BROTHMAN
PMB 71644, BROOKLYN, N.Y.
To Rev. J. E. Nielsen
(Name)

Dec. 17, 1955
(Date)
7 Ave. 4
BROOKLYN, N.Y.
(Address)

Dear Bjorn,

I have your letters of Dec. 25 and Jan. 1, and as always these letters have brought the warmth, the loving kindness, and in general the wonderful spirit that I have in contact with you. And nothing comes more welcome here than these good and human qualities. [and human] and not just 'good' alone, because something has then these qualities in it, more than 'human', something more that is associated with the lower species. I

I'm reminded of what the word 'human' has always meant to me whenever in the past as happened tonight, a sheet of paper entitled "Notice of Action of Parole Board" came to me. The message, as you might surmise, in a single word: - "Denied", but, as is so often the case, what the high and the mighty would determine with a single word, it never quite gets that easily. For every contemporaneous verdict, it must be borne in mind, there will be a later and later decision, and that later decision belongs to history; and I'm confident that history will be with me.

But it nevertheless never fails, when I look at ^{that} presumptuous "Denied", to evoke a whole train of thought for it is no light matter to be told that your freedom is "Denied". I cherish freedom, but, as I might find out a little more than a year ago, I place it ^{it} cheaper than my ^{written} legal history. My application to the Parole Board and what I had to say in my personal appearance. Parole Judge made this clear, for as accurately as I can recall both my written and ^{spoken} words. I stated that one of my ^{main} reasons for ^{that} ^{my} ^{application} was for the earliest termination of a manifest injustice. And then I went on to say that the only ^{possible} motive for the alleged crime had to be a guilty association with espionage, and nothing be more ludicrous than such an accusation for neither the Brothman that people knew in person nor the one they knew thru his writings could conceivably have been a trafficker in "secrets". On the contrary, I insisted, mine had been a record of a ruthless opposition to the penetration of magic and wizardry into science; and, moreover, I argued, I had always felt that the ^{only} ^{real} ^{scientist} to make his work publicly known stands as a higher calling than any other pursuit.

think of, being none the less required by such a Opoint, and I offered more than a
reprint of published articles to substantiate my claim to this viewpoint, could possibly have
in "look and dagger" escapism to piffle "secrets", nor could he have become the accomplice
who found in such endeavor a satisfaction which outweighed their judgment or better knowledge.

So "Denied" is the verdict on my request to serve at the earliest possible moment the
direction of my lineage! "Denied" is the verdict on my open, announced intention of "mentally
serving"! "Denied" is the verdict on my contention that my return to society is at least, and
with the best interests of society as they ^{found} the applications of Japanese and German war criminals
be! And "Denied" is the verdict on my children's oft-repeated request that their interests
be!

Those who have surrounded themselves in the slanders of democracy and who are
of crocodile tears for the supposed transgression of others against the rights of individuals
within the society; and I do not think for a moment that I should understand them, their
in the last and final analysis even less desirous to me than their consistent behavior
to "Denied" which consists from the fact that I have dedicated one iota more of my life to
negligible part of a second by the existing triumph of theirs. And moreover, whereas the "He
which they have handed me is their certificate of illegitimacy for the cause of history's
oppression, the one which will be handed them will be the verdict of those who will
with the population - to the great world of London and abroad!

I know that their "Denied" will be the final word, by badge of identification for
American historians, for its inclusion in the final opinion of the United States
will be the final recognition of the fact of freedom, of life, of the right of
the world that other nations are not to be allowed to, and that the world is
since in the past I have been of opinion that I should not have been in the
place of freedom in which I am now at present.

The day when I will again be able to sit down with you and other
discussions has been delayed by the "Denied" of the day. I will be in the
the that day again, with you and other, and the world will be a better place
I look forward to this day!

Yours truly,

Walter D. Williams

BULKY EXHIBIT

Date received 3/10/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 769

Address _____

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

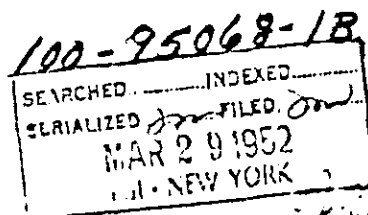
Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

- 155. Photostatic copy of a letter to Abraham Brothman from his wife Naomi.
- 156. Photostatic copy of a letter to Naomi Brothman from her husband Abraham Brothman.

(84)



To: Abraham Brothman #71647
From: Naomi Brothman, 41-08-42 St. LIC

Feb. 13th
Wednesday

Dear Abe:

Have had no letters from you this week but ~~what~~ with the Holiday yesterday and the general delay this is not surprising at all. Will probably get one tomorrow.

Saw yesterday the play I wrote you before. Was greatly impressed by it this time, even more than before. I have completely forgotten what it was all about but found it even more timely now than before. I wonder if you remember it though I am sure that you do. You have such a good memory. They have changed the play somewhat but the punch is the same. By the way the part of the inquisitive boy, played formerly by our neighbor, is now played by a girl. I guess it was easier to get a girl than a boy to do this small but good part.

It has gotten very cold here again and it looks like I have caught something of a cold. In fact as soon as I finish this letter I will go home, not because I feel bad but merely as a precaution. I guess I swallowed too much cold air last night and as a result I am somewhat hoarse. However, it is nothing to worry about.

Otherwise there is very little to write about. Children are doing pretty well and behaving also pretty well. Anita still comes out with pretty funny remarks. When I reprimanded her for some or other she retorted "Well I did not turn out so well" or something to that effect. I do not know how this sounds now but it was pretty funny at the time she said that. She is a very comical character in general.

With further reference to my conversation with Joe, while this matter has not been fully settled, it is on the way and will be handled again through Goldie, as formerly.

It also seems that the Pumpkin man has written another installment of his memoirs for a big magazine. I have not read it as I would not spend a dime or whatever it is for same. You probably saw it and I understand it is quite the thing. He practically refuted the theories of science, etc. Quite a guy he turned out to be. I guess he wants to be immortal and is making sure that his opinions are recorded. Besides of course, the fee of something like 75 thousand dollars helps along. He even appeared on the radio and television.

Please excuse me for not writing more - I am going home - so again with Best Regards and Love from the Family. As ever

Naomi

Naomi Brothman

didn't qualify for 2^d institution of higher learning, and he had to content himself with an admission to an establishment of less rigorous entrance standards, - a disappointment which sure he keenly feels! [My competence to speak for him, I'm sure you will understand, and course from that kinship between us that derives from the fact that both of us had to grow from Ivy League schools to eventually make this circuit. If indeed my residence in the halls of Columbia University taught me to forever seek the highest realms of attainment in every endeavour, I'm sure that his tenancy at Harvard, where to be sure there's a bit more of that ing vident species ^(of creature) than at Columbia, must have similarly implanted in him a comparable standards governing his ego-expression.]

And since one thing leads to another, I see by the newspapers that that certain insurance gent is now seeking a new trial on the basis of some new evidence. Silly boy! By this time, have learnt that facts have nothing to ^{do with} the facts! Of like Orestes Pearson, I too "predict" that will come to nothing, for the good Federal Judge who is slated to hear this thing is probably brighter gent than the character on whose behalf the petition was filed and because of this fact dismiss the whole thing. I'm sure that this sagacious jurist, who in the first place found it in with his standards of court-entertained and court-entertainable veracity to listen the Pump out, will also find that a few additional departure from the truth by that latter species really of small consequence; and in this judgement, I too would frankly join him, for what's about a few extra lies when the Pumpkin Man's whole story was palpably one long organism of and auditory hallucinations.

I'm afraid that the Harvard alumnus will have to complete the course for which he is rolled; and it may be that it will do him some good, though this latest action doesn't do highly for his scholarly aptitude. He's going to have to learn to view the world in less static terms by less congealed standards. In his day and mine at school, we were taught that fiction is confined to literature and the right to tamper with even normal word-usage required a "poet's license". Well that doesn't hold anymore! In this more highly-refined culture of ours, in this all possible civilizations, we've widened the frontiers where fiction is permitted, and when it's in court its teller, if he's on the right side, is equipped with a new kind of legal privilege, a "prosecutor's license"; and indeed it's a sorry sort of liar who doesn't make use of this new

Abraham Brothman, 71847

as ever,
He

From ABRAHAM BROTHMAN
PMB 71647, ATLANTA, GA.

To MRS. NAOMI BROTHMAN
(Name)

THURS. EVENING

JAN. 31, 1952
(Date)

41-08 42 ST.

LONG ISLAND CITY, N.Y.
(Address)

Dear Naomi,

Since my last writing, I've received your letters of Thurs.-Jan. 24 and Mon.-Jan. 27. The letter of Jan. 28, there came a receipt-slip for your \$20 money-order. I thank you from the my heart for this contribution to a "worthy cause"; as, as for undelivered advice to hold for when the need arises, please be assured that I am afflicted with few if any inclinations in of soliciting financial assistance, and on that account you would be well-advised to avoid of a cessation of such solicitations. In fact, this inclination of mine to earnestly, persistently, consistently request monetary aid, believe me, is one which stands in the heart, need of coaxing, for it, in common with my other stronger leanings, rests ^{firmly} on the on the deepest and of my intellectual convictions.

But to be serious again, Monday's letter thrilled me! I'm very happy that you enjoyed it. As I've already written, you know that I enjoyed it too. And if I haven't said this before, proud of the way you conducted yourself. I'd like to say more about the visit but I'm still too ecstatic about it to be coherent; and so, until I calm down, let me set it down. It still makes me feel good all over just to recollect it.

It's too bad that the weather was so poor while you were here. Though I'm not a member of the Georgia Chamber of Commerce, I wouldn't be doing right by my present status as a "member" permit you to go away thinking that Sunday's and Monday's weather is the usual thing. It isn't; and there's a little doubt in my mind but that it was some Yankee weather either drifted down here by accident, or was directed here by some subversive plot to your impression of this land of sunshine and a few lesser marks of distinction. I'm sure a certain Senator had been here, that he'd join me in the latter notion and probably, some account for the whole thing. But what am I laughing at! I'd probably rank high on the names, unless there's a State Dept. official or two around. About the latter possibility, I know, for truth to tell even if there were they wouldn't reside here with me unless they had worked them over as one ^{former} State Dept. official was. And even in that one case, that

BULKY EXHIBIT

Date received 3/18/52

ABRAHAM BROTHMAN

100-95068-1 B

(Title of case)

Submitted by Special Agent J.P. Collins

Source from which obtained See Serial 770

Address _____

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

157. Photostatic copy of letter dated 1/11/52 to Abraham Brothman from Naomi Brothman.
158. Photostatic copy of letter dated 1/5/52 to Mrs. Naomi Brothman from Abraham Brothman.

(85)

100-95068-1B

SEARCHED.....	INDEXED.....
SERIALIZED.....	FILED.....
APR 29 1952	
FBI - NEW YORK	

Jim

I have just received your letter of January 3rd. I have read it and am very pleased that the work you have been doing is so interesting and productive. While most of it is not very comprehensive, I can see its implications and future uses.

As far as my trip is concerned, I am somewhat at a loss to figure it out at the present time. As I have written you, I will have to travel by train - it seems that air travel now is out of question - sea conditions are bad and then I have no right to worry mother. This means a long trip by train, which will certainly not stop me. But how to spend two days in Atlanta and then another day in Washington I do not know. I was planning to take two days off - Monday and Tuesday, but this will permit me to spend two days in Atlanta. Of course, I will write for permission to the Warden but before doing this I intend to get a train schedule from Penn Station tomorrow and try and figure the connections. I am not too anxious to spend any more time in Atlanta than necessary and do not particularly feel like sight-seeing, with all due respect to Atlanta. If I could see you over the week-end twice, it would work out all right but I do not think that this will be allowed. At any rate I will have to work it out myself and will of course inform you accordingly in my next letter. Please, if it is at all possible, send out the material as soon as you can, so that if I get to Washington on Tuesday of next week, January 22nd, Mr. Bennett should have it in his possession. I will write to him for an appointment, of course.

I have been told over the phone, that there is a letter from you today addressed to Elsa. I am very pleased with that and much relieved too. While I do not wish to influence you in any way, it is very important to my way of thinking to write to the children as often as possible. I have ~~now~~ heard a few remarks from Elsa to the effect that she has written you twice but has received no reply. It is very hard to impress a child that you cannot write as often as you want to, a being quite a spirited or stubborn child cannot be confined of many things and I prefer to leave her alone, if I can at all help it. I find that too much pressure usually results in contrary results. I will write them as often as you can and always write a few lines to Anita.

I haven't spoken to Mr. Nielsen for a long time but Mr. Messier recently met him somewhere and they had a nice chat together. He mentioned that he has been getting nice letters from you. It is very hard for me to find Mr. Nielsen because I never can find him in his office. On the other hand I do not like to call him at his apartment because his wife is quite

I expect to see Goldie over the week-end and will convey to him all your recent remarks, etc. He does not get to New York too often. I will make it a point to see him this time. After all when he does get in to New York there are ~~many~~ so many ~~business~~ affairs of one kind or another that he has to attend to that his time is limited. I will write to you very soon and let you know of my plans, the best that I will be able to make. I will try to arrange for next week end but do not get disappointed if it will have to be the following one. You know the ~~kind~~ of nice and men. etc. So again with best regards from the family, I am,

as ever,

NUMBER 71647

NAME ABRAHAM BROTHMAN

If written for one inmate by another enter name and number of the actual writer in space below:

WRITTEN BY

NUMBER

Inmate's name and number must be signed at the bottom of this letter and correspond with that on this coupon.

NOTE: Do not write on reverse side of this coupon.

Letter sent to Following Address

NAME MRS. NAOMI BROTHMAN

Street and Number 71-08

City LONG ISLAND CITY, N.Y.

Relationship WIFE

DO NOT WRITE BELOW THIS LINE

Last Letter to Same Address

Total Number to Same Address

FPI-LX-11-2-40-1,100M-4-6

From ABRAHAM BROTHMAN

PMO 71647, JAHANIA, GO

To MRS. NAOMI BROTHMAN

(Name)

(Date)

(Address)

Dear Naomi,

Yesterday I received your letter of Wed. Dec. 2, and I trust that even as I write this Anita has already recovered from her battle with the "bug". I'm confident that this is already somehow Anita to me has always epitomized the quintessence of healthy, happy living; and it's impossible for me to conceive of any "bug" that could be evil enough to want to hurt her too much. It seems to me Anita's innate charm is so great that for her to have a most ill-intentioned "bug" into a love-ly would be no stupendous task, but rather a routine matter. It's just as if she had had such a rough anti-climax; and it hurts to think of anything that would take her happy face even for a moment. By way of some compensating moments for her uncomfortable struggle with tell her that everybody here who's seen her photos - and that means just about 2000 people - has in love with her. One of the quaintest things said of her was a remark by a country-boy who said that "she's got plenty of 'tickum' in her eyes". [A 'tickum' is most likely a contraction of 'tick' and probably connotes a coquettish quality.]

With this blend of a fervent prayer that all is now ^{well} with Libby and my confidence that you're thing under control; I turn to a request you made of me some time ago, namely that you'd like for ^{more interesting} comment on some of the ^{more} interesting items appearing in the newspaper we both read. Just such an item of interest appeared in the "Times" of Sun. Dec. 30, and it concerned the conversion of the heat energy of a "nuclear reactor" to electricity. The quality which made this article so appropriate for comment by me is the noteworthiness of this achievement ^{more} the fact that I predicted it to you some years ago, but rather as a demonstration of the art of "secretism".

A "breeder" reactor is a flamboyant name for the type of U-235 to Plutonium-239 cycle designed for maximum neutron economy efficiency. As you may remember from my previous explanation of a breeder, it's the reactor where neutrons obtained from a controlled fission of U-235 are used to convert the non-fissionable U-238 to the man-made and fissionable element Plutonium-239. This is done to prompt the desirability of such a conversion - (a) the fact that the naturally found fissionable is present in very small concentrations (about 0.7% by weight) in normal uranium ore, which must be at

[illegible]

BULKY EXHIBIT

Date received 6/12/52

ABRAHAM BROTHMAN

100-95068-1B

(Title of case)

Submitted by Special Agent J. M. Collins

Source from which obtained See Serial 774

Address _____

Purpose for which acquired Investigation

Location of bulky exhibit In cabinet with file

Estimated date of disposition To be decided at conclusion of case

Ultimate disposition to be made of exhibit Retain

List of contents:

159. Photostatic copies of letters received by subject, Brothman, at the U.S. Penitentiary, Atlanta, Georgia.

(86)

100-95068-1B

SEARCHED	INDEXED
SERIALIZED	FILED
JUN 24 1952	
FBI - NEW YORK	

Sm

FOIA(b)(7)(C) - 12/20/2011

My mother & father also received two letters from you. The letter from
to be sent to the children - this in addition to the letter of
Apr. 24th - makes three letters for last week. The letter to the
is very good - of course I will read it first to Elsie and then to
to Anita, depending on how she will take this. Elsie will answer
this week as she is already planning a letter to you.

Your letter of Nov. 8th is fine and very appropriate. I recall I also mentioned this anniversary to you together with much. Life is just a succession of struggles one after another and all we to do is to live and look forward to a better life.

This being "Open School Week" I visited Elsa's classroom last night and found out that she is quite pleased with Elsa. I think there is a lot of improvement in her work now and that she is beginning to accept school and maybe even like it. This morning I went to Anita's class and was very pleased with her behavior there. She certainly shines among other children. Of course, I am prejudiced by her family. I do not particularly care for her mother but Anita gets along with everybody. She is beginning to read and is making good progress in school.

I spoke yesterday to Clare - and she sent her love to you. She is preparing for me two sets of your articles which I will send as directed by you. She told me, among other things, that an uncle who is down South, visited his sister who is very well and happy and is kept very busy.

I have not heard from Goldie for a while. He is kept busy and does not have time to call him and find out whether there is any news there. On the other hand, you promised me to write something about your work and I have not received it as yet. Of course, it may come in one of the letters that you have written since. If not, if you can.

again there is very little that I can write in to the above. Like I assure you is very monotonous here there is nothing that I can complain of - absolutely none still there is so little of interest that I can write about these letters. I want to assure you, however, that I appreciate your letters and the spirit in them very much. Of course I did not expect anything else but still it is very reassuring to read it. Many people feel that way too and even if one does get something which is very natural, still there are many things to look forward to.

[illegible]

Abraham Brothman
PMB 21647, Atlanta, Ga.

From Ch. H. H. 13, 1951
Hammington Court
4520 4 Ave NE
August 21, 55

Dear Abe,

I am not, this time, trying to explain how sorry
for not meeting you before. I shall only say that
I have been going in circles with my next move and many
incidents and appointments. I shall talk more when
we meet in New York.

It seems almost certain that I will be accepting
an appointment at Bellevue Hospital. This is to me, the
difficult and challenging position at the time I have been
turning over my mind. However, it is only for a
period of one year. Then, I will have to look for some
place, again. My family has also expressed their desire
to stay in New York, on the condition that we are able
to find an apartment near the hospital. My daughter is
very anxiously that she wants to see me as often
possible as well as much as possible. As soon as
I can find a place to live, I will resign from my
present position. Dr. Howard Rusk as already expressed
a light in having me on the staff. He seems to be
the type of a personality I want to work with, because
of an intensive desire to help his patients and he
has a healthy interpretation of the chaplain's work.
In making this decision you also came into the pic-
ture. I am fully aware of the fact that I have not
been as much help to you and your family as
much I could be while you have been away. Now

...has developed into a mutual
...looking forward to the day when we can
...in New York as you at the first
...with your friends in the prison yard. Will
...about these experiences. I have not known
...and it has always been under some mor-
...strain. In spite of this I have always
...have a genuine warmth for people, and
...I felt your deep concern for your
...with them behind the
...I wish to see more of you -
...a sentimental for-
...in this circle of my acquaintance
...and feeling for
...to see you frequent
...it is a strong mutual
...when you can spare
...I think your wife said
...212

...must also add that my stay in New York will give me
...to continue with her doctor for another year
...baked the first cake for
...the only cake I did not like
...and all. She is a great comfort
...for me. He does my
...I hope you are able to keep up the good spirit
...in your letters to both me and your
...with best wishes
Chaplain, B. J. Nelson
Norwegian Lutheran Hospital
4520 4 Ave Brooklyn 20, N.Y.

To: Abraham -
From: Naomi -

Friday
May 9th

Dear Abe:

Received your letter of 1st March and was very pleased to have answers to my questions even before my letter reached you. I am very glad that you are getting along in sports and otherwise. I was also glad to see that you have been making resolutions about acquired habits and that you intend to continue ~~with~~ to live with them in the future. These are very encouraging news as you know so strongly I feel about these things and how much I have talked and about them in the past.

I was also pleased with the promises you made to Anita and also hope that you intend to honor them in the future. I have wanted to write and to talk to you about these things before but unfortunately, when I saw you, we never had any time. I have always wanted to bring it up but somehow never did do it. As you have now plenty of time to think things over, you must recall a lot of situations and many conversations that we have had in the past about personal matters, which I believe, I was on the right track and not you. You must realize that you can rationalize and verbalize much better than I and, while you never convinced me that I was wrong, things went on the way you were shaping them. Of course I realize the cause of all but still in all certain situations will have to be changed and eliminated. Unfortunately we cannot go into this in our letters and I do hope that we will have time to discuss it next time when I see you. But in the meantime I do hope you will give it consideration as I am sure that you are well aware of what I mean. You remember the song you used to sing about "resolutions on paper". Well another dictum of yours was always about theory and practice. So I do hope that all your theoretical resolutions will have practical applications and that you are making plans along these directions. I do not want to go into this any further and have only written the above because you gave me an opening about your habits and about your intentions to live with the better ones in the future.

I saw Mr. Nielsen yesterday and have conveyed to him what we have discussed. I think that for the present it would be best that he writes first. Then this can be followed up by a visit, if necessary. What do you think about it. He will write you directly.

I spoke to Clara yesterday too. She has received a letter from you and has written you this week in reply. I am arranging to see her in the very near future that I am able - so that will take care of your request.

I know that there is a letter at home from you - probably of last Sunday - I will answer same during the week-end - probably tomorrow, I hope. Otherwise, there is nothing new to write - the children are all right and busy. Otherwise there is nothing new to write about. I am still, as always, attending to everything that is to do and will keep you posted about any new development.

So again with Best Regards and love from the Family, I am

As ever

BULKY EXHIBIT - INVENTORY OF PROPERTY ACQUIRED AS EVIDENCE

Bureau New York Field Division
Various Date

Title and Character of Case:

ABRAHAM BROTHMAN
100-95068-1B

Date Property Acquired: See below

Source From Which Property Acquired: See below

Location of Property or Bulky Exhibit: In Vault

Reason for Retention of Property and Efforts Made to Dispose of Same: Evidence & Information

Description of Property or Exhibit and Identity of Agent Submitting Same: See below

160. The photostat of letter from Subject to Chaplain E.B. NIELSEN, 8703 3rd Ave., Brooklyn 9, NY dated 7/10/52. - See serial 780

File #:

100-95068-1B

SEARCHED	INDEXED
SERIALIZED	FILED
SEP 30 1952	
FBI - NEW YORK	

10/1/52

From ABRAHAM BROTHMAN
P.M.B. 71047, ATLANTA, GA.
To CHAPLAIN B. B. NIELSEN
(Name)

THURS. EVENING
JULY 10, 1922
Date
8703 - S AVE
L'ROOKLYN, 7, NEW YORK
(Address)

Dear Bjorn,

It's my guess that by the time that this letter comes, Evelyn & I will be on our way to the north. I hope that she'll have just the kind of a summer vacation that she's been longing for so long, just that a child's vacation, for now and for later on.

I'm mindful as I think of Evelyn leaving off on her vacation of the two summer vacations country that I had as a child. I thrill to the recollection of those weeks today even as I did then. They stand today in a different framework of experience than they did then. What was a matter of great pleasure then is a matter of humor today; and what only vaguely troubled me then stands out in sharp relief today.

From the cool-boden air and the nondescript greyness of a New York ghetto to the sun and the rich greenness of the countryside was a bigger trip than the four hours that he told of. Only a journey thru celestial space could encompass such a change; and so our preparations for the voyage were certainly no less in scope or magnitude than those Peary had made for his trip to the Pole. All things were taken into account: - the possibility of a monstrous change in the weather; a first-aid kit to deal with bloody emergencies; and of course an ample supply of sandwiches and a thermos-jug of coffee. This was our 'mobile kit'; a 'mobile supply dump' of food and other necessities accompanied us in the baggage-car of the train. This latter 'supply dump', packed in a dozen borrowed travelling-grips and an ancient trunk that happened to belong to me, took even more into account; everything that the imagination could conjure up. And the imagination of a ghetto people in a big city knows no limit!

A thousand years of adventure were crowded into approximately five hours: - a ferry-boat to a distant land known as Weclawken, New Jersey; and then an honest-to-goodness locomotive-powered train belonging to the ostentatiously-named New York, Westchester, and Albany Railroad. Our destination? A frontier-land in the Catskills, Ellenville by name. Even as I write of this journey it seems to me that I can still feel the sweep of the wind against my face as I stood on the point on the ferry-boat's deck. A month of anticipation of this journey and the morning of

In the years since this event took place, a mighty torrent of hours and pages have been in an almost never-ceasing endeavor to place the concept of the 'infinite' within an ultimate definition; but even today I've nothing but a few devices - of - mathematical convenience by which to make the momentous projection. But what has for good and sufficient reason escaped my (and every else's) intellect as a hard and fast physical concept has been known to me on an intuitive level ever since the day I boarded the country-bound train at Weehawken. An eternity, an infinite time, is still the length of time it took for that train to get started. I can't remember much that happened from then on until we arrived at Ellenville because a cruel fate, to my everlasting grief, caused ^{me} to fall asleep on the train; and, tired by the accumulated nervous strains, slumbered almost all of the trip. But Ellenville will always stand for me as my first rendezvous with extravagance, for it was at Ellenville Station that we sent a telegram to my Father and Mother, saying that we had safely and soundly survived the rigors of our ghetto-shattering journey. The Brother, the Sister, and the son - , carefully worded a message to be whipped across the long line up until that moment had - so far as we knew - served ^{only} the whims of the makaregale of finance.

A 'bon voyage' to Evelyn Horne, even though a belated one, and my very best wishes you and Mrs. Nielsen for the happiest kind of a summer! I hope that these reminiscences bored you. In an indirect way, they'll at least convey why I've always hated poverty and of residence, a ghetto.

Abraham Brothman, 71647 Yours-in-friendship,
Abz